

# SelectiveCS-FEM-T10: Selective cell-based smoothed finite element methods with 10-node tetrahedral elements

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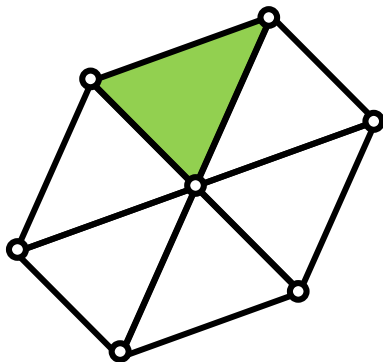
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# What is S-FEM?

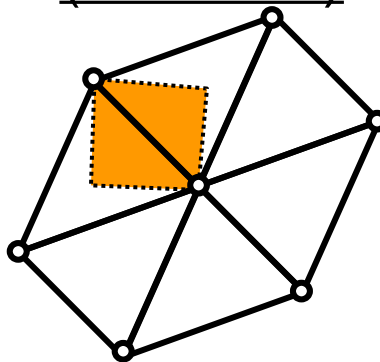
- **Smoothed** finite element method (**S-FEM**) is a relatively new FE formulation proposed by Prof. G. R. Liu in 2006.
- S-FEM is one of the **strain smoothing** techniques.
- There are several types of classical S-FEMs depending on the **domains of strain smoothing**.

**For example in 2D triangular mesh:**

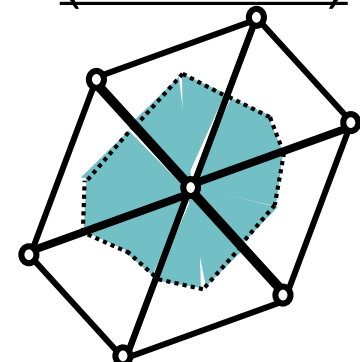
Standard FEM



Edge-based S-FEM  
(ES-FEM)

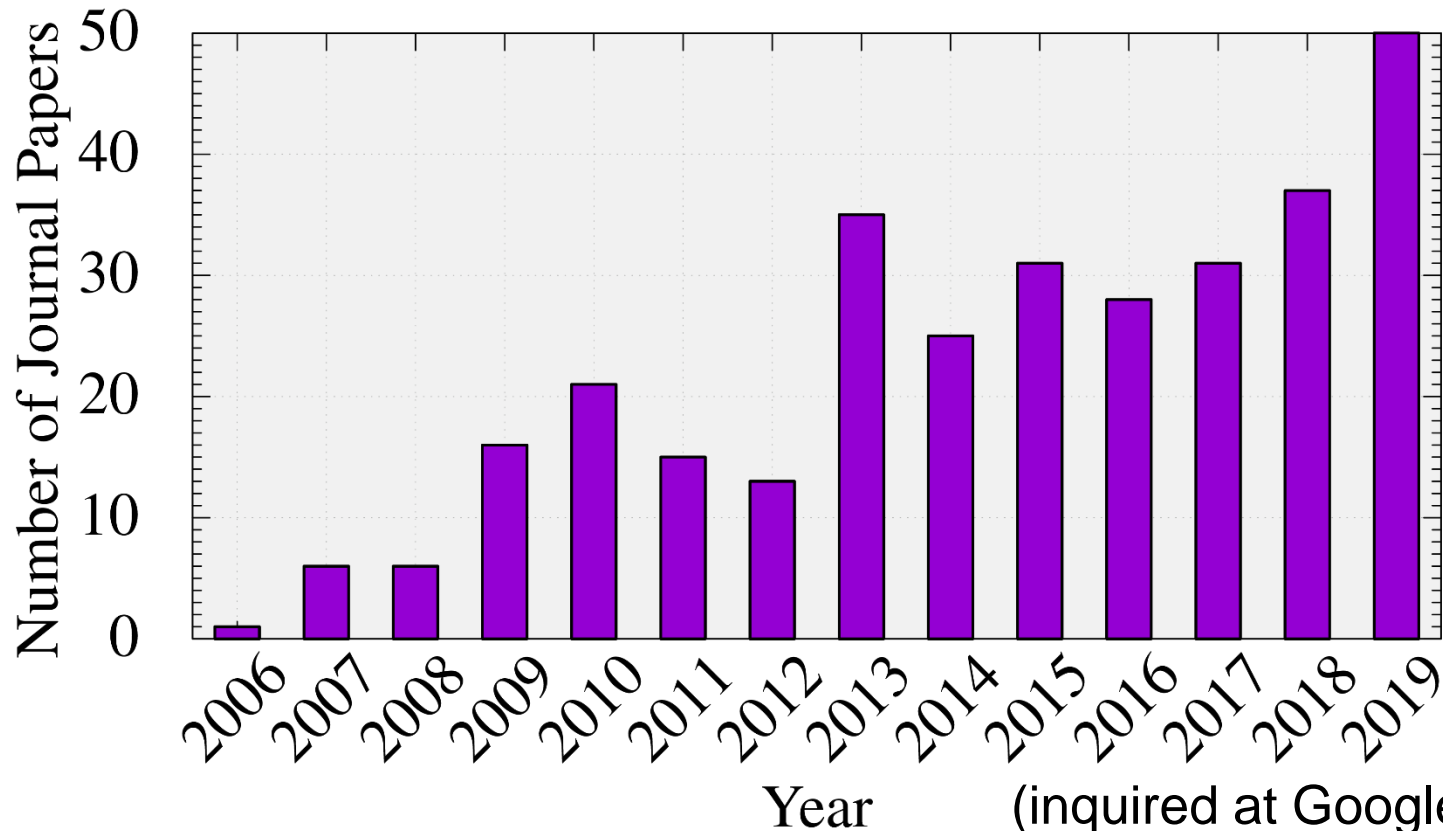


Node-based S-FEM  
(NS-FEM)



# How popular is S-FEM?

Number of journal papers written in **English** whose **title** contains “**smoothed finite element**”:



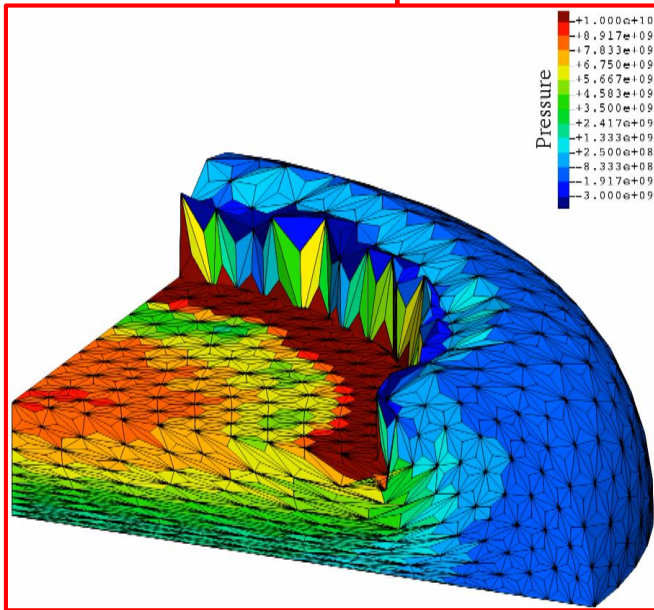
The attraction of S-FEM is expanding continuously.



