

Explicit Dynamic Analysis using **SelectiveCS-FEM-T10** with Radial Element Subdivision

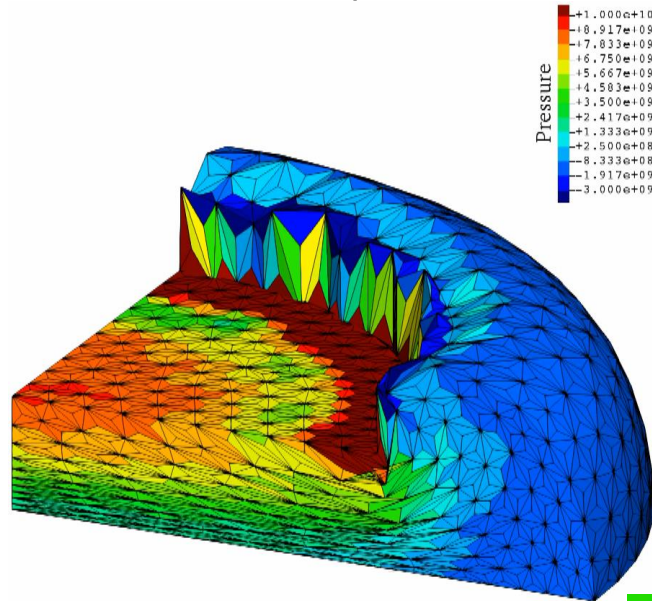
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(Tokyo Institute of Technology)

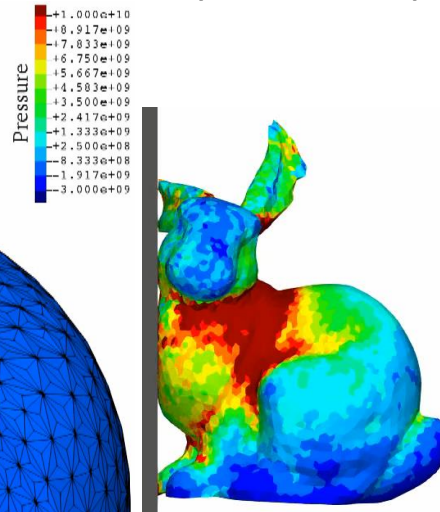
Applications of S-FEMs in Our Lab

■ Large deformation solid mechanics (still in academic)

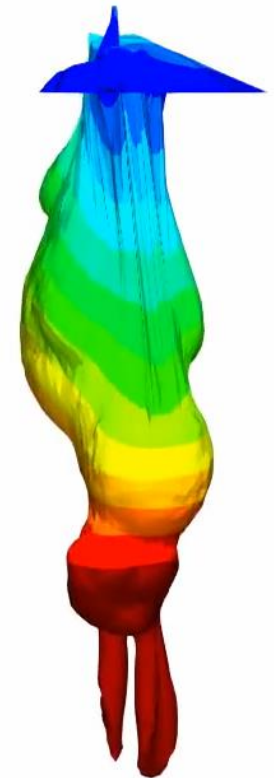
Static Implicit



Dynamic Explicit



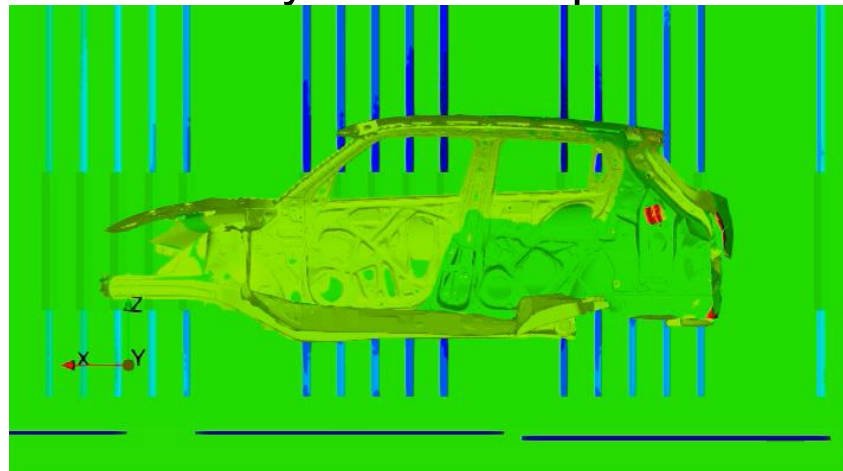
Viscous Implicit



■ Electrostatic (already in practice)

- 64 CPUs (512 cores)
- MPI/OpenMP hybrid
- 140M elements
- 2000 timesteps
- 18.5 h wall time

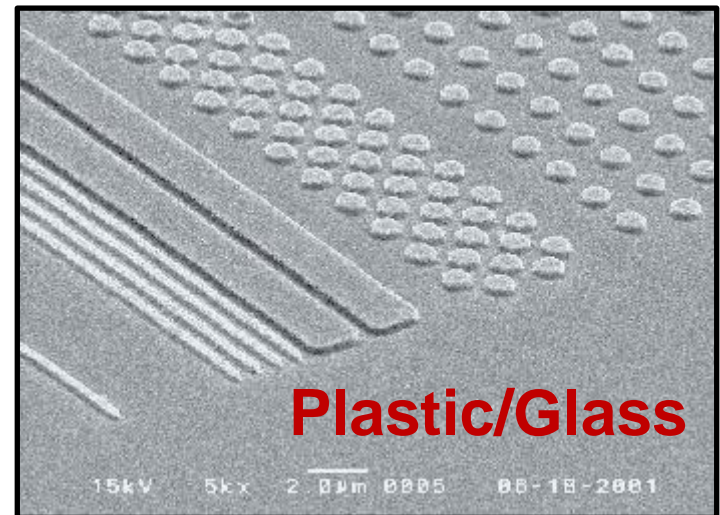
Carbody Electro Deposition



Motivation

What we want to do:

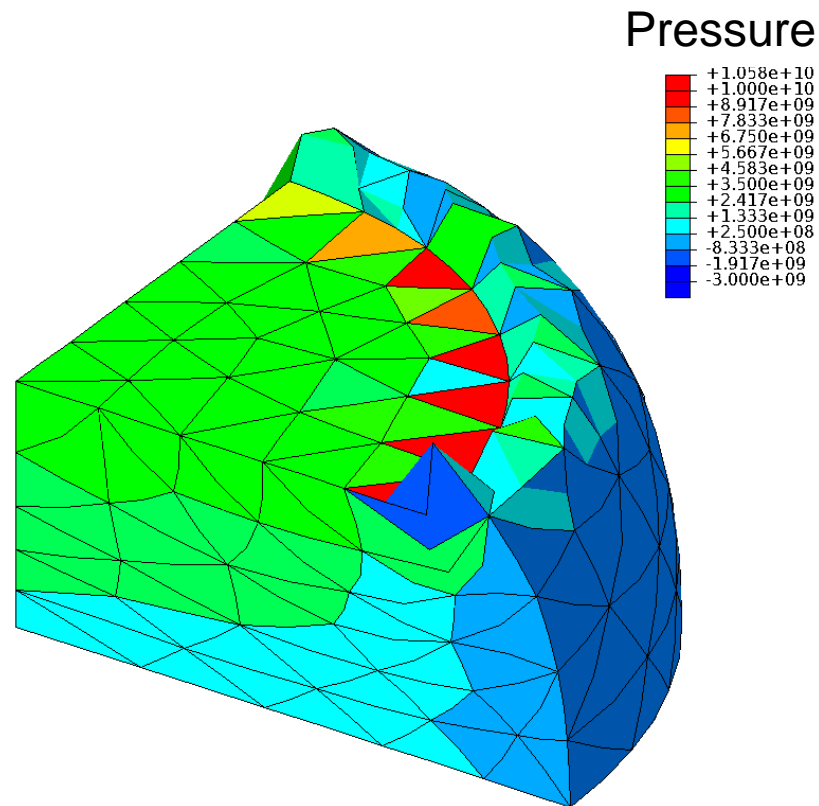
- Solve **severe large deformation** analyses accurately and robustly.
- Treat complex geometries with **tetrahedral meshes**.
- Consider **nearly incompressible materials** ($\nu \simeq 0.5$).
- Support **contact** problems.
- Handle **auto re-meshing**.



Issues (e.g., barreling analysis of rubber cylinder)

Neo-Hookean hyperelastic body with $\nu_{ini} = 0.49$

With the best tetrahedral element in ABAQUS



T10:
10-node Tetrahedra

2nd order modified hybrid T10 (ABAQUS C3D10MH)

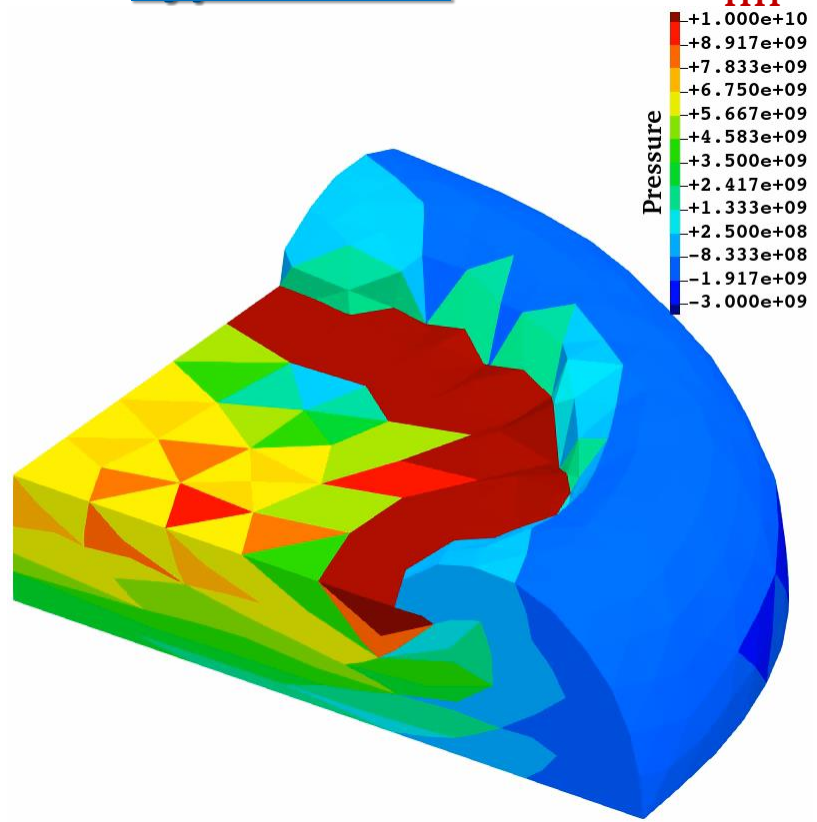
- ✓ No shear/volumetric locking
- ✗ Short lasting (weak to severe deformation)
- ✗ Low interpolation accuracy

Our Approach (e.g., barreling analysis of rubber cylinder)

Neo-Hookean hyperelastic body with $\nu_{ini} = 0.49$

With the our latest S-FEM tetrahedral element

Same mesh & contour range as C3D10MH case.



Selective CS-FEM-T10 is much better than conventional tetrahedral elements in static analyses.

