F-barES-FEM-T4: a new finite element formulation of nearly incompressible solids with tetrahedral elements

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In this presentation,

there are no structural elements and no collapse...

But there are a few dynamic analyses of continuum elements. I hope they interest you.





Motivation & Background

<u>Motivation</u>

We want to analyze **severe large deformation** of nearly incompressible solids **accurately and stably**!

(Target: automobile tire, thermal nanoimprint, etc.)

<u>Background</u>

Finite elements are **distorted** in a short time, thereby resulting in convergence failure.

> Mesh rezoning (aka., remeshing) is indispensable.



Polymer





Our First Result in Advance

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What we want to do:

- Large deformation
- Mesh rezoning
- Various kinds of analyses:
 - Static implicit
 - Dynamic explicit
 - Eigen Mode



Issues

<u>The biggest issue</u>

in large deformation mesh rezoning

It is impossible to remesh arbitrary deformed 3D shapes with hexahedral 8-node (H8) elements.



We have to use tetrahedral 4-node (T4) elements...

However, the *standard* (constant strain) T4 elements easily induce shear and volumetric locking, which leads to inaccurate results.



Conventional Methods

- Higher order elements:
 - Not volumetric locking free; Unstable in contact analysis; No good in large deformation due to intermediate nodes.
- EAS method:
 - X Unstable due to spurious zero-energy modes.
- B-bar, F-bar and selective integration method:
 - X Not applicable to T4 mesh directly.
- F-bar patch method:

X Difficult to construct good patches. Not shear locking free.

- u/p hybrid elements based on the mixed variational principle:
 - X No sufficient formulation for T4 mesh so far. (There are almost acceptable hybrid elements such as C3D4H of ABAQUS.)
 - Smoothed finite element method (S-FEM):

Various Types of S-FEMs

Basic type

- Node-based S-FEM (NS-FEM)
- Face-based S-FEM (FS-FEM)
- Edge-based S-FEM (ES-FEM)

Selective type

- Selective FS/NS-FEM
- Selective ES/NS-FEM_

- X Spurious zero-energy
- X Volumetric Locking
- X Restriction of constitutive model, Pressure oscillation,
 - Corner locking (detailed later)
- Bubble-enhanced or Hat-enhanced type
 - bFS-FEM, hFS-FEM
 - bES-FEM, hES-FEM
- Pressure oscillation, Short-lasting

■ **F-bar type** ��● F-barES-FEM

? Unknown potential





Objective

Develop a new S-FEM, F-barES-FEM-T4, by combining <u>F-bar method</u> and <u>ES-FEM-T4</u> for large deformation problems of rubber-like materials

Table of Body Contents

- Methods: Formulation of F-barES-FEM-T4
- Results: Some verification analyses
- Summary





<u>Methods</u>

Formulations of F-barES-FEM-T4

(F-barES-FEM-T3 in 2D is explained for simplicity.)





Quick Review of F-bar Method

*

For quadrilateral (Q4) or hexahedral (H8) elements

<u>Algorithm</u>

- X 1. Calculate deformation gradient F at the element center, and then make the relative volume change \overline{I} (= det(F)).
- 2. Calculate deformation gradient *F* at each gauss point as usual, and then make \mathbf{F}^{iso} (= $\mathbf{F} / J^{1/3}$).
- 3. Modify F at each gauss point to obtain \overline{F} as $\overline{F} = \overline{I}^{1/3} F^{iso}$.
- for *J* 4. Use \overline{F} to calculate the stress, nodal force and so on.

F-bar method is used to **avoid volumetric locking** in Q4 or H8 elements. Yet, it cannot avoid shear locking.





A kind of

low-pass filter

Quick Review of ES-FEM

For triangular (T3) or tetrahedral (T4) elements.

<u>Algorithm:</u>

- 1. Calculate the deformation gradient *F* at each element as usual.
- 2. Distribute the deformation gradient F to the connecting edges with area weights to make $E^{dge}F$ at each edge.
- 3. Use Edge **F** to calculate the stress, nodal force and so on.

ES-FEM is used to **avoid shear locking** in T3 or T4 elements. Yet, it **cannot avoid volumetric locking**.







 $\mathbf{E}^{\text{Edge}}\overline{F}$ is calculated in the manner of F-bar method:

 $Edge\overline{F} = Edge\overline{I}^{1/3} Edge\overline{F}^{iso}$.





Outline of F-barES-FEM

Brief Formulation

- 1. Calculate ^{Elem}*J* as usual.
- 2. Smooth ^{Elem} J at nodes and get ^{Node} \tilde{J} .
- 3. Smooth ^{Node} \widetilde{J} at elements and get ^{Elem} \widetilde{J} .
- 4. Repeat 2. and 3. as necessary (*c* times).
- 5. Smooth Elem $\tilde{\tilde{J}}$ at edges to make $E^{dge}\overline{J}$.
- 6. Combine $E^{dge}\overline{J}$ and $E^{dge}F^{iso}$ of ES-FEM as $E^{dge}\overline{F} = E^{dge}\overline{J}^{1/3} E^{dge}F^{iso}$.

Hereafter, F-barES-FEM-T4 with *c* cycles of smoothing is called "F-barES-FEM-T4(*c*)".





A kind of

low-pass filter

for *J*

Cyclic

Smoothing

of J

Equations to Satisfy Implicit static

• Balance equation: $\{f^{\text{ext}}\} - \{f^{\text{int}}\} = \{0\}.$

 In Newton-Raphson loop, there is a need for solving the matrix equation:

 $[K]{\delta u} = {f^{\text{ext}}} - {f^{\text{int}}}.$

Dynamic explicit

- Motion equation: $[M]{\ddot{u}} = {f^{\text{ext}}} {f^{\text{int}}}.$
- Using the lumped mass matrix for [*M*], there is no need for solving any matrix equations.
- Velocity Verlet method is applied for time integration.