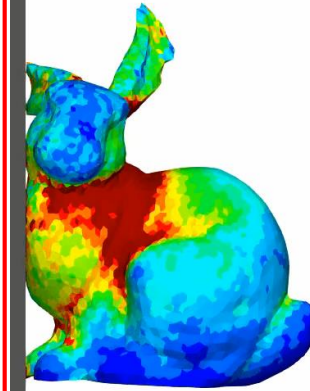
# Applications of S-FEMs in Our Lab

## ■ Solid mechanics

### Static Implicit



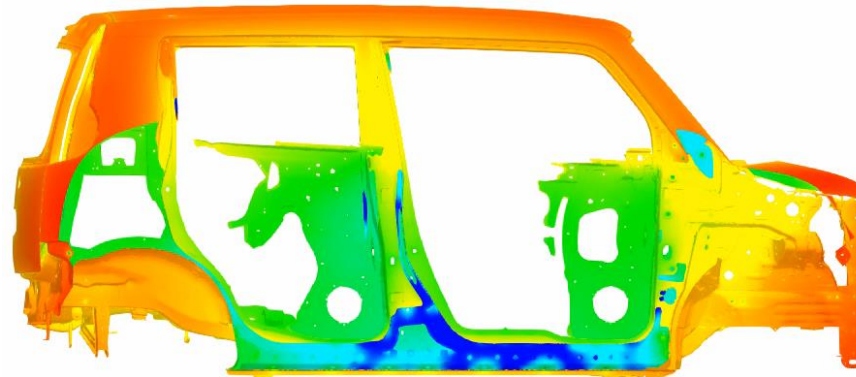
### Dynamic Explicit



### Viscous Implicit



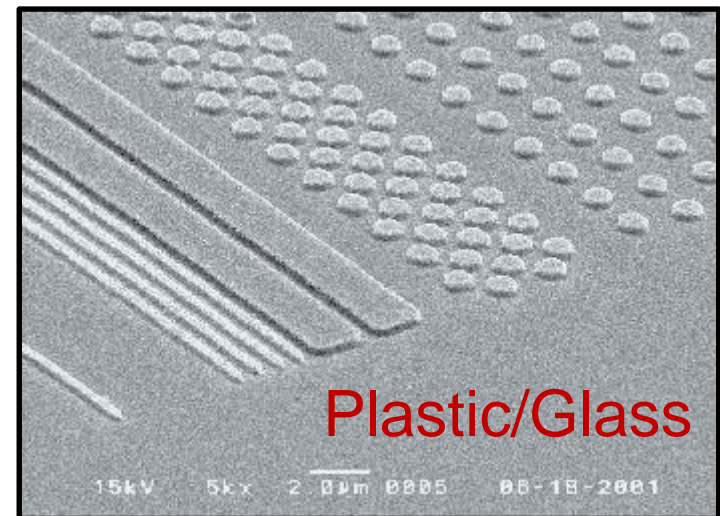
## ■ Electrostatic



# Motivation

## What we want to do:

- Solve **hyper large deformation** analyses accurately and stably.
- Treat complex geometries with **tetrahedral meshes**.
- Consider **nearly incompressible materials** ( $\nu \approx 0.5$ ).
- Support **contact** problems.
- Handle **auto re-meshing**.



# Issues

Conventional **tetrahedral (T4/T10)** FE formulations still have issues in accuracy or stability especially in **nearly incompressible** cases.

- 2<sup>nd</sup> or higher order elements:

- ✗ Volumetric locking.

- Accuracy loss in large strain due to intermediate nodes.

- B-bar method, F-bar method, Selective reduced integration:

- ✗ Not applicable to tetrahedral element directly.

- F-bar-Patch method:

- ✗ Difficulty in building good-quality patches.

- u/p mixed (hybrid) method:

- (e.g., ABAQUS/Standard **C3D4H** and **C3D10MH**)

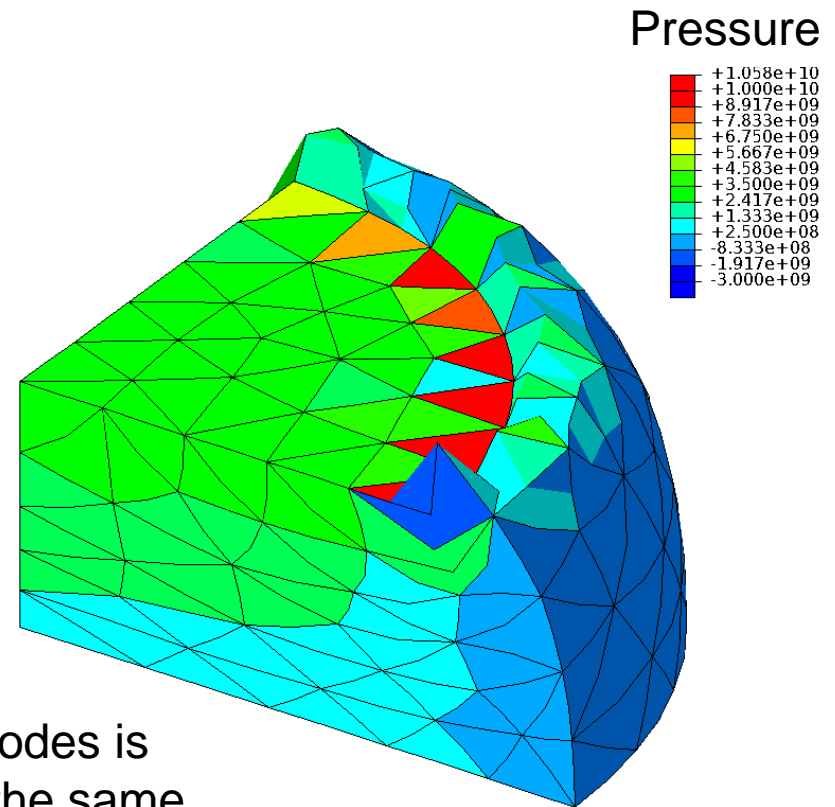
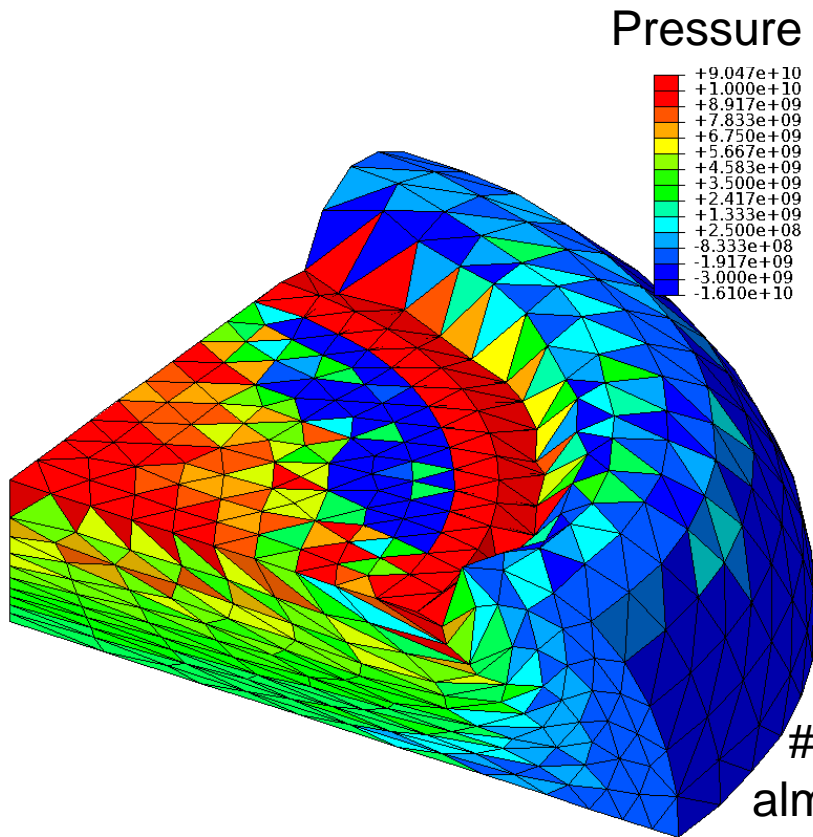
- ✗ Pressure checkerboarding, Early convergence failure etc..

- F-bar type smoothed FEM (F-barES-FEM-T4):

- ✓ Accurate & stable ✗ Hard to implement in FEM codes.