Y. Onishi, IJCM, (2021).



Latest S-FEM T10 (SelectiveCS-FEM-T10)

- ✓ No shear/volumetric locking
- ✓ Less pressure checkerboarding
- ✓ Long lasting (robust to severe deformation)
- ✓ Same CPU time as T10 elements.

Further evaluation is necessary in dynamic analyses.

Objective

1. Development of a **dynamic** version of **SelectiveCS-FEM-T10**
2. Evaluation of its **accuracy and robustness** in dynamic severe large deformation analyses.

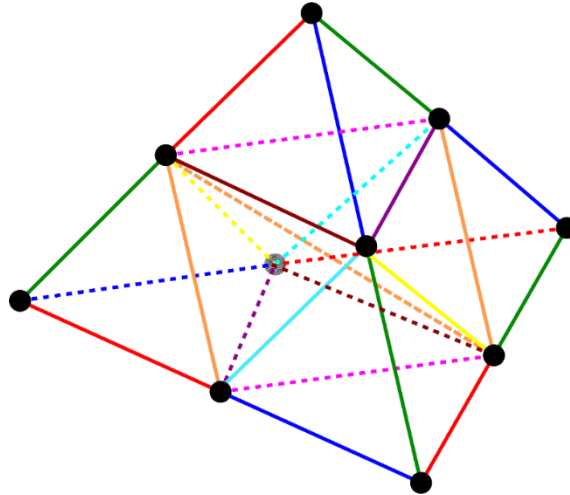
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- Methods: Formulation of SelectiveCS-FEM-T10
- Results: Demonstrations of SelectiveCS-FEM-T10
- Summary

Methods: Formulation of **SelectiveCS-FEM-T10**

Concepts of SelectiveCS-FEM-T10

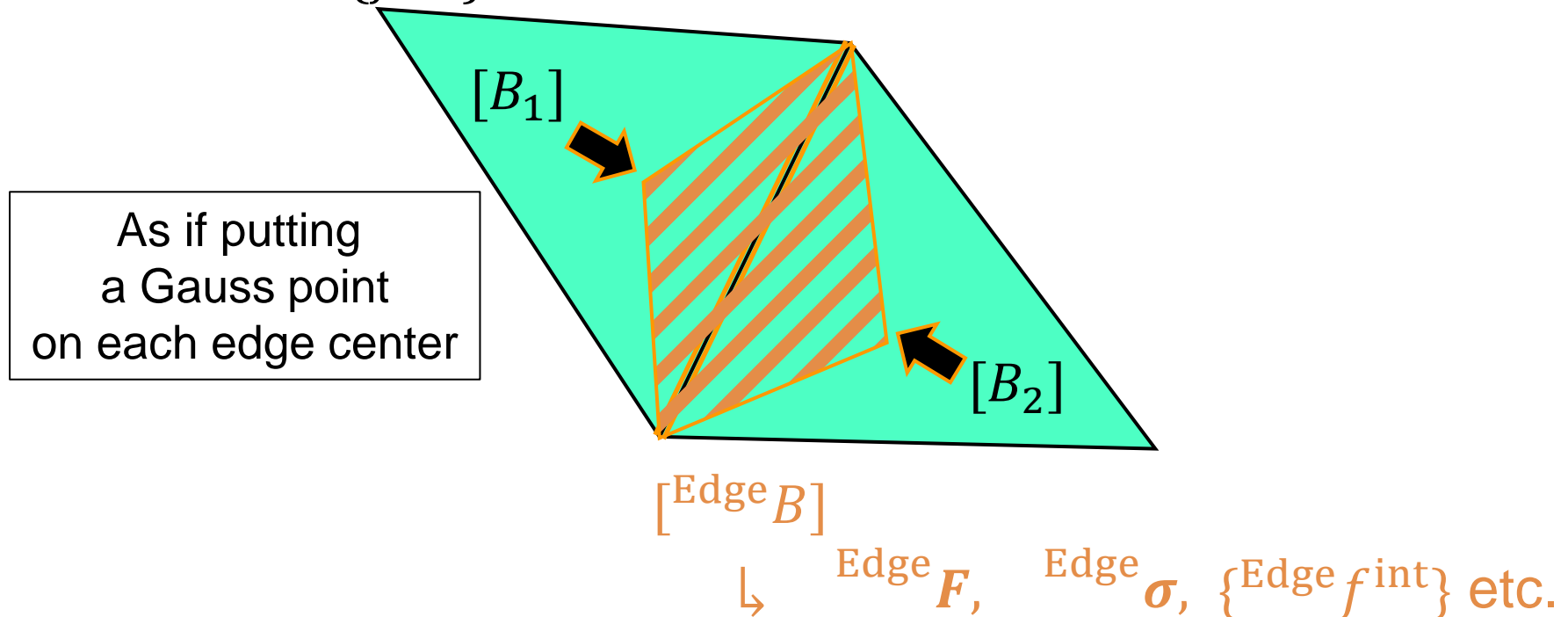
- Using T10 element and subdivide it into T4 sub-elements.
⇒ Overcomes the drawbacks of intermediate nodes.
- Adopting intra-element ES-FEM (a kind of CS-FEM) having no strain smoothing across multiple elements.
⇒ Becomes an independent element of existing FE codes.
- Applying selective reduced integration (SRI).
⇒ Overcomes volumetric locking.



Brief Formulation of ES-FEM

Let us consider two 3-node triangular elements in 2D for simplicity.

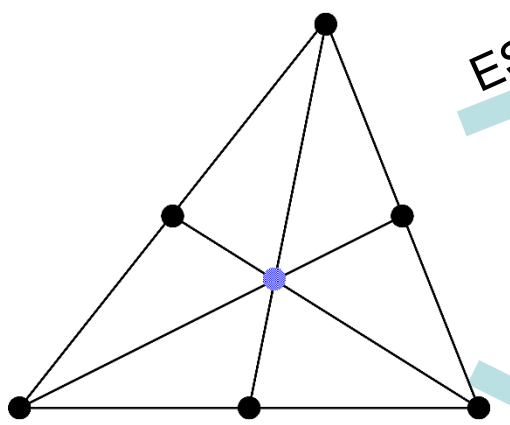
- Calculate $[B](= dN/dx)$ at each element as usual.
- Distribute each $[B]$ to the connecting **edge** with an area weight and build $[{}^{\text{Edge}}B]$.
- Calculate deformation gradient (F), Cauchy stress (σ) and nodal internal force $\{f^{\text{int}}\}$ in each **edge smoothing domain**.



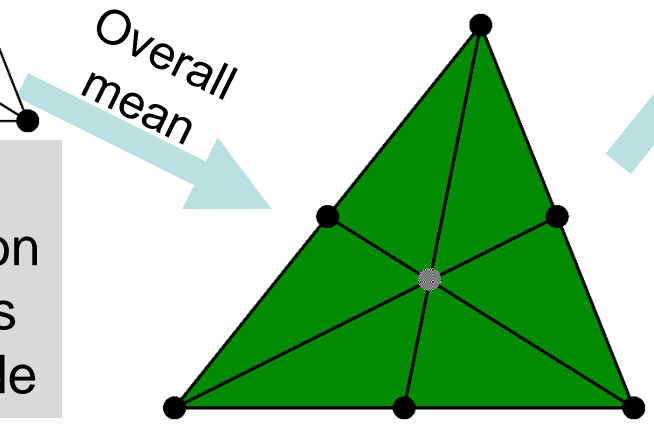
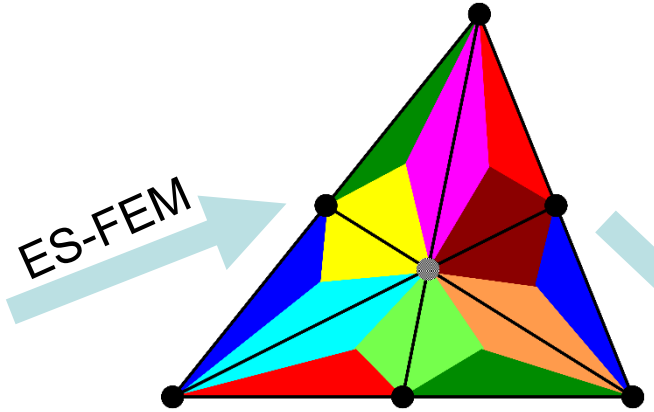
Flowchart of SelectiveCS-FEM-T10

Explanation in 2D (6-node triangular element) for simplicity

(2) Iso-vol. strain smoothing at edges



(1) Radial type element subdivision into sub-elements with a dummy node



(3) Vol. strain smoothing with all sub-elements

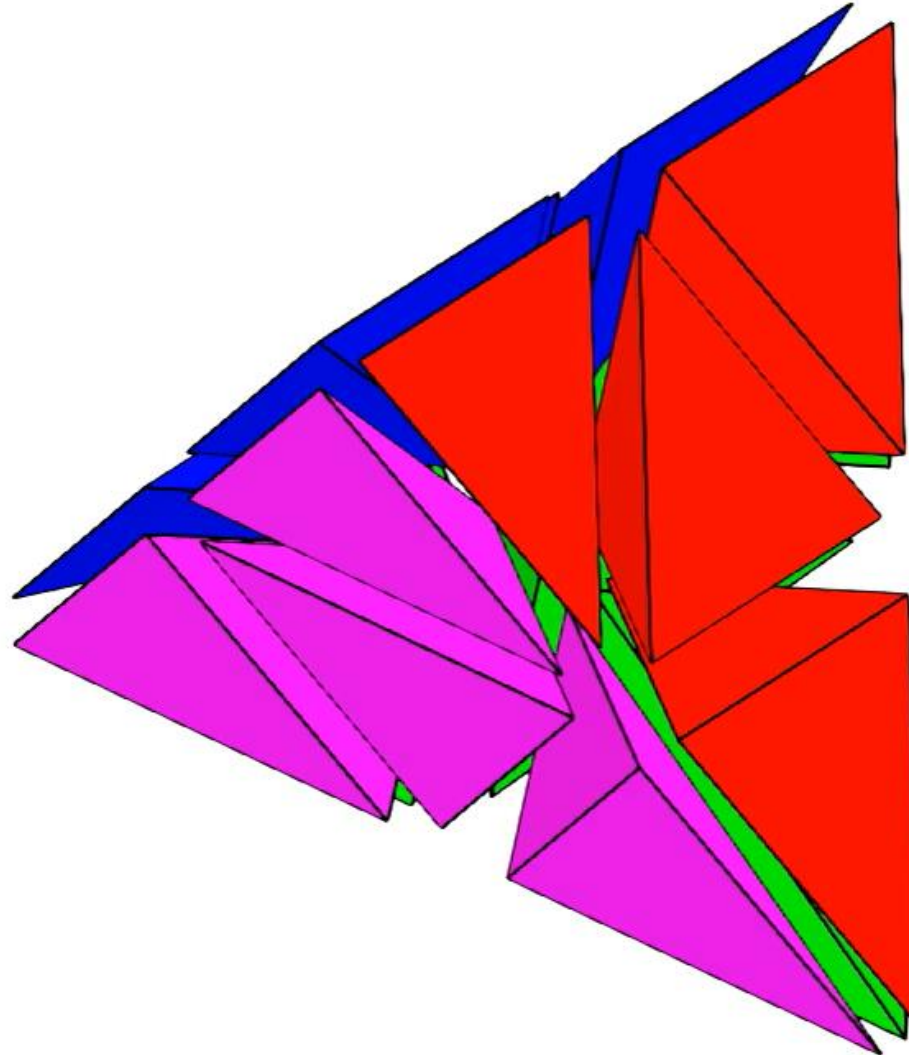
SRI

(4) $\{f^{int}\}$ and $[K]$

T10 Element Subdivision in 3D

Radial subdivision (30% shrunk mesh)

There are 16
T4 sub-elements
in total.