<u>Results</u>

Some verification analyses

(Analyses for hyperelastic materials <u>without</u> mesh rezoning are presented for pure verification.)





Bending of a Cantilever

<u>Outline</u>

Static

Implicit



- Neo-Hookean hyperelastic material
- Initial Poisson's ratio: 0.49 or 0.499.
- Two types of T4 meshes: a structured mesh and an unstructured mesh.
- Compared to ABAQUS C3D4H (1st-order hybrid tetrahedral element).







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Compared to ABAQUS C3D4H with the same unstructured T4 mesh.





Compression of a Block

Pressure Distribution

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Static

Implicit



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Compression of a Block

Pressure Distribution

Static

Implicit









• Neo-Hookean hyperelastic material ($v_{ini} = 0.499$).

- Enforced displacement is applied to the top surface.
- Compared to ABAQUS C3D4H with the same unstructured T4 mesh.











Implicit Barreling of 1/8 Cylinder

<u>Result</u> <u>of F-bar</u> <u>ES-FEM(2)</u> (Mises Stress)

50% nominal compression

Smooth Mises stress distribution is obtained except just around the rim.



Mises_Stress (Pa)

0e+00 7e+7 1.4e+8 2e+08





Examplicit Barreling of 1/8 Cylinder **Pressure Distribution**

Streppe defermation (comer lacking)



F-barES-FEM-T4 with a sufficient cyclic smoothing can resolve the corner locking issue.



Bending of a Cantilever

Outline 10 m 1 m 1 m 1 m Neo-Hookean Hyperelastic Material z y z yinitial condition: $\dot{u}_z = -2.0$ m/s (uniform)

Neo-Hookean hyperelastic material:

- $E_{\text{ini}} = 6 \text{ MPa}, \ v_{\text{ini}} = 0.499, \ \rho = 1000 \text{ kg/m}^3.$
- Uniform initial velocity: $\dot{u}_z = -2 \text{ m/s}$.
- Compared to ABAQUS/Explicit C3D4 (NOT C3D4H)
 & C3D8 (hexahedral selective reduced integration).



Dynamic

Explicit

Dynamic Bending of a Cantilever

Pressure sign distributions





F-barES-FEM has no locking & less pressure oscillation in dynamic explicit analysis.







F-barES-FEM-T4 has good accuracy in pressure.







Displacement accuracy of F-barES-FEM is independent of the number of cyclic smoothing.





Swinging of Bunny Ears



- Iron ears: $E_{ini} = 200 \text{ GPa}$, $v_{ini} = 0.3$, $\rho = 7800 \text{ kg/m}^3$, Neo-Hookean, **No cyclic smoothing.**
- Rubber body: $E_{ini} = 6$ MPa, $v_{ini} = 0.49$, $\rho = 920$ kg/m³, Neo-Hookean, **1 cycle of smoothing.**
- Compared to ABAQUS/Explicit C3D4.



Dynamic

Explicit



Dynamic Swinging of Bunny Ears Explicit Swinging of Bunny Ears Pressure sign distributions



- F-barES-FEM is apparently softer than C3D4.
- F-barES-FEM shows patchy pressure patterns due to complex reflections of pressure waves.
- C3D4 shows typical checkerboard patterns.





Explicit Swinging of Bunny Ears <u>Pressure distributions (back shot)</u>



C3D4 shows checkerboard patterns even on the iron ears. (Because of the negative influence from rubber body???)

F-barES-FEM-T4 shows smooth pressure distribution except the connection interfaces (corners).





Mode Natural Modes of 1/4 Cylinder Outline



- Iron part: $E_{ini} = 200 \text{ GPa}$, $v_{ini} = 0.3$, $\rho = 7800 \text{ kg/m}^3$, Elastic, **No cyclic smoothing.**
- Rubber part: $E_{ini} = 6$ MPa, $v_{ini} = 0.499$, $\rho = 920$ kg/m³, Elastic, **2 cycles of smoothing.**
- Compared to ABAQUS C3D4, C3D4H, and C3D8.





Eigen Natural Modes of 1/4 Cylinder Eigen frequencies



C3D4 and C3D4H show higher frequencies (stiffer results).

■ F-barES-FEM-T4 and C3D8 are in good agreement.

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Mode Natural Modes of 1/4 Cylinder

<u>Eigen modes</u>



F-barES-FEM-T4 has good accuracy in eigen mode analysis.





<u>Summary</u>





Benefits and Drawbacks of F-barES-FEM-T4

<u>Benefits</u>

- Locking-free with 1st -order tetra meshes.
 No difficulty in severe strain or contact analysis.
- No increase in DOF.
 No need of static condensation.
- ✓ No restriction of material constitutive model.
- ✓ Less pressure oscillation in rubber-like materials.
- Less corner locking.
- Applicable to static/dynamic, implicit/explicit, and modal analyses.





Benefits and Drawbacks of F-barES-FEM-T4

<u>Drawbacks</u>

X Slow speed of calculation.



In *implicit* analyses, CPU Time is roughly linear with respect to the band width of [K].





Benefits and Drawbacks of F-barES-FEM-T4

<u>Drawbacks</u>

X Slow speed of calculation.



In *explicit* analyses, [K] is unnecessary; yet, CPU Time increases gradually with the # of cyclic smoothings.





Conclusion

F-barES-FEM-T4 has excellent accuracy, but needs some effort for speed-up.

Thank you for your kind attention!