# Issues (cont.)

E.g.) Compression of neo-Hookean hyperelastic body with  $\nu_{ini} = 0.49$



# of Nodes is almost the same.

## 1<sup>st</sup> order hybrid T4 (C3D4H)

- ✓ No volumetric locking
- ✗ Pressure checkerboarding
- ✗ Shear & corner locking

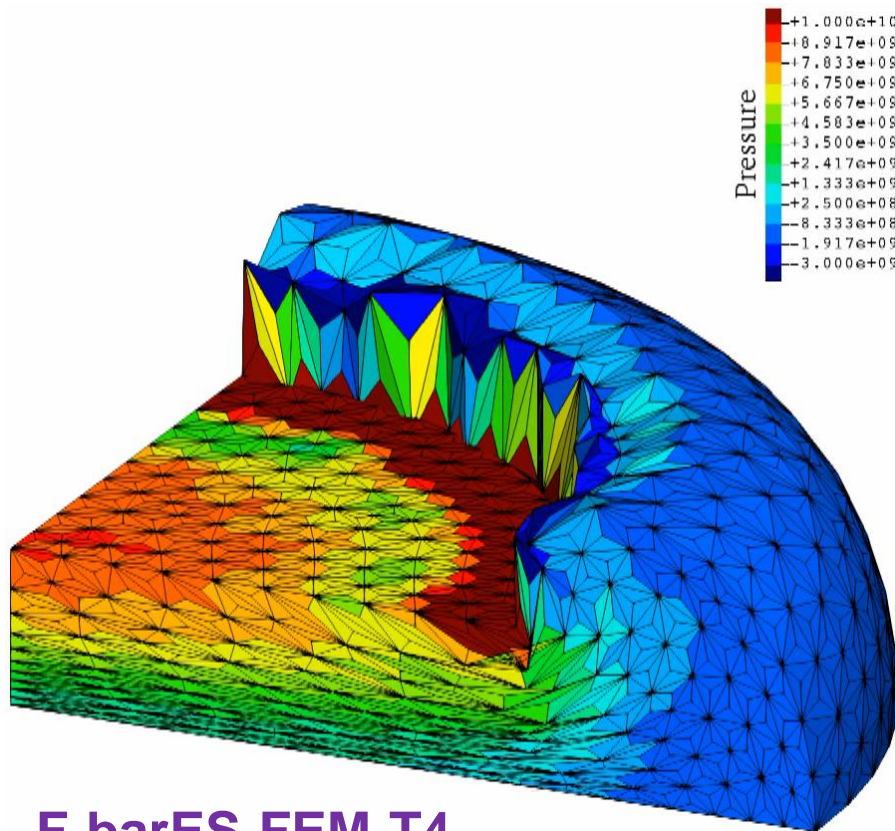
## 2<sup>nd</sup> order modified hybrid T10 (C3D10MH)

- ✓ No shear/volumetric locking
- ✗ Early convergence failure
- ✗ Low interpolation accuracy

# Issues (cont.)

E.g.) Compression of neo-Hookean hyperelastic body with  $\nu_{ini} = 0.49$

Same mesh  
as C3D4H  
case.



Although F-barES-FEM-T4 is accurate and stable, **X** it cannot be implemented in general-purpose FE software due to the adoption of ES-FEM. Also, it consumes larger memory & CPU costs.

## F-barES-FEM-T4

- ✓ No shear/volumetric locking
- ✓ No corner locking
- ✓ No pressure checkerboarding
- ✓ No increase in DOF

Another approach adopting CS-FEM with T10 element would be effective.



# Objective

To develop an S-FEM formulation using T10 mesh (SelectiveCS-FEM-T10) for severe large deformation analyses.

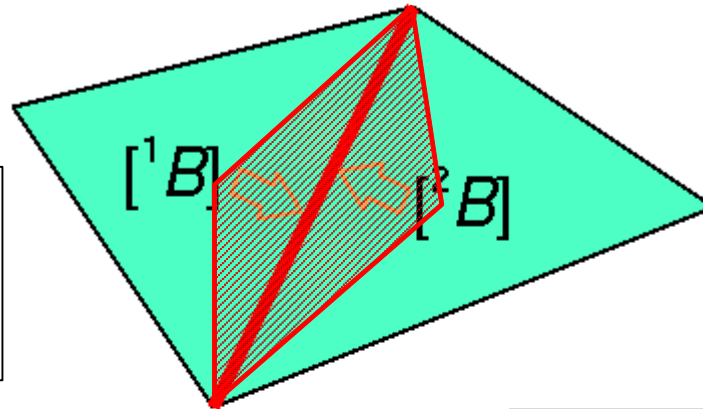
## **Table of Body Contents**

- Quick introduction of F-barES-FEM-T4
  - Why not T4 but T10? –
- Formulation of SelectiveCS-FEM-T10
- Demonstrations of SelectiveCS-FEM-T10
- Summary

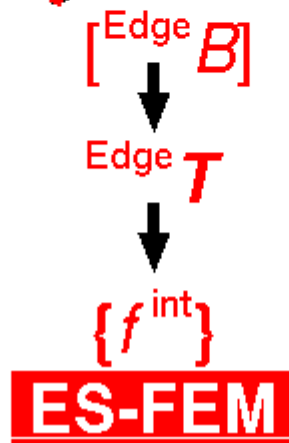
# Quick Introduction of F-barES-FEM-T4 – Why not T4 but T10? –

# Brief of Edge-based S-FEM (ES-FEM)

- Calculate  $[B]$  at each element as usual.
- Distribute  $[B]$  to the connecting edges with area weight and build  $[^{\text{Edge}}B]$ .
- Calculate  $F, T, \{f^{\text{int}}\}$  etc. in each edge smoothing domain.



As if putting  
an integration point  
on each edge center

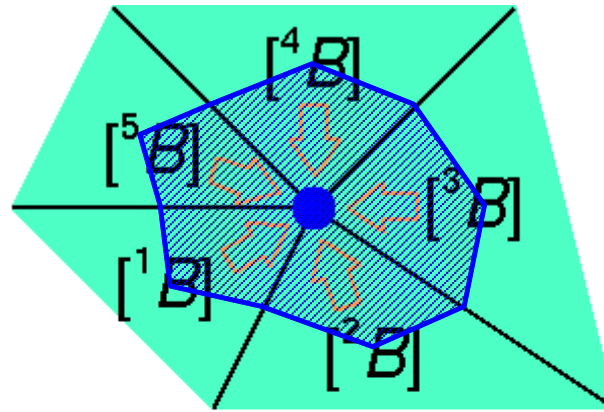


ES-FEM can avoid shear locking.  
However,  
it cannot be implemented in  
ordinary FE codes due to the  
strain smoothing across  
multiple elements...

# Brief of Node-based S-FEM (NS-FEM)

- Calculate  $[B]$  at each element as usual.
- Distribute  $[B]$  to the connecting nodes with area weight and build  $[^{\text{Node}}B]$ .
- Calculate  $F, T, \{f^{\text{int}}\}$  etc. in each node smoothing domain.