Strain on
all 34 edges
are smoothed
by ES-FEM.

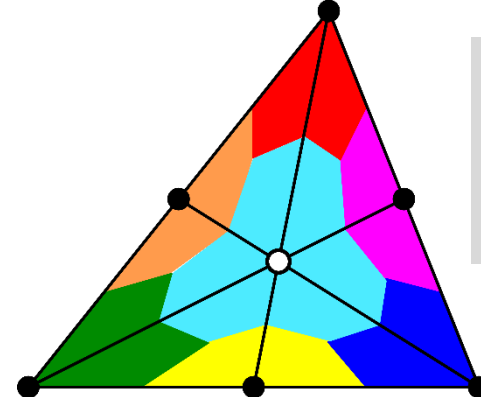
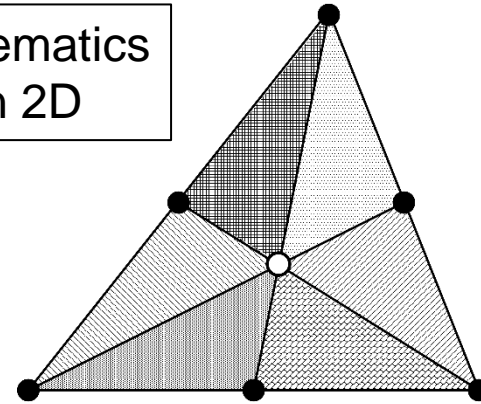
Sub-elements
have a little
larger skewness.

but skewness
is not a big issue
for ES-FEM.

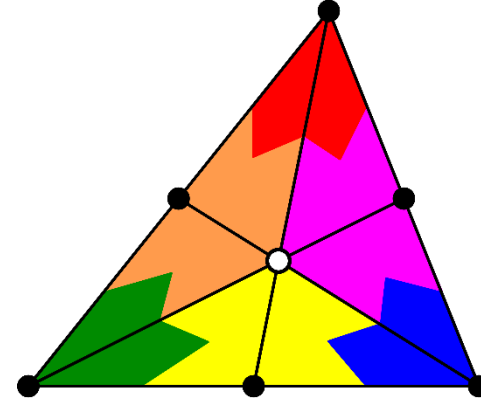
Building Lumped Mass Matrix

1. Calculate the mass of each sub-element.
2. Distribute it to composing 4 nodes.
(3 nodes in 2D.)
3. The mass of the dummy node is distributed to the connecting 6 mid-nodes.
(3 mid-nodes in 2D.)

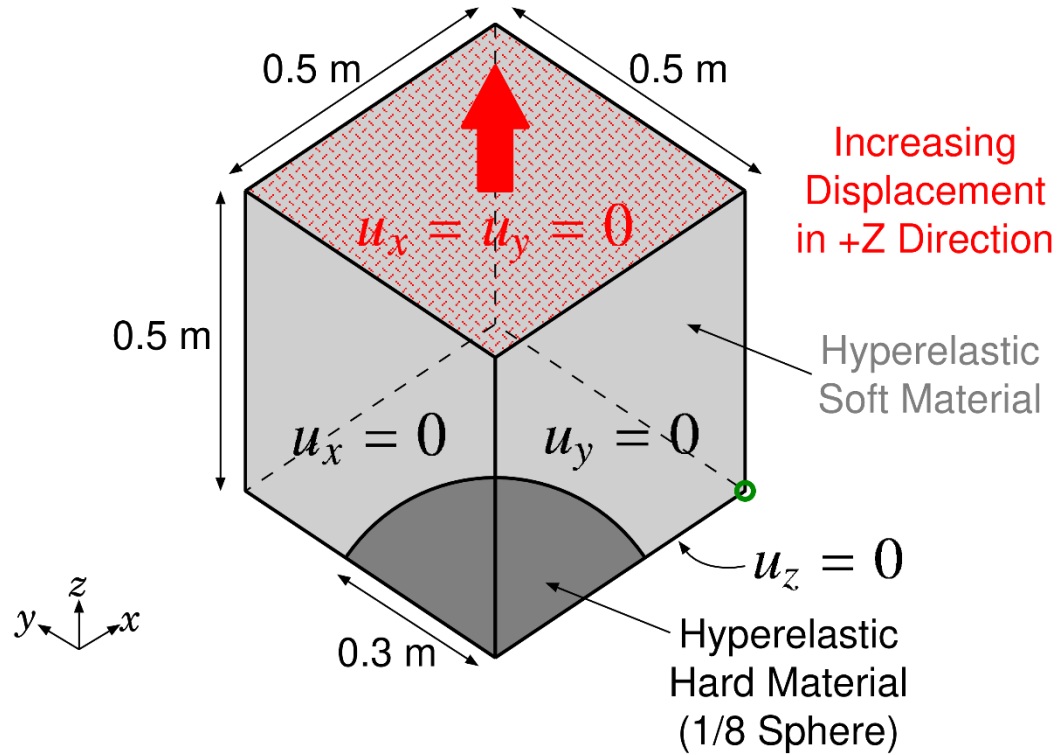
Schematics
in 2D



Each color denotes the corresponding area for mass.

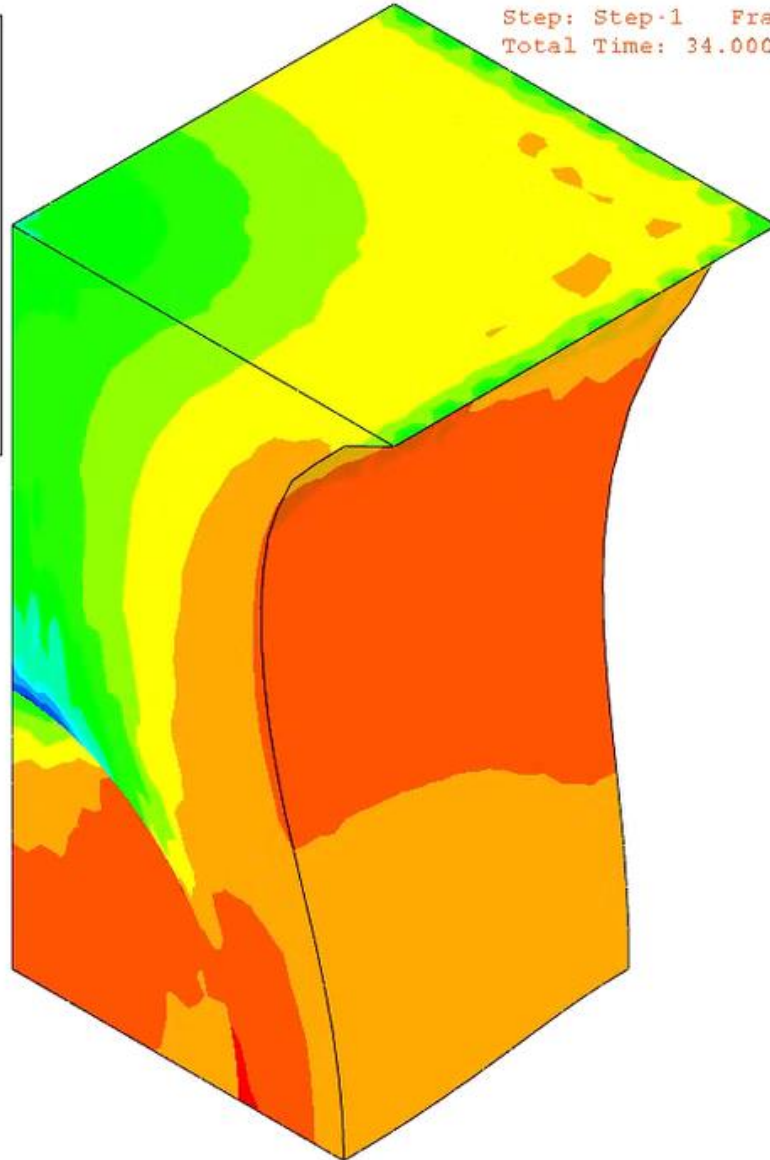
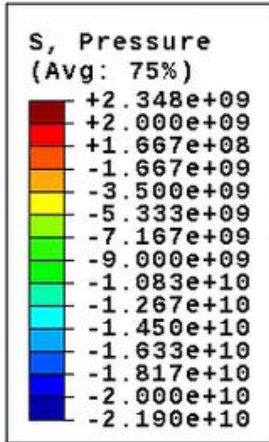


Results: Demonstration of **SelectiveCS-FEM-T10**

Outline

- Soft material: Neo-hookean, $E_{ini} = 6$ GPa, $\nu_{ini} = 0.49$.
- Hard material: Neo-hookean, $E_{ini} = 260$ GPa, $\nu_{ini} = 0.3$.
- Discretized into T10 mesh. (about 11,000 nodes and 7,000 elements)
- Compared to [ABAQUS C3D10MH](#), the best T10 element of ABAQUS, with the same mesh.

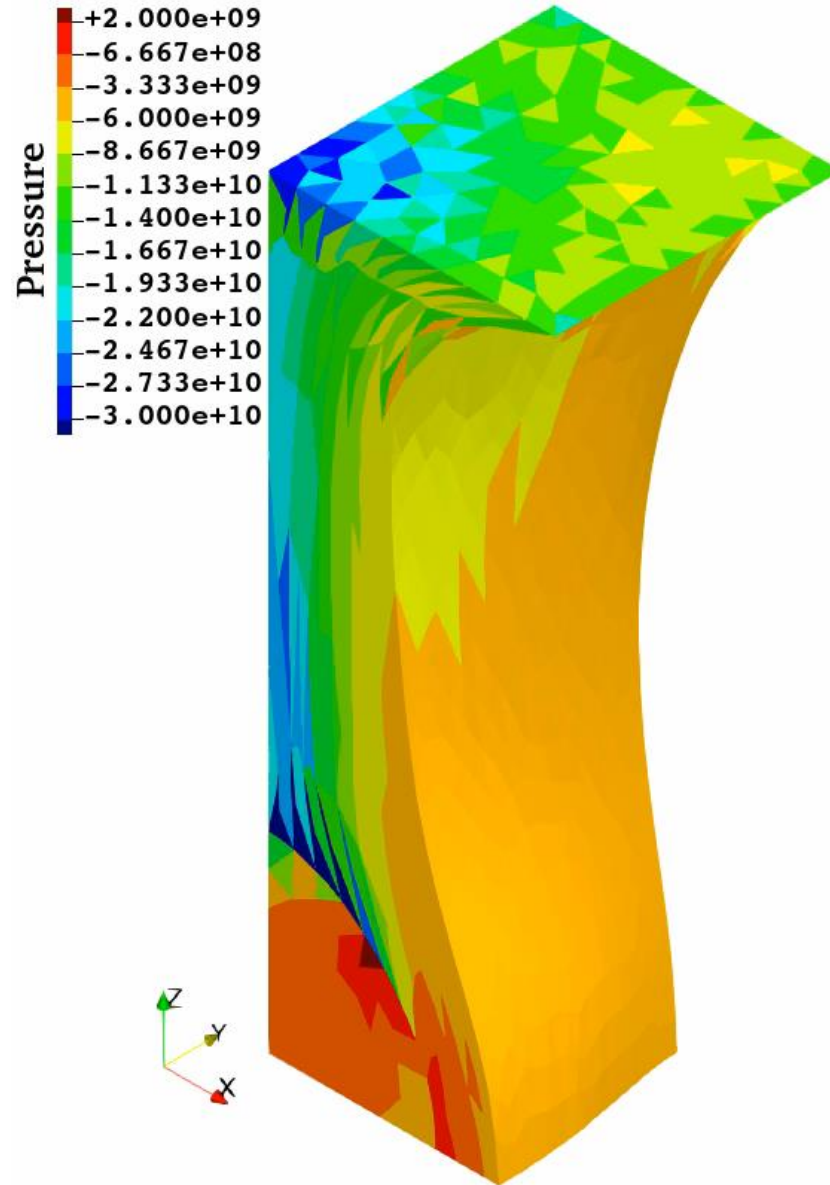
Result of
ABAQUS
C3D10MH
with
pressure
contour