As if putting  
an integration point  
on each node



$[^{\text{Node}}B]$

Node  $T$

$\{f^{\text{int}}\}$

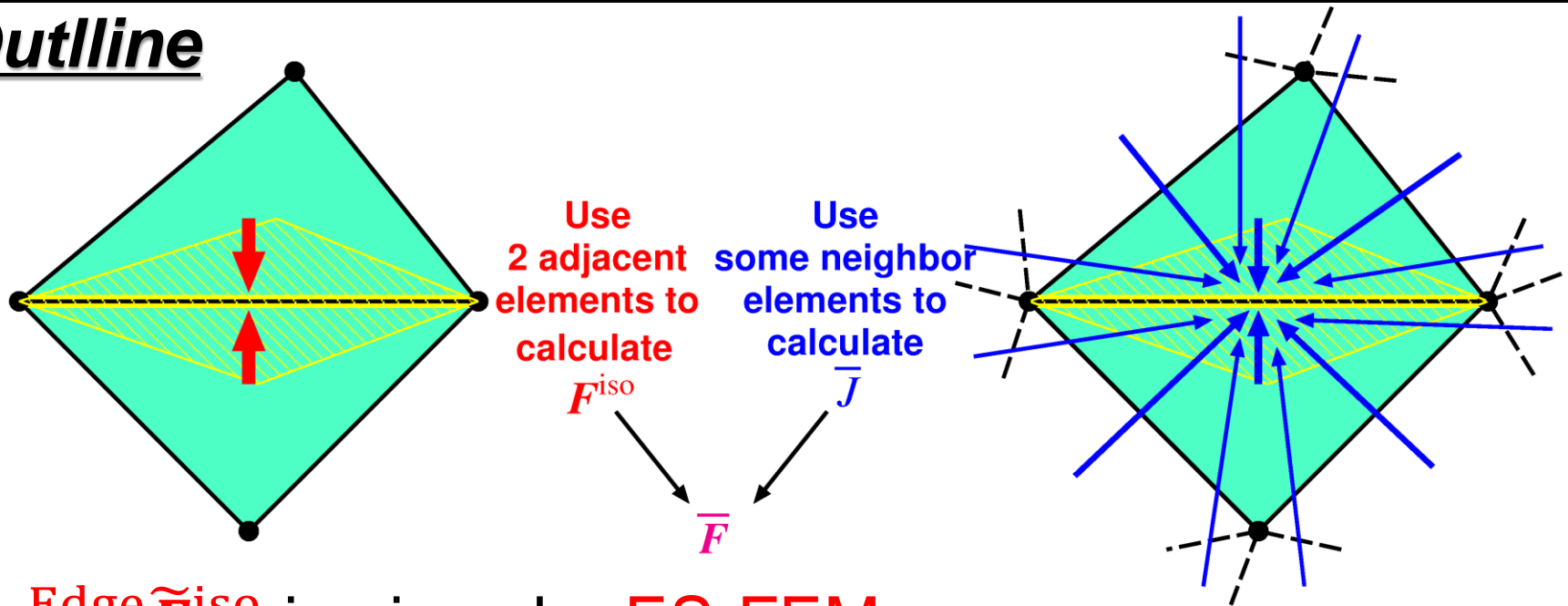
**NS-FEM**

- ✗ Spurious low-energy mode (or hour-glass mode)
- ✓ Less pressure checkerboarding
- ✓ No shear locking
- ✓ No volumetric locking

# Concept of F-barES-FEM

Concept: combining **ES-FEM** and **NS-FEM** using **F-bar** method

## Outline



- Edge  $\tilde{F}^{\text{iso}}$  is given by **ES-FEM**.
- Edge  $\bar{J}$  is given by **cyclically applied NS-FEM**.
- Edge  $\bar{F}$  is calculated in the manner of **F-bar** method:

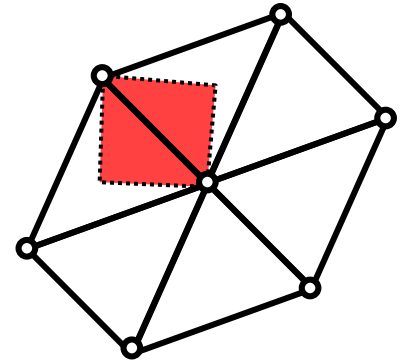
$$\text{Edge } \bar{F} = \text{Edge } \bar{J}^{1/3} \text{ Edge } \tilde{F}^{\text{iso}} .$$

# Formulation of F-barES-FEM (1 of 2)

Deformation gradient of **each edge** ( $\bar{\mathbf{F}}$ ) is derived as

$$\bar{\mathbf{F}} = \tilde{\mathbf{F}}^{\text{iso}} \cdot \bar{\mathbf{F}}^{\text{vol}}$$

in the manner of F-bar method.



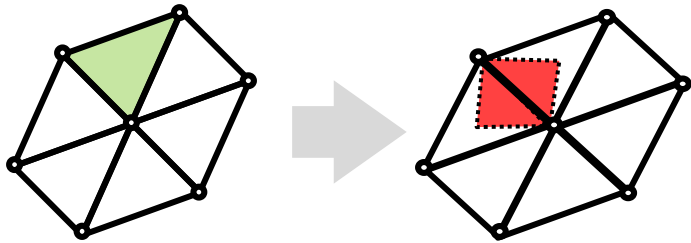
ES-FEM

# Formulation of F-barES-FEM (2 of 2)

Each part of  $\bar{F}$  is calculated as

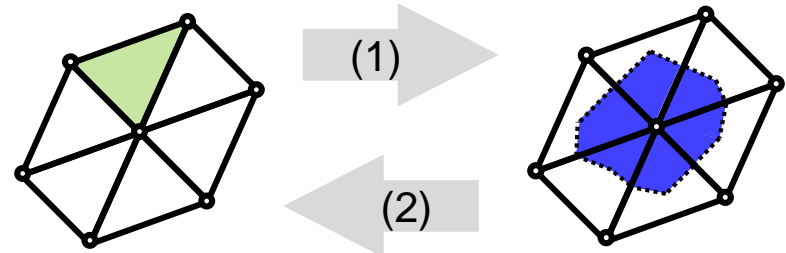
$$\bar{F} = \tilde{F}^{\text{iso}} \cdot \bar{F}^{\text{vol}}$$

## Isovolumetric part



Smoothing the value of adjacent elements.  
(same manner as ES-FEM)

## Volumetric part



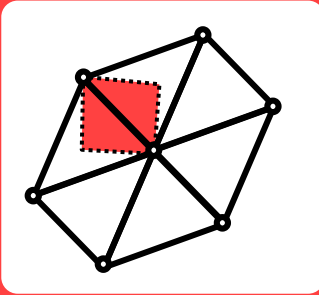
- (1) Calculating node's value by smoothing the value of adjacent elements
- (2) Calculating elements' value by smoothing the value of adjacent nodes
- (3) Repeating (1) and (2) a few times

# Advantages of F-bar ES-FEM

This formulation is designed to have 3 advantages.

$$\bar{\mathbf{F}} = \tilde{\mathbf{F}}^{\text{iso}} \cdot \bar{\mathbf{F}}^{\text{vol}}$$

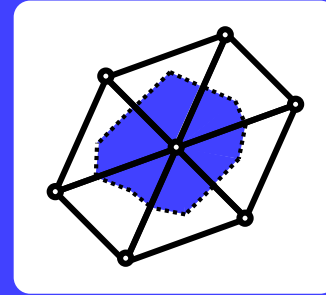
Isovolumetric part



Like a ES-FEM

1. Shear locking free

Volumetric part



Like a NS-FEM

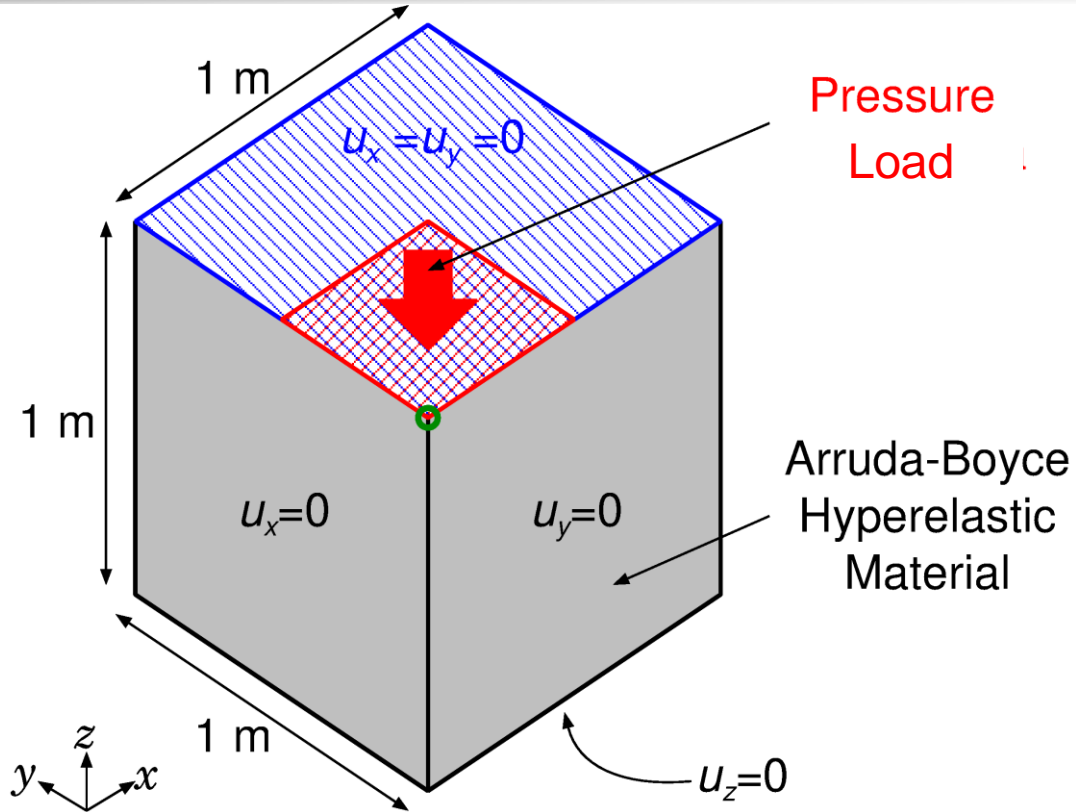
2. Little pressure oscillation

3. Volumetric locking free  
with the aid of F-bar method



# Compression of Rubber Block

## Outline

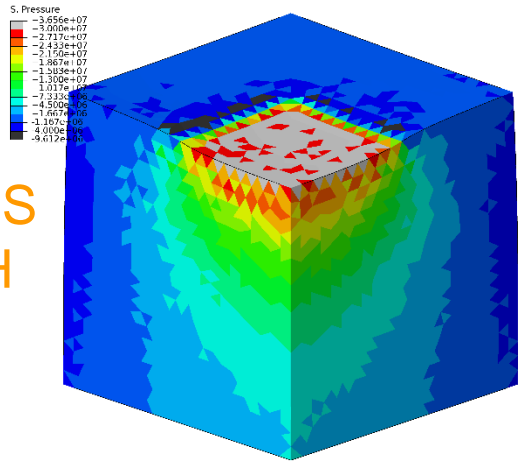


- Arruda-Boyce hyperelastic material ( $\nu_{ini} = 0.499$ ).
- Applying pressure on  $\frac{1}{4}$  of the top face.
- Result of F-barES-FEM-T4 is compared to ABAQUS C3D4H with the same unstructured T4 mesh.

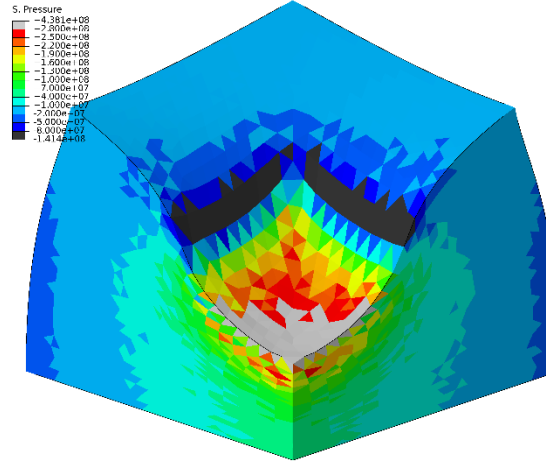
# Static Implicit Compression of *Rubber* Block

## Pressure dist.

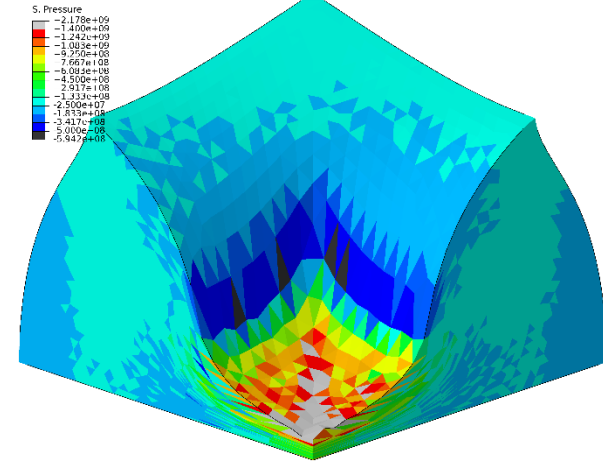
Early stage



Middle stage

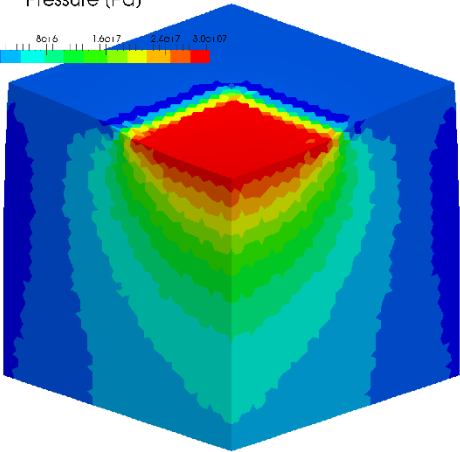


Later stage



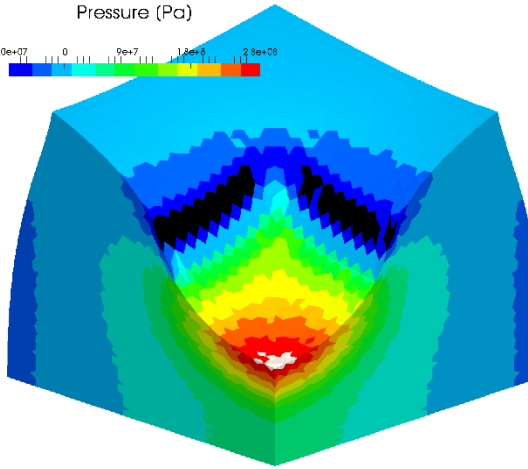
Pressure (Pa)

4.0e+06 0 8.0e+6 1.6e+07 2.4e+07 3.0e+07



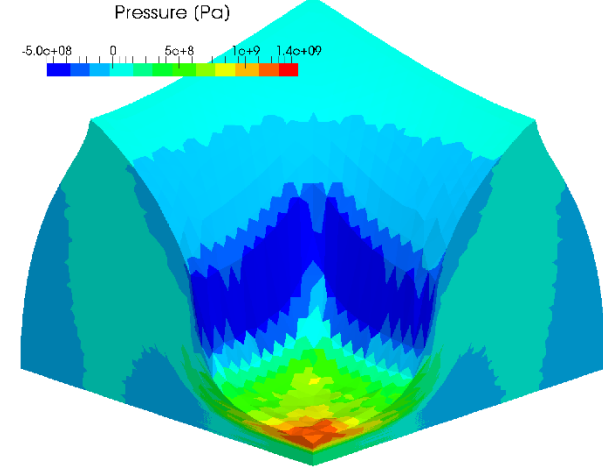
Pressure (Pa)

-8.0e+07 0 0e+7 1.0e+8 2.0e+8



Pressure (Pa)