Step: Step-1 Frame: 34
Total Time: 34.000000

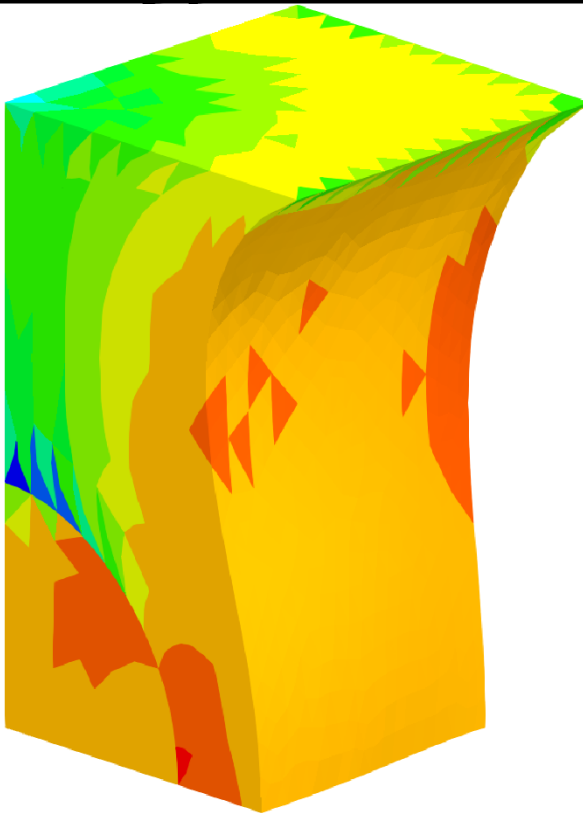
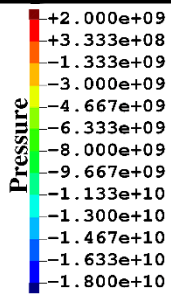
Convergence failure at 69% nominal stretch (short lasting)

Result of
Selective
CS-FEM-T10
with
pressure
contour

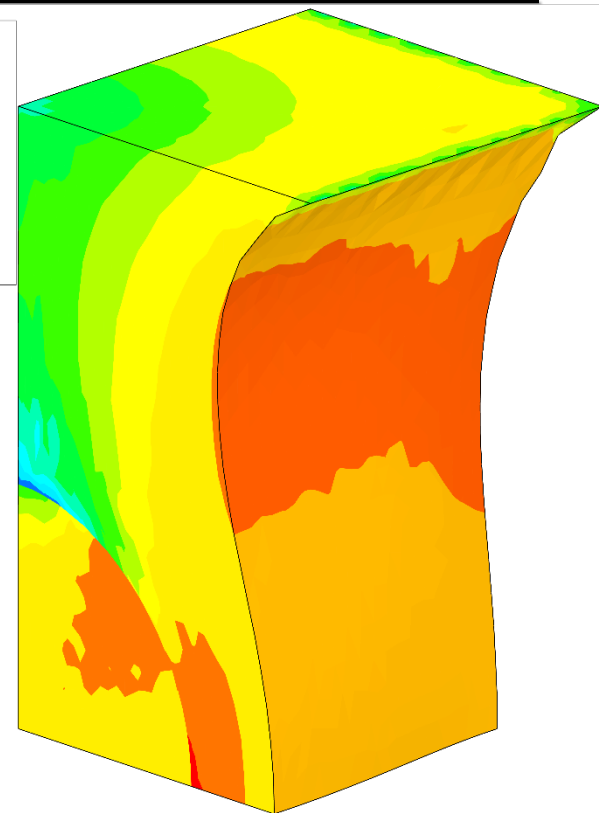
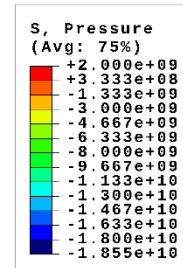


Convergence failure at 166% nominal stretch (long lasting)

Comparison of pressure dist. at 60% nominal stretch



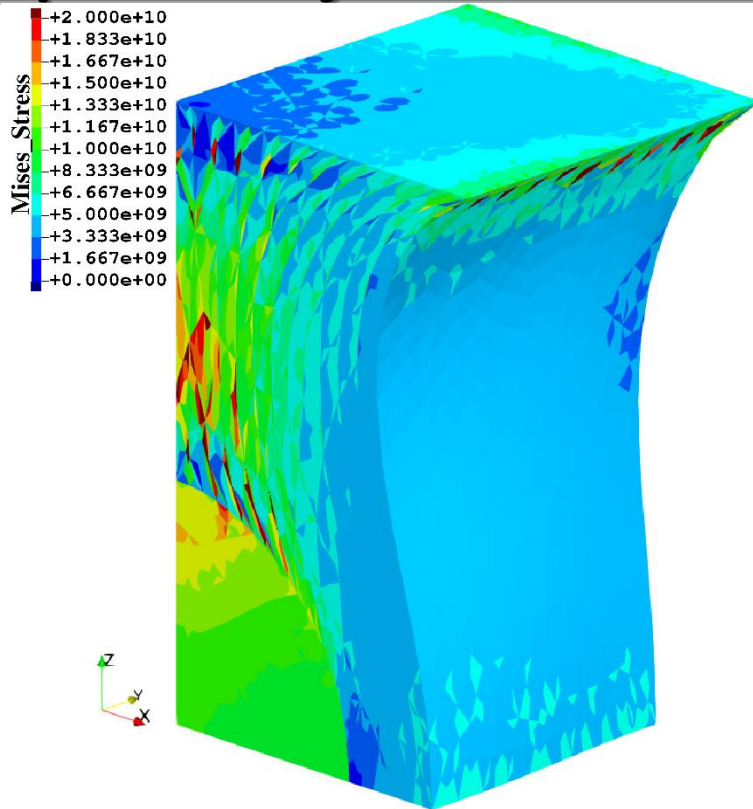
SelectiveCS-FEM-T10



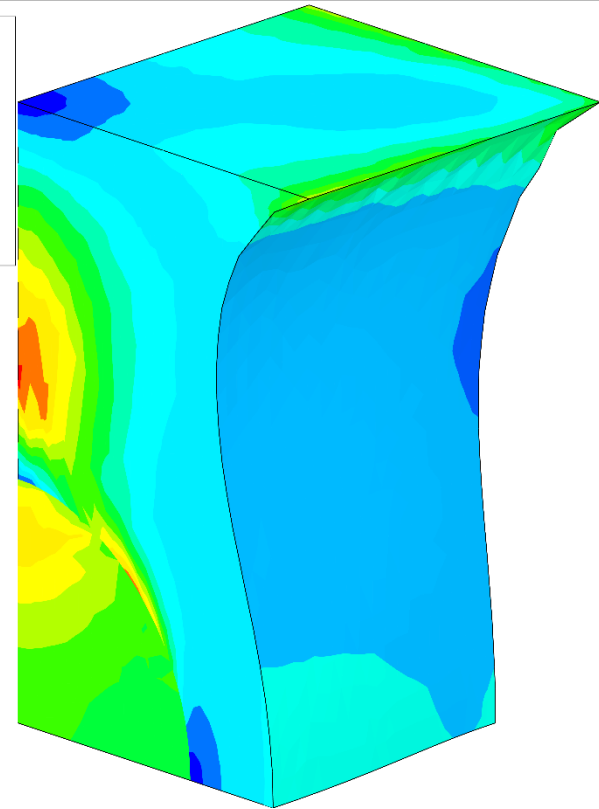
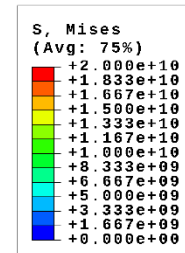
ABAQUS C3D10MH

SelectiveCS-FEM-T10 has good pressure accuracy.

Comparison of Mises stress dist. at 60% nominal stretch

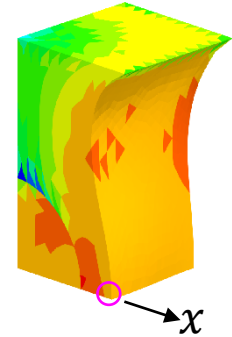
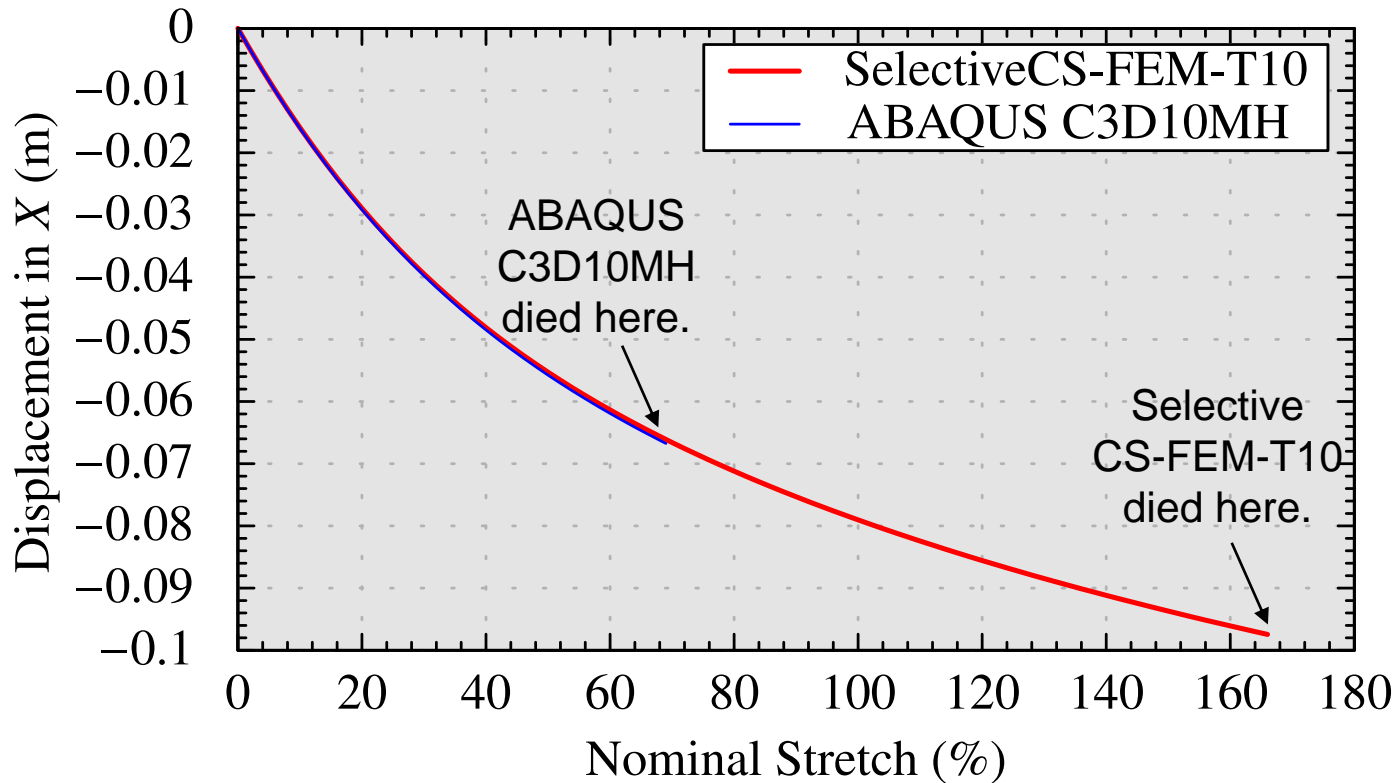