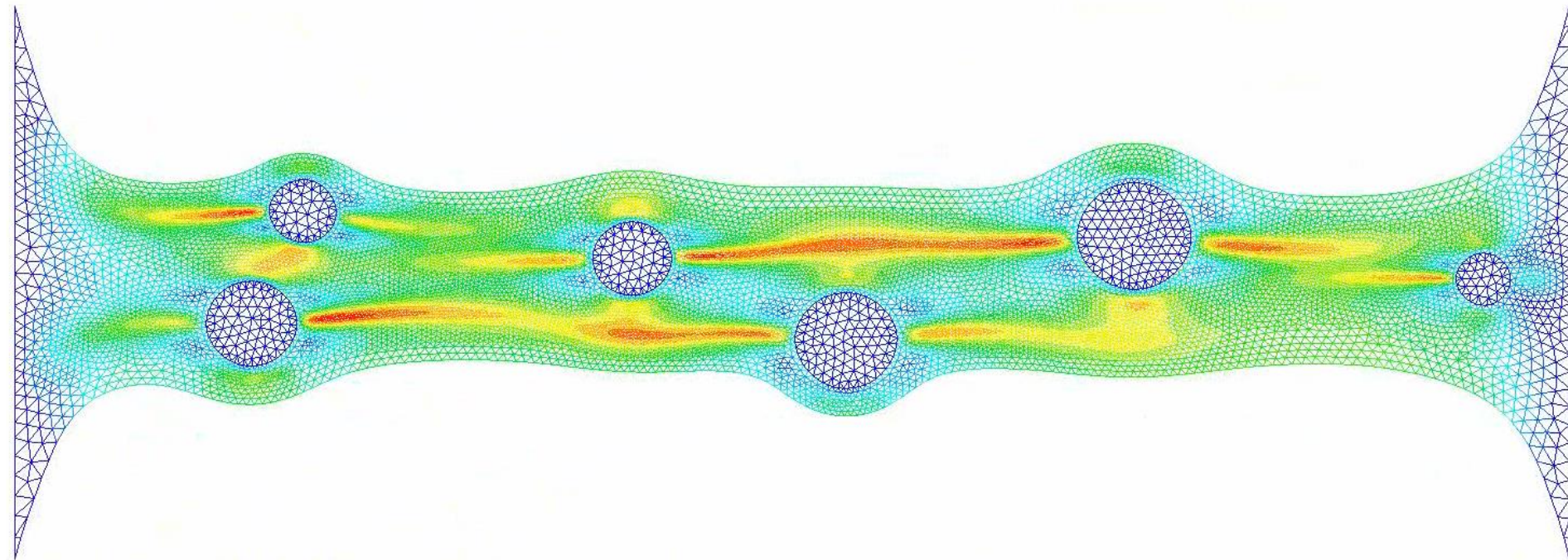
-5.0e+08 0 5e+8 1e+9 1.4e+09



Smooth pressure distributions are obtained.

# Stretch of Filler-containing Rubber with 2D Remesing

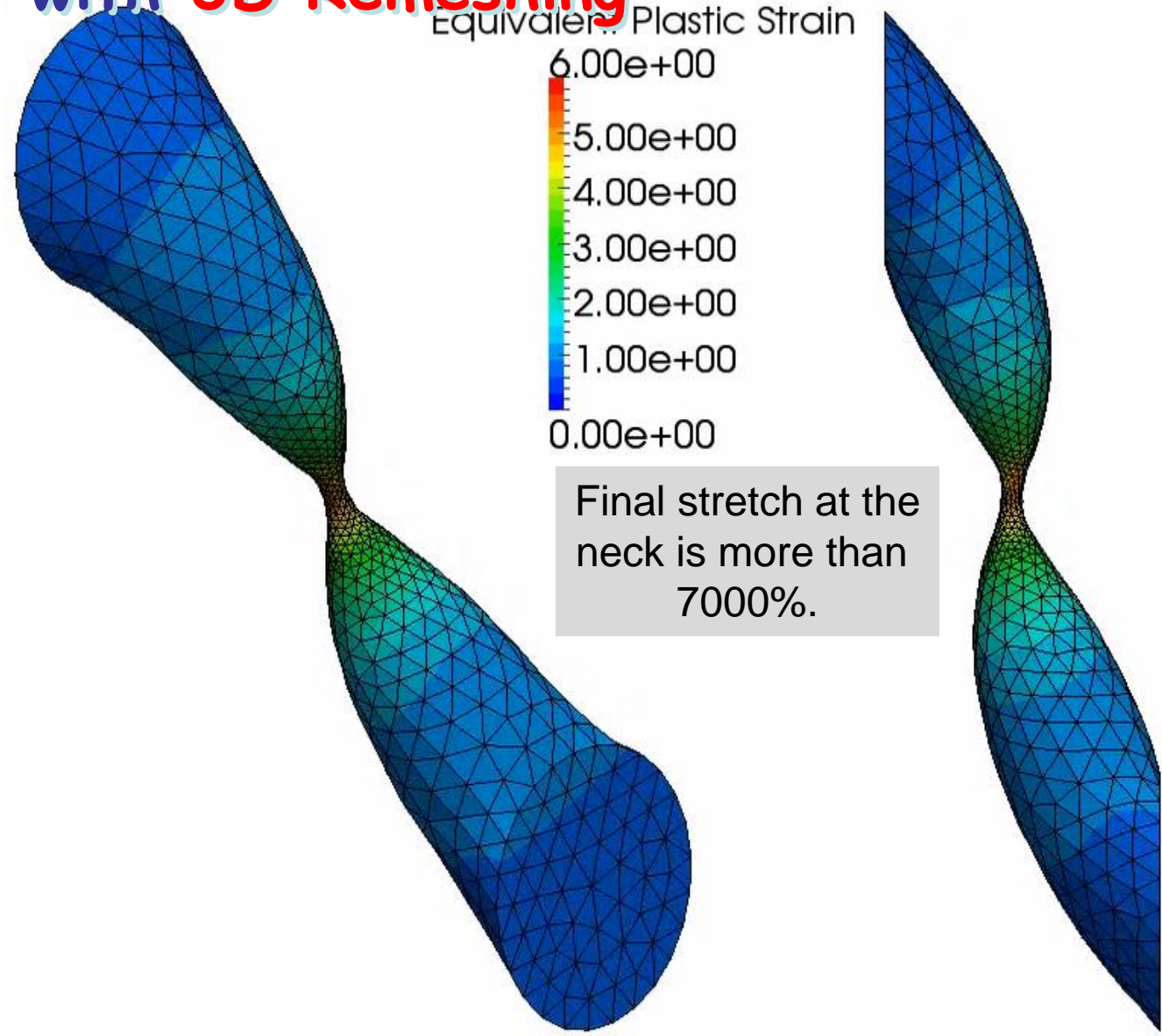
- Several hard circular fillers are distributed in a square soft matrix rubber (neo-Hookean hyperelastic with  $\nu_{ini} = 0.49$ ).
- $E_{ini}$  of the filler is **100 times larger** than  $E_{ini}$  of the matrix.
- Left side is constrained and right side is displaced.



Valid Mises stress dist. is obtained after many time remeshings.

# Shear-tensioning of Elasto-plastic cylinder with 3D Remeshing

- Aluminium cylinder subjected to enforced disp..
- Pure shear at the initial stage, but stretch dominates at the later stage.
- Necking occurs in the end.



Valid plastic strain dist. is obtained after many time remeshings.

# Characteristics of F-barES-FEM-T4

- ✓ No increase in DOF.  
(No Lagrange multiplier. No static condensation.)
- ✓ Locking- & checkerboarding-free with T4 mesh.
- ✗ Higher costs in memory and CPU time due to wider bandwidth of  $[K]$ .

In case of standard unstructured T4 meshes:

Method	Approx. Bandwidth
Standard FEM-T4	40
F-barES-FEM-T4(1)	390

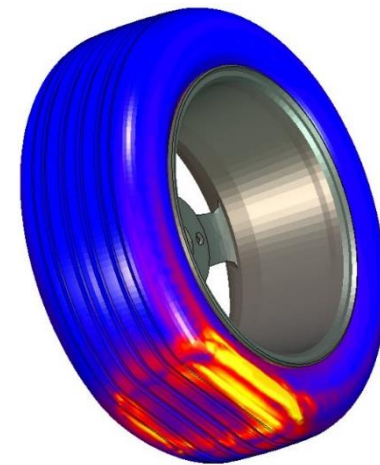
- ✗ Difficulty in implementation to existing FE codes due to the smoothing across elements. **Critical Issue!!**

# Why Not T4 But T10?

If we cannot implement F-barES-FEM-T4 to existing FE codes, then we have to code **everything** in our in-house code for practical use.

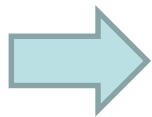
## For example in tire analyses:

- Material constitutive models,
- Structural elements,
- Cohesive elements,
- Contact functionality and so on.



MSC Software  
web page

Therefore, choosing S-FEM-T4 leads us to the long and winding road...

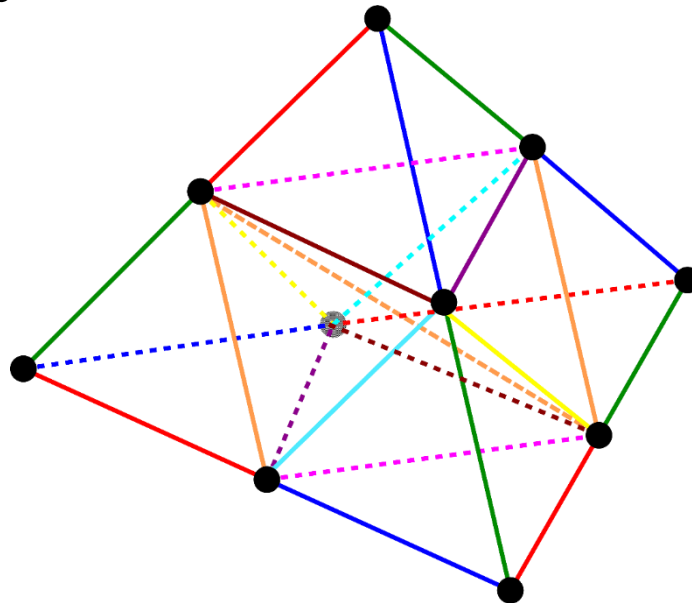


We gave up T4 and chose T10 for solid mechanics analyses.

# Formulation of SelectiveCS-FEM-T10

# Concept of SelectiveCS-FEM-T10

- Our new approach using T10 mesh.
- Adopting CS-FEM having no smoothing across multiple elements, SelectiveCS-FEM-T10 becomes an independent finite element.  
⇒ We can implement it as an element of existing FE code.
- Same memory & CPU costs as the T10 elements.

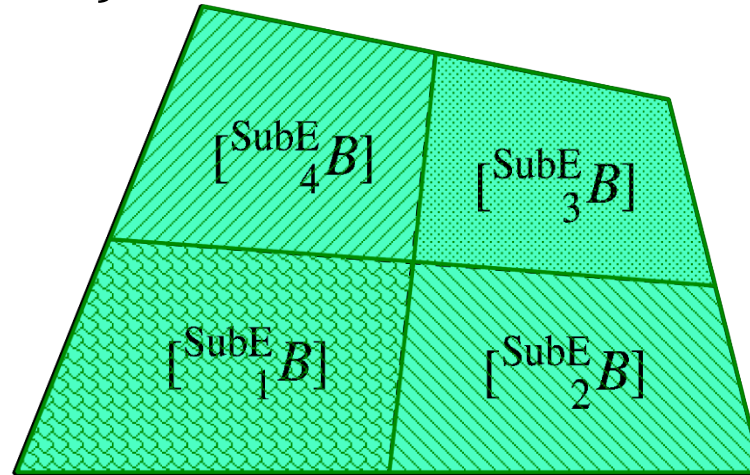




# Brief of Cell-based S-FEM (CS-FEM)

- Subdivide each element into some **sub-element**.
- Calculate  $[{}^{\text{SubE}}B]$  at each sub-element.
- Calculate  $F, T, \{f^{\text{int}}\}$  etc. in each sub-element.

As if putting  
an integration point  
on each sub-element



$$[{}^{\text{SubCell}}_i B]$$



$$\text{SubCell } T_i$$



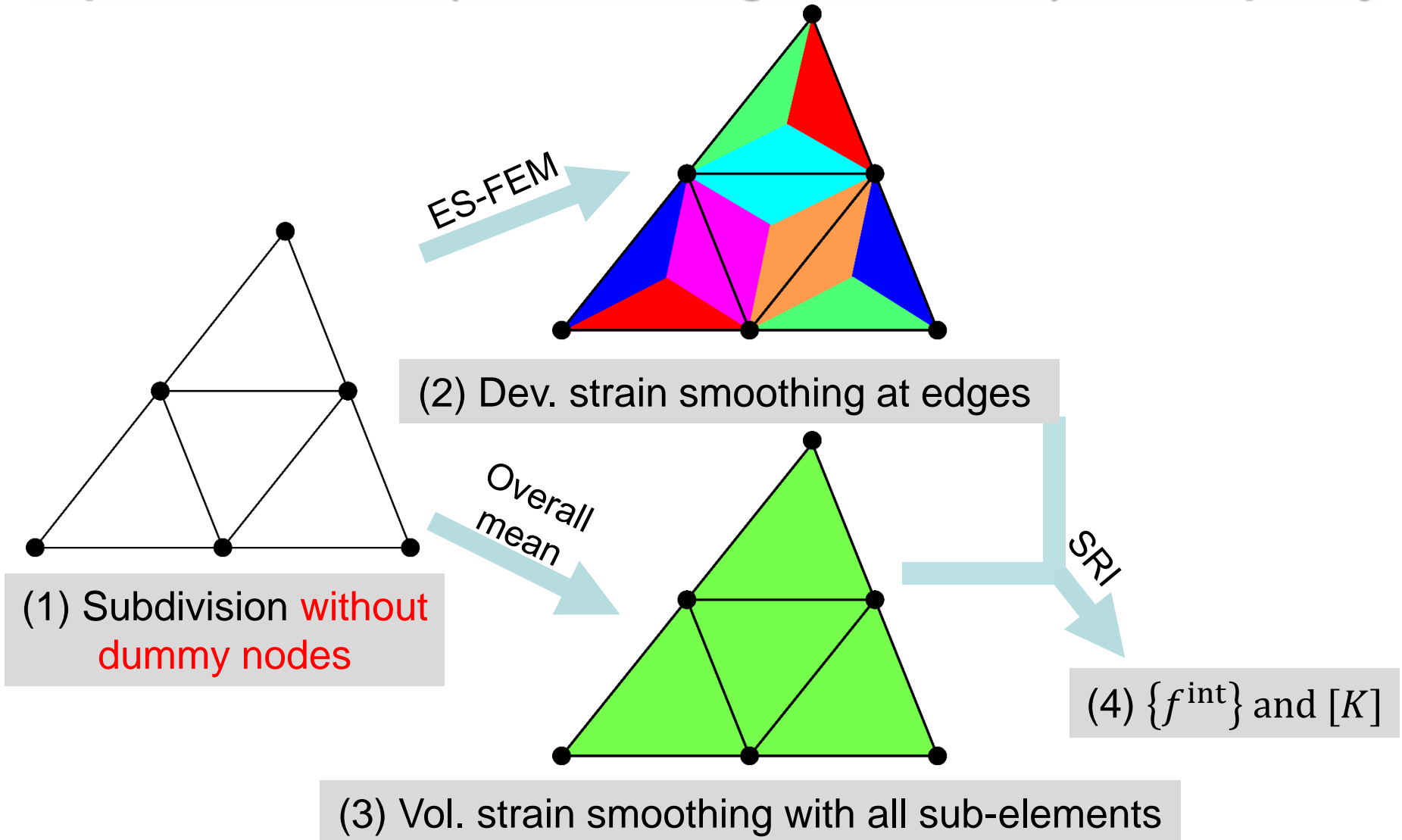
$$\{f^{\text{int}}\}$$

**CS-FEM**

- Implementable as an independent finite element.
- Locking can be avoided with SRI etc..