SelectiveCS-FEM-T10



ABAQUS C3D10MH

SelectiveCS-FEM-T10 has an **issue of Mises stress oscillation**, which should be resolved in the future.

Comparison of history of u_x at the bottom corner

SelectiveCS-FEM-T10 has enough accuracy in displacement (and force, also) in addition to large deformation robustness.

Outline

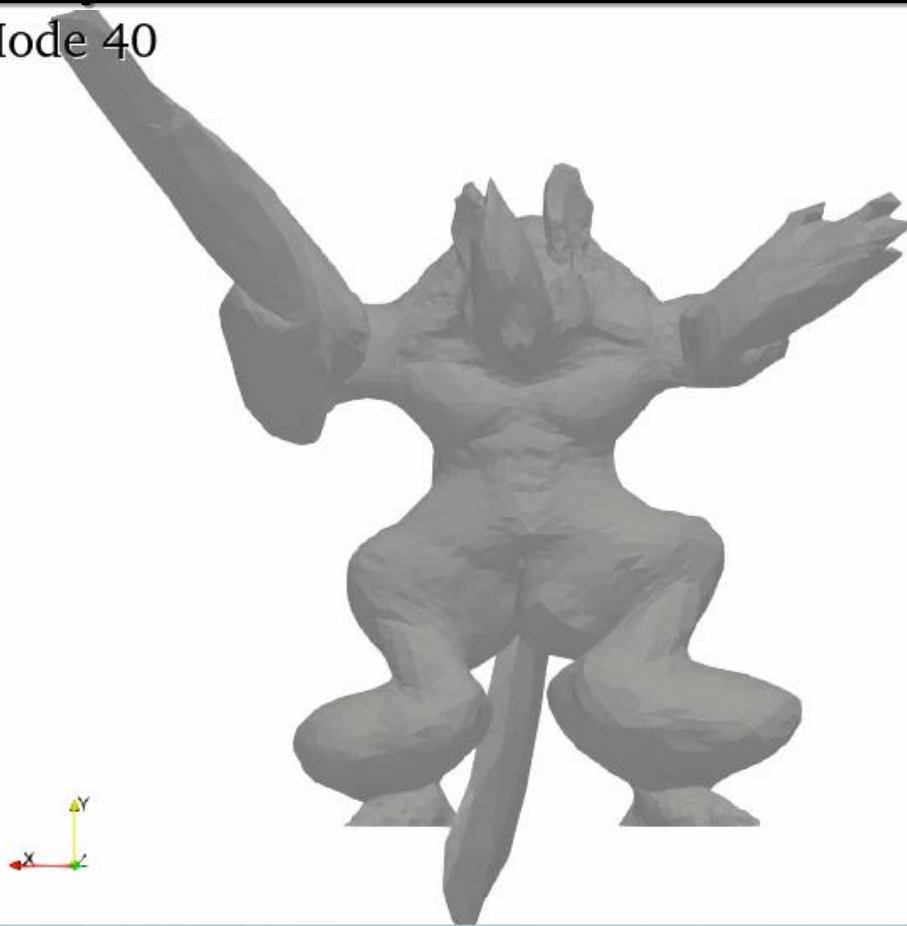
- Rubber body.
(Young's modulus: 5MPa,
Poisson's ratio: 0.49)
- Discretized in T10 mesh.
(about 80,000 nodes
and 52,000 elements)
- Both soles of the feet are
perfectly constrained.
- **Modal analysis up to 40
eigen modes.**
(This is not a large deformation analysis.)
- Compared to **ABAQUS C3D10MH** with the same mesh.



Deformation Modes of Armadillo

Eigen modes up to Mode 40 with SelectiveCS-FEM-T10

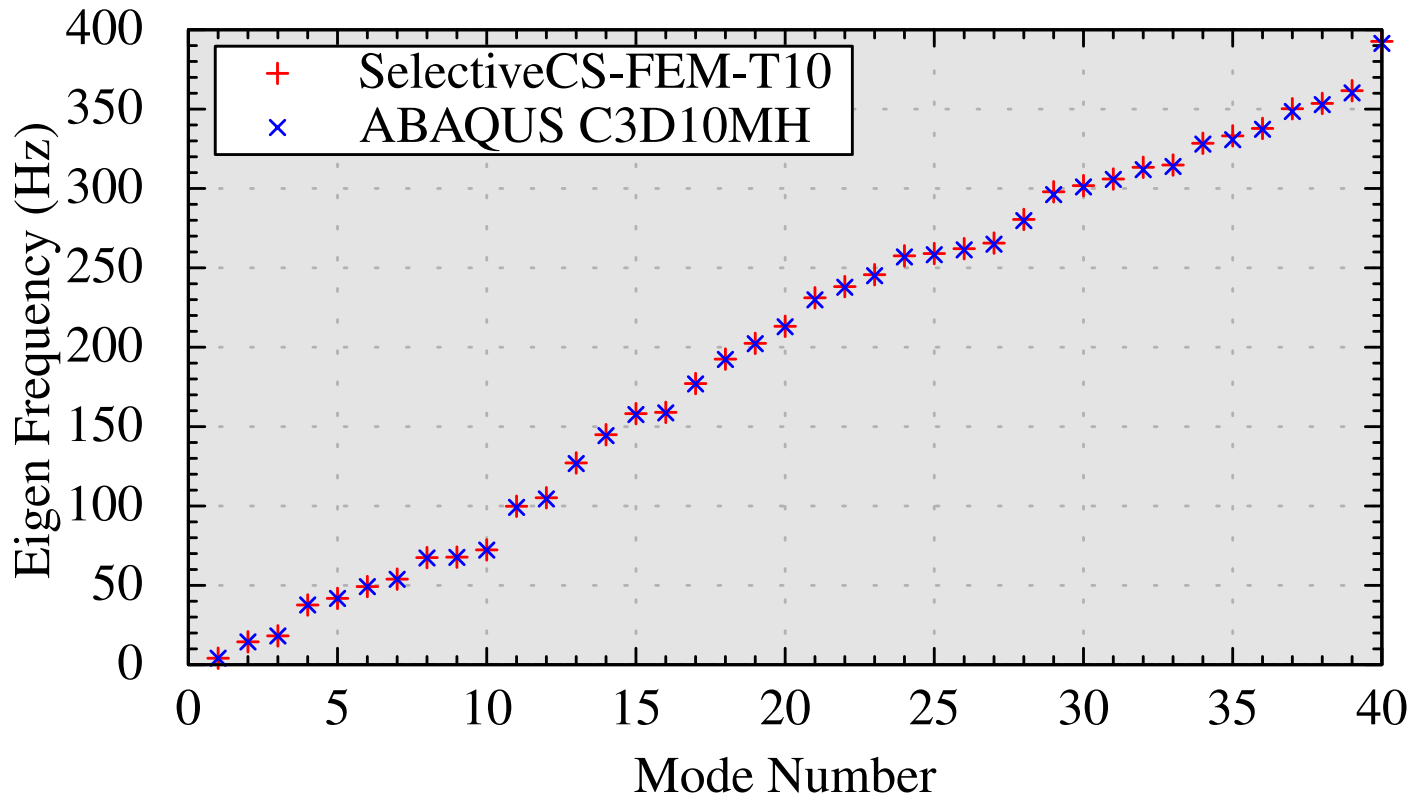
Mode 40



There are no
unnatural
modes.

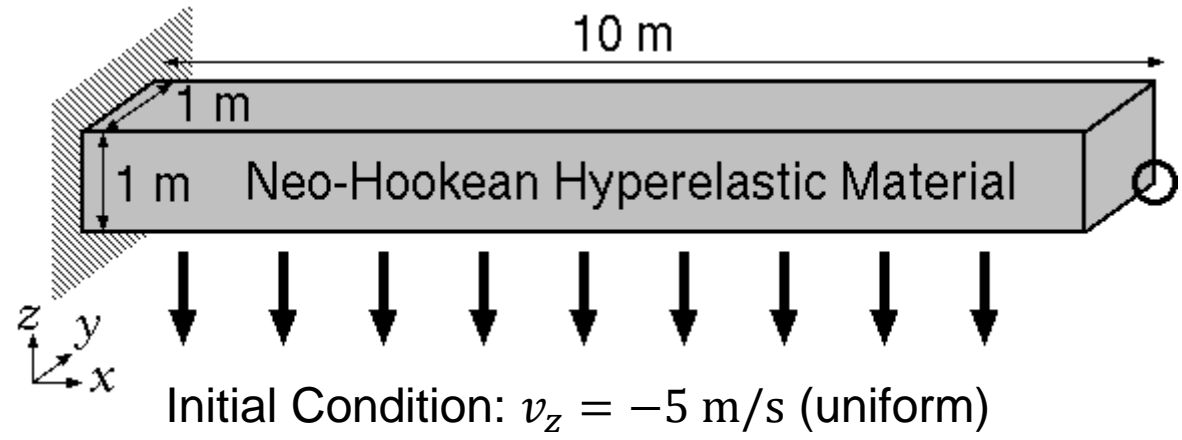
SelectiveCS-FEM-T10 has **no spurious low-energy modes**
like hour-glass modes.

Comparison of eigen frequencies



SelectiveCS-FEM-T10 has practical accuracy in modal analyses as ABAQUS C3D10MH; therefore, SelectiveCS-FEM-T10 would be **stable in dynamic analyses.**

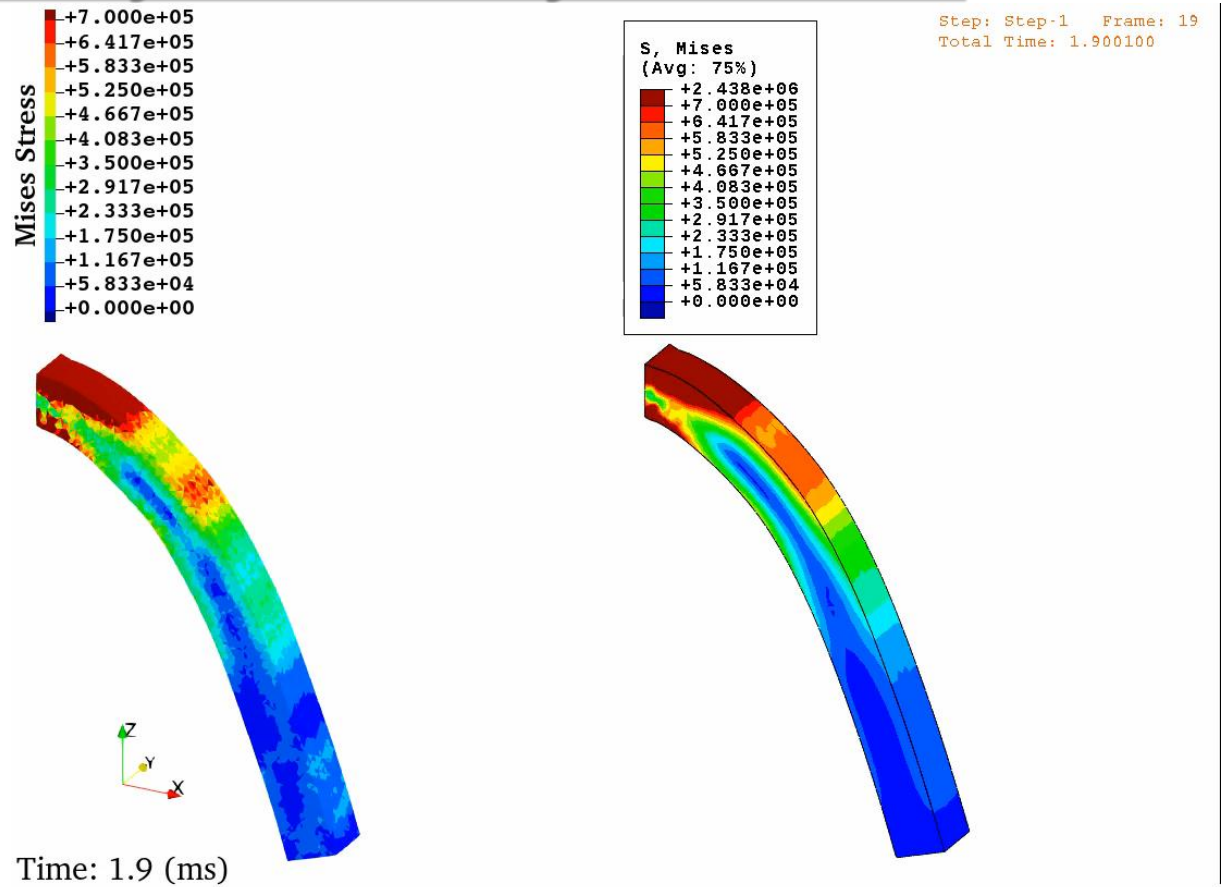
Dynamic Bending of Cantilever



- Neo-Hookean, $E_{ini} = 6.0$ MPa, $\nu_{ini} = 0.49$, $\rho = 920$ kg/m³
- Initial velocity: $v_z = -5$ m/s for all nodes of cantilever
- Discretized into T10 mesh. (about 4,000 nodes and 2,000 elements)
- Compared to [ABAQUS/Explicit C3D10M](#) (NOT C3D10MH) with the same mesh and $\Delta t (= 0.1$ ms).

Dynamic Bending of Cantilever

Comparison of animation of Mises stress



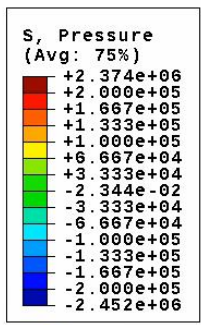
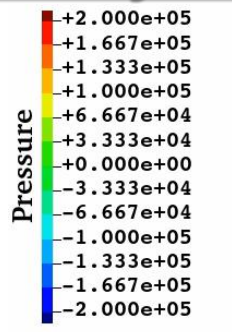
SelectiveCS-FEM-T10/Explicit

ABAQUS/Explicit C3D10M

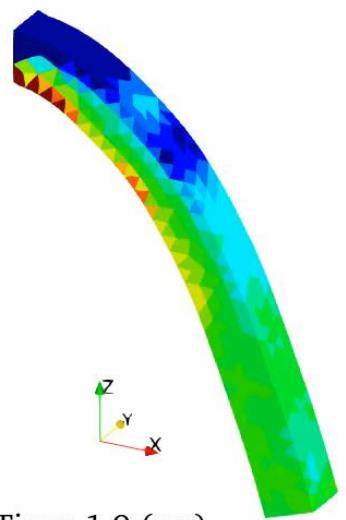
SelectiveCS-FEM-T10 has similar accuracy in displacement and Mises stress to ABAQUS C3D10M.

Dynamic Bending of Cantilever

Comparison of animation of pressure

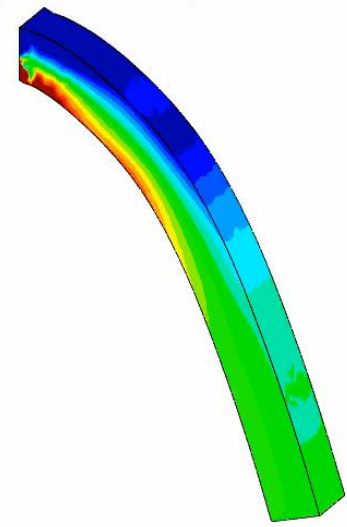


Step: Step-1 Frame: 19
Total Time: 1.900100



Time: 1.9 (ms)

SelectiveCS-FEM-T10/Explicit

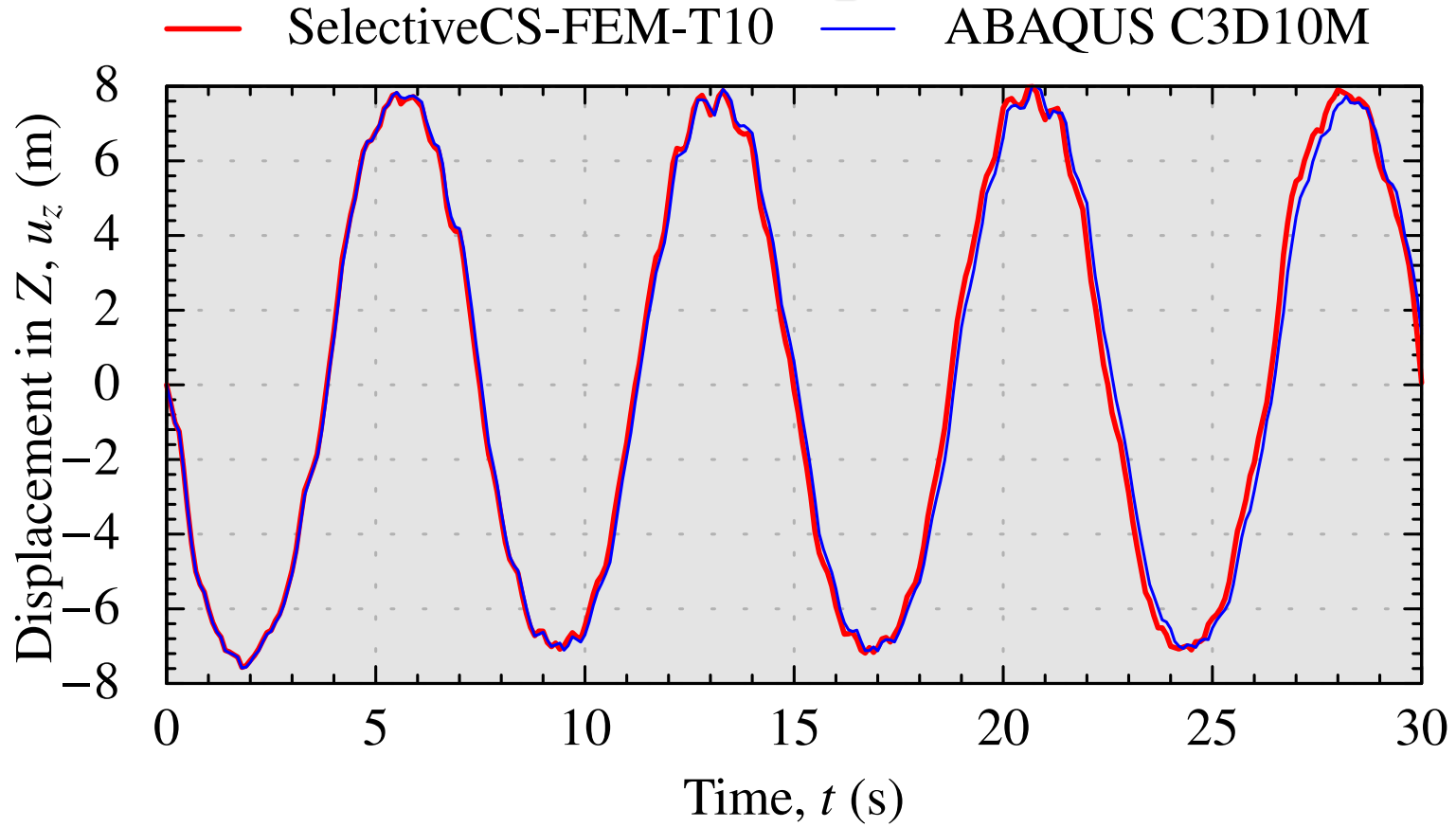


ABAQUS/Explicit C3D10M

SelectiveCS-FEM-T10 has similar accuracy in displacement and pressure to ABAQUS C3D10M.

Dynamic Bending of Cantilever

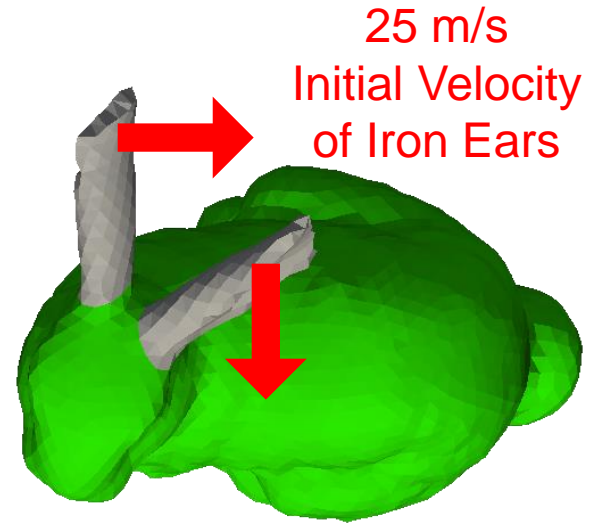
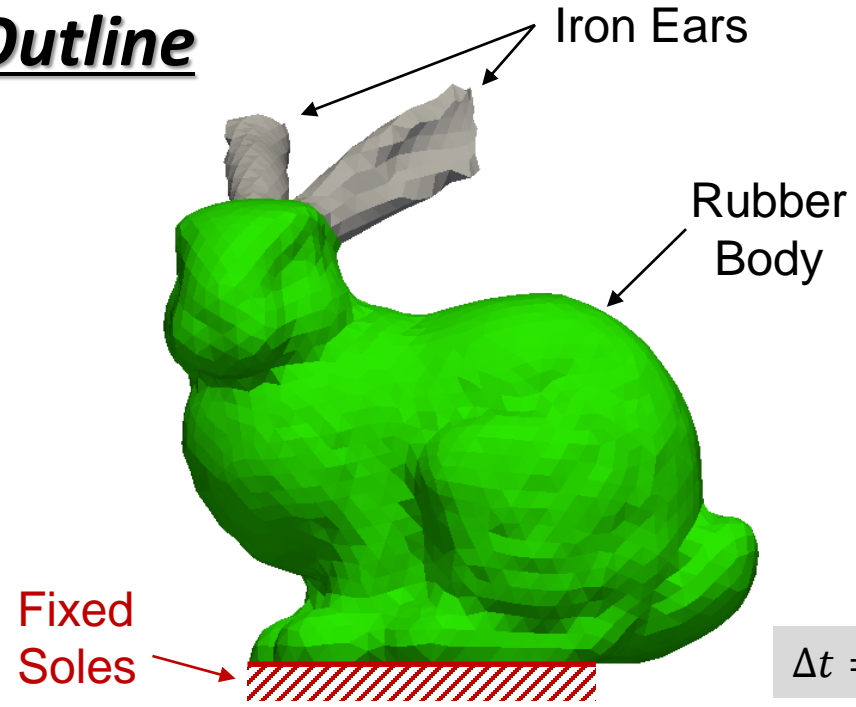
Comparison of time-history of u_z at the tip node



SelectiveCS-FEM-T10 has similar accuracy in displacement to ABAQUS C3D10M.

Swing of Bunny Ears

Outline



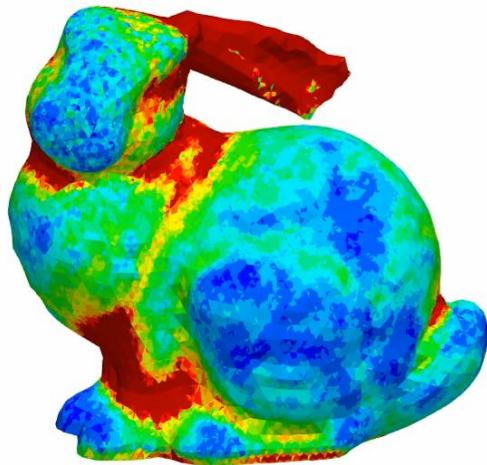
$\Delta t = 0.05 \mu s$, which is recommended Δt for C3D10M

- Iron ears: Neo-Hookean, $E_{ini} = 200 \text{ GPa}$, $\nu_{ini} = 0.3$, $\rho = 7800 \text{ kg/m}^3$.
- Rubber body: Neo-Hookean, $E_{ini} = 6 \text{ MPa}$, $\nu_{ini} = 0.49$, $\rho = 920 \text{ kg/m}^3$.
- Discretized into T10 mesh. (about 61,000 nodes and 41,000 elements)
- Compared to [ABAQUS/Explicit C3D10M](#) (NOT C3D10MH) with the same mesh and Δt .
- Contact is not considered.

Swing of Bunny Ears

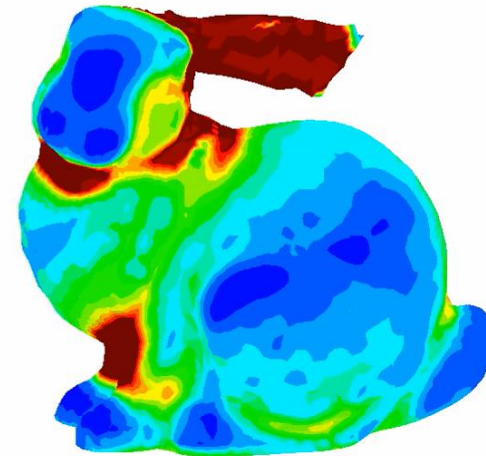
Comparison of Mises stress animation

Mises Stress
1.000e+06
9.167e+05
8.333e+05
7.500e+05
6.667e+05
5.833e+05
5.000e+05
4.167e+05
3.333e+05
2.500e+05
1.667e+05
8.333e+04
0.000e+00



Time: 37.3 (ms)

S, Mises
(Avg: 75%)
+1.623e+08
+1.000e+06
+9.167e+05
+8.333e+05
+7.500e+05
+6.667e+05
+5.833e+05
+5.000e+05
+4.167e+05
+3.333e+05
+2.500e+05
+1.667e+05
+8.333e+04
+0.000e+00



Step: Step-1 Frame: 373
Total Time: 0.037300

SelectiveCS-FEM-T10/Explicit

ABAQUS/Explicit C3D10M

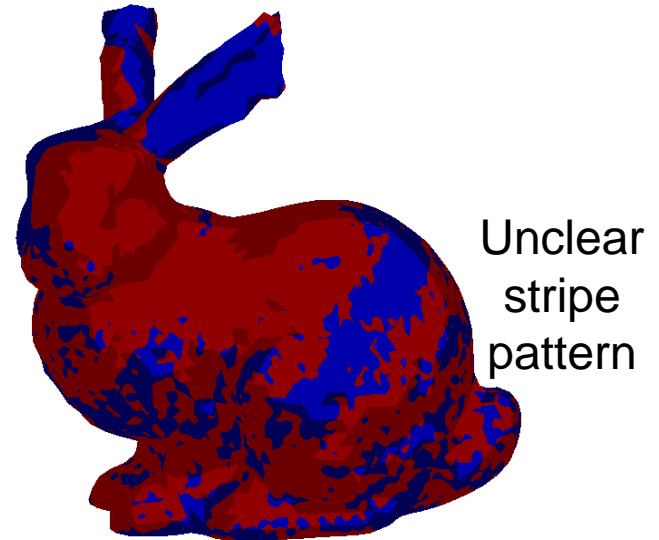
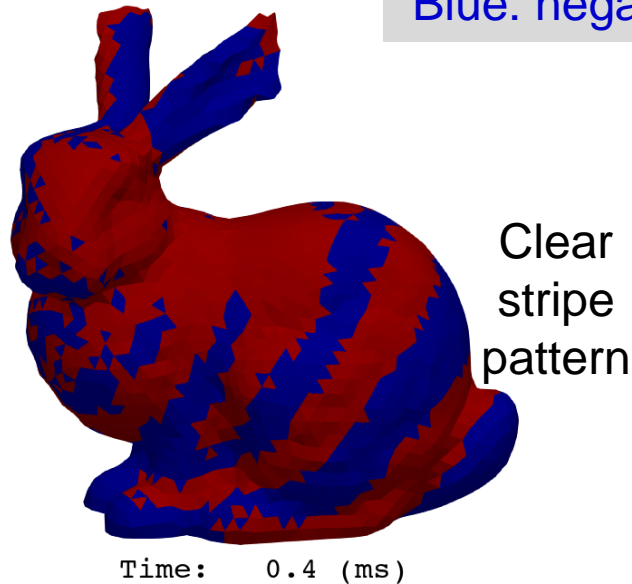
SelectiveCS-FEM-T10 has similar accuracy
in displacement and Mises stress
to ABAQUS C3D10M.

Swing of Bunny Ears

Comparison of pressure sign at $t = 0.4$ ms (right after the stat)

Step: Step-1 Frame: 4
Total Time: 0.000400

Red: positive pressure
Blue: negative pressure



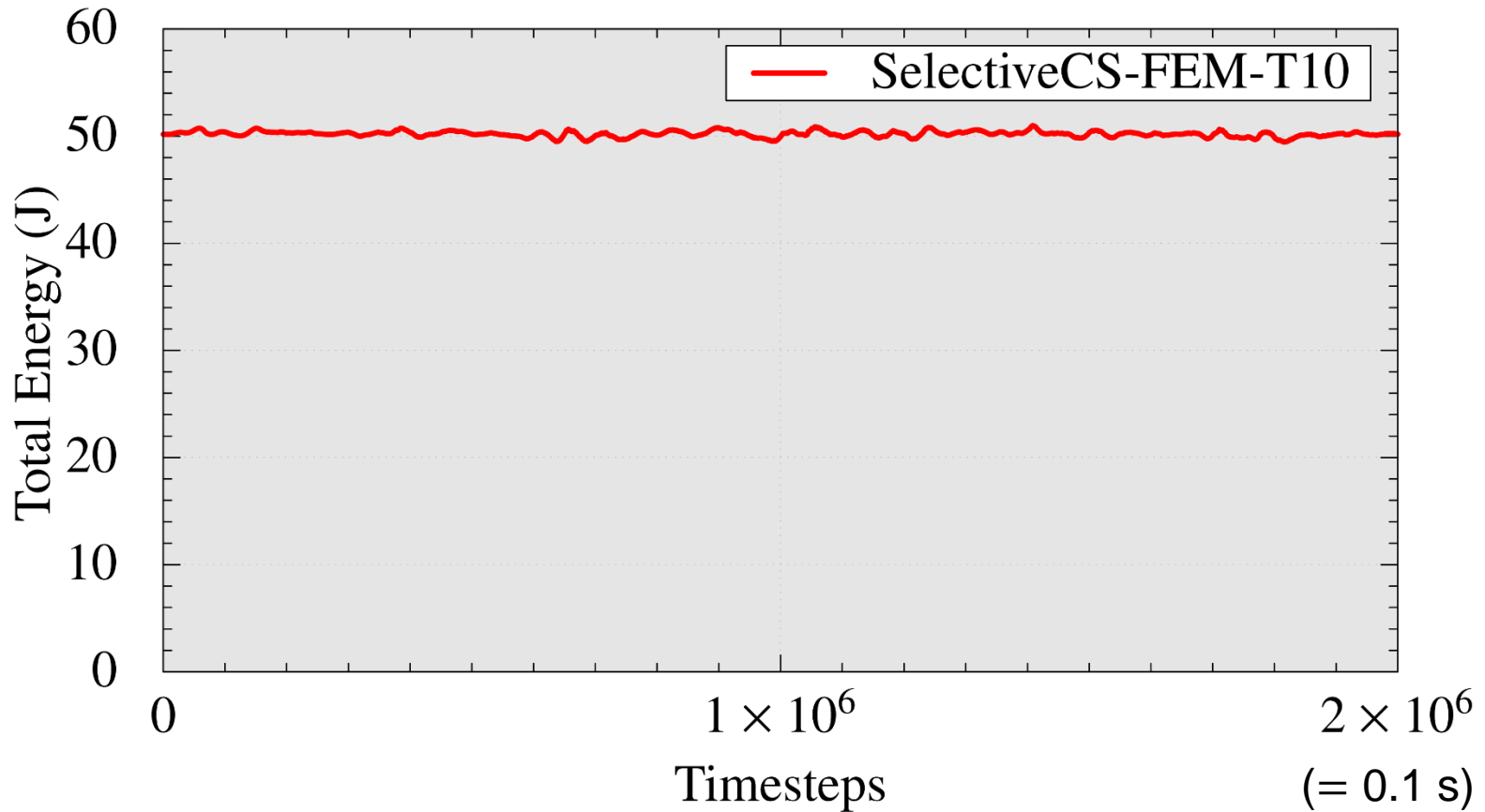
SelectiveCS-FEM-T10/Explicit

ABAQUS/Explicit C3D10M

SelectiveCS-FEM-T10 seems to calculate the initial pressure wave propagation more correctly than ABAQUS C3D10M.

Swing of Bunny Ears

Timestep-history of total energy (= kinetic + strain)



SelectiveCS-FEM-T10 has enough energetic stability in dynamic analysis.

Summary

Summary

Summary

- A new **SelectiveCS-FEM-T10** was proposed, which is:
 - **More robust to severe large deformation** than the conventional T10s.
 - **Enough accuracy for practical use** as compared to ABAQUS's best T10.
 - Slower than conventional T10s only in dynamic explicit analysis.
- More severe large deformation dynamic analyses should be performed for evaluation.

Take-home message

If you are interested in large deformation analysis,
please consider implementing **SelectiveCS-FEM-T10** to your FE code.
It's supremely useful & easy to code!!

Thank you for your kind attention!

Appendix

Characteristics of SelectiveCS-FEM-T10

Benefits

- ✓ Accurate (no locking, no checkerboarding, no force oscillation).
- ✓ Robust (long-lasting in large deformation).
- ✓ No increase in DOF (No static condensation).
- ✓ Same CPU costs as the other T10 elements (except explicit analyses).
- ✓ Implementable to commercial FE codes (e.g., ABAQUS UEL).

Drawbacks

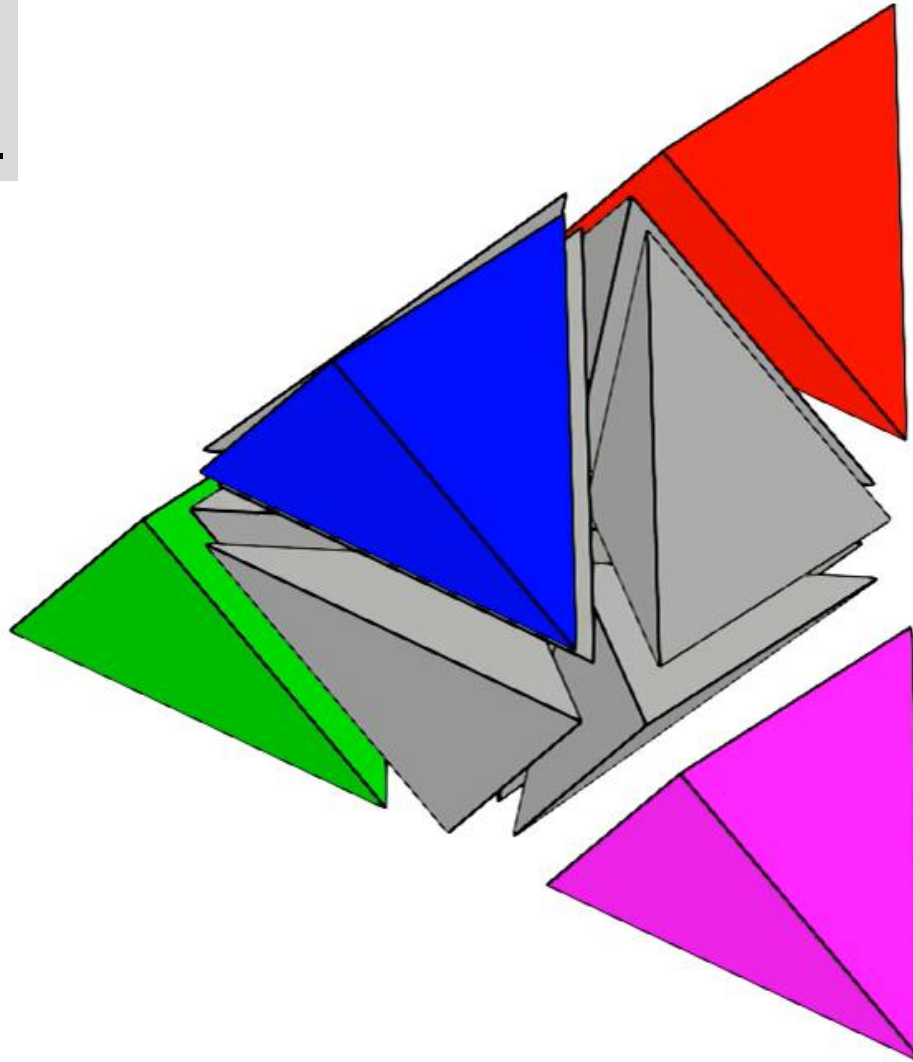
- ✗ Mises stress oscillation in some extreme analyses.
- ✗ Several times larger memory size than other T10 elements.
- ✗ No longer a T4 formulation.

SelectiveCS-FEM-T10 is competitive
with the best ABAQUS T10 element, C3D10MH.

T10 Element Subdivision in 3D

Natural subdivision (30% shrunk mesh)

Each frame edge is owned by only one sub-element.



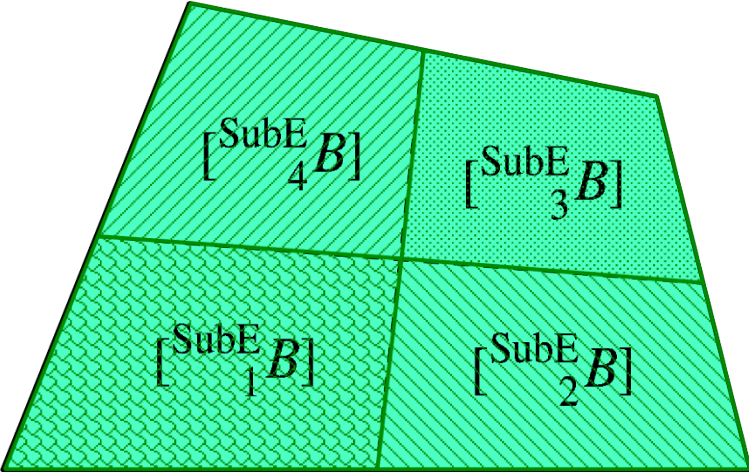
There are 12 sub-elements in total.

Strain on frame edges are NOT smoothed by ES-FEM.

Brief of Cell-based S-FEM (CS-FEM)

- Subdivide each element into some **sub-element**.
- Calculate $[{}^{\text{SubE}}B]$ at each sub-element.
- Calculate $F, T, \{f^{\text{int}}\}$ etc. in each sub-element.

As if putting
an integration point
on each sub-element



$$[{}^{\text{SubCell}}_i B]$$



$$\text{SubCell } T_i$$



$$\{f^{\text{int}}\}$$

CS-FEM

The biggest advantage
of CS-FEM is its
**portability to existing
FE codes.**

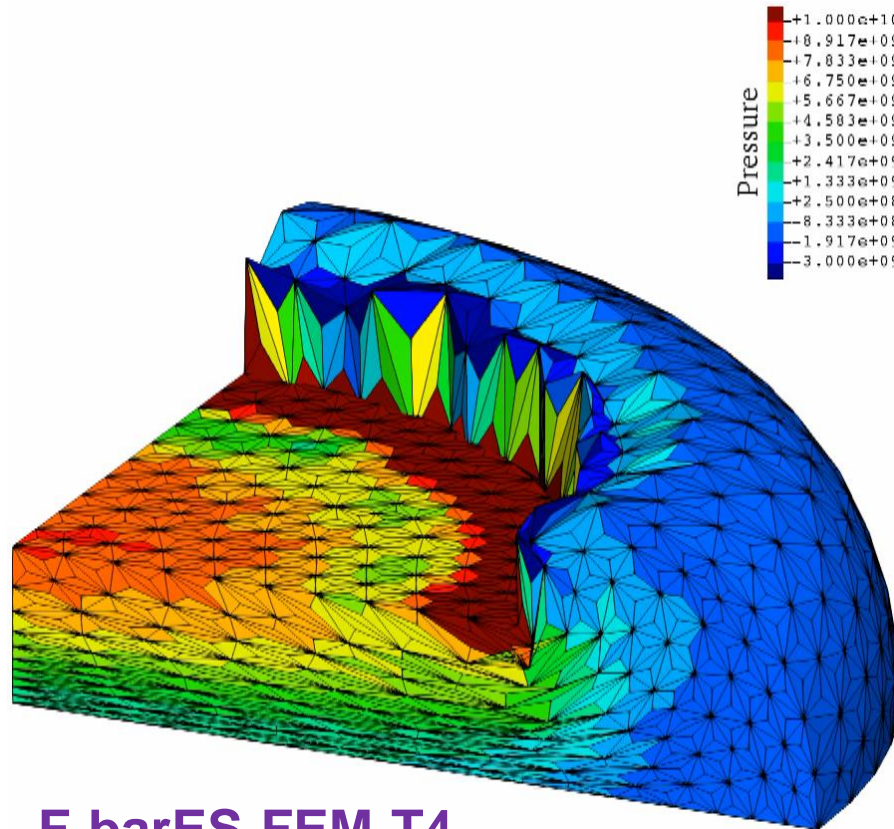
Conventional **tetrahedral (T4/T10)** FE formulations still have issues in accuracy and/or robustness especially in **nearly incompressible** cases.

- 2nd or higher order elements:
 - ✗ Volumetric locking. Accuracy loss in large strain.
- B-bar/F-bar method, Selective reduced integration (SRI):
 - ✗ Not applicable to tetrahedral element directly.
- F-bar-Patch method:
 - ✗ Difficulty in building good-quality patches.
- u/p mixed (hybrid) method (ABAQUS **C3D10MH** etc.):
 - ✗ Early convergence failure. Accuracy loss in large strain.
- F-bar aided ES-FEM-T4 [Y.Onishi, IJNME, 109 (2017)] :
 - ✓ Accurate & robust ✗ Hard to implement in FEM codes.
- SelectiveCS-FEM-T10 [Y.Onishi, IJCM, 17 (2020)] :
 - ✓ Accurate, robust & easy to implement. ✗ Not yet optimal.

Issues in Barreling Analysis of Rubber Cylinder

Neo-Hookean hyperelastic body with $\nu_{ini} = 0.49$

Same mesh
as **C3D4H**
case.



Although
F-barES-FEM-T4 is
accurate and robust,

- ✗ it consumes larger memory & CPU costs.
- ✗ it cannot be implemented in general-purpose FE software due to the adoption of ES-FEM.

F-barES-FEM-T4

- ✓ No shear/volumetric locking
- ✓ No corner locking
- ✓ No pressure checkerboarding
- ✓ No increase in DOF

Another approach
adopting **CS-FEM**
with **T10** element
would be effective.

Y. Onishi, IJMNE,
Vol. 109 (2017).