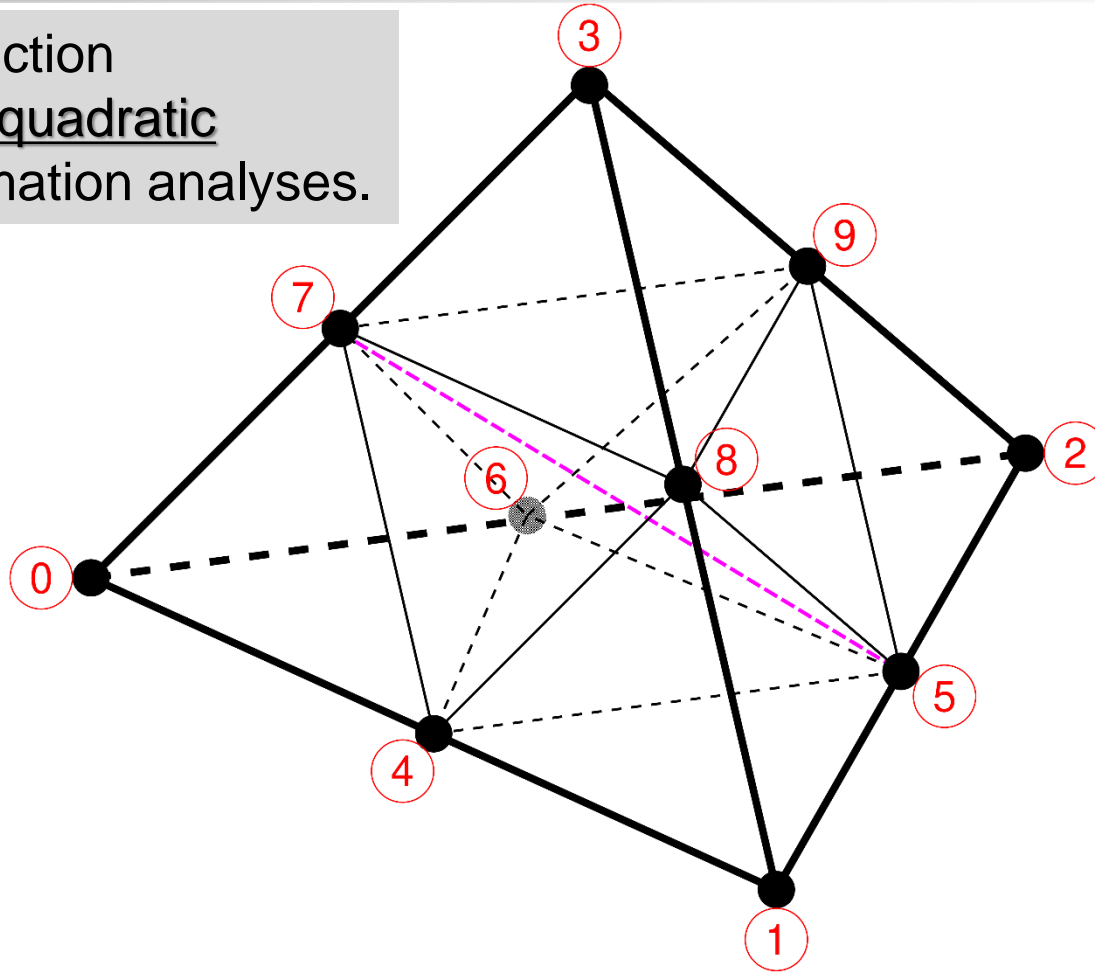
# Flowchart of **SelectiveCS-FEM-T10**

Explanation in 2D (6-node triangular element) for simplicity



# (1) Subdivision into T4 Sub-elements

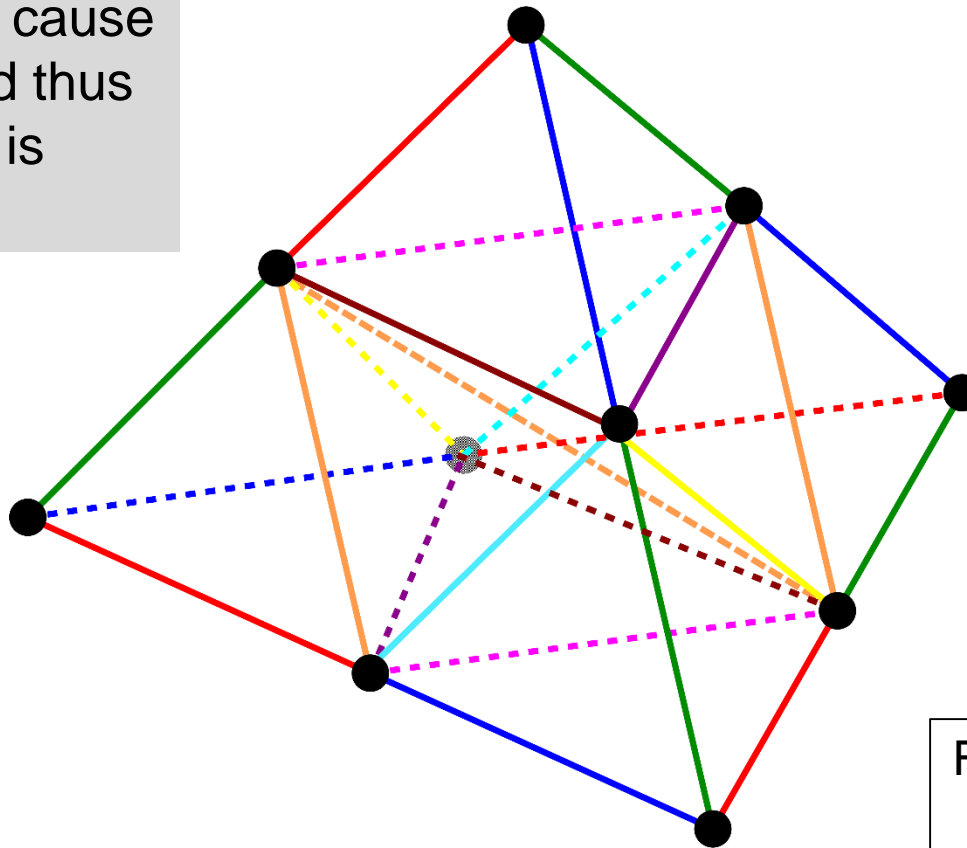
The shape function should not be quadratic in large deformation analyses.



- Introduce **no dummy node** (i.e., asymmetric element).
- Subdivide a T10 element into eight T4 sub-elements and calculate their  $B$ -matrices and strains.

# (2) Deviatoric Strain Smoothing

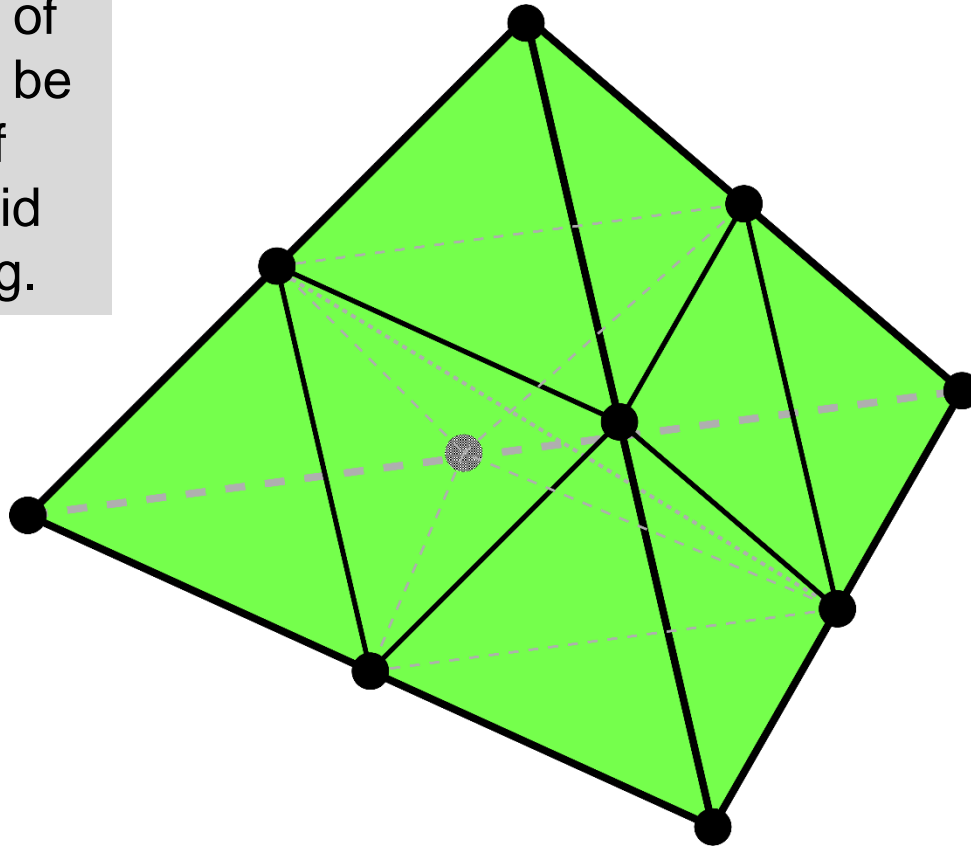
T4 sub-elements cause shear locking and thus strain smoothing is necessary.



- Perform strain smoothing in the manner of **ES-FEM** (i.e., average dev. strains of sub-elements at edges).
- Evaluate deviatoric strain and stress at edges.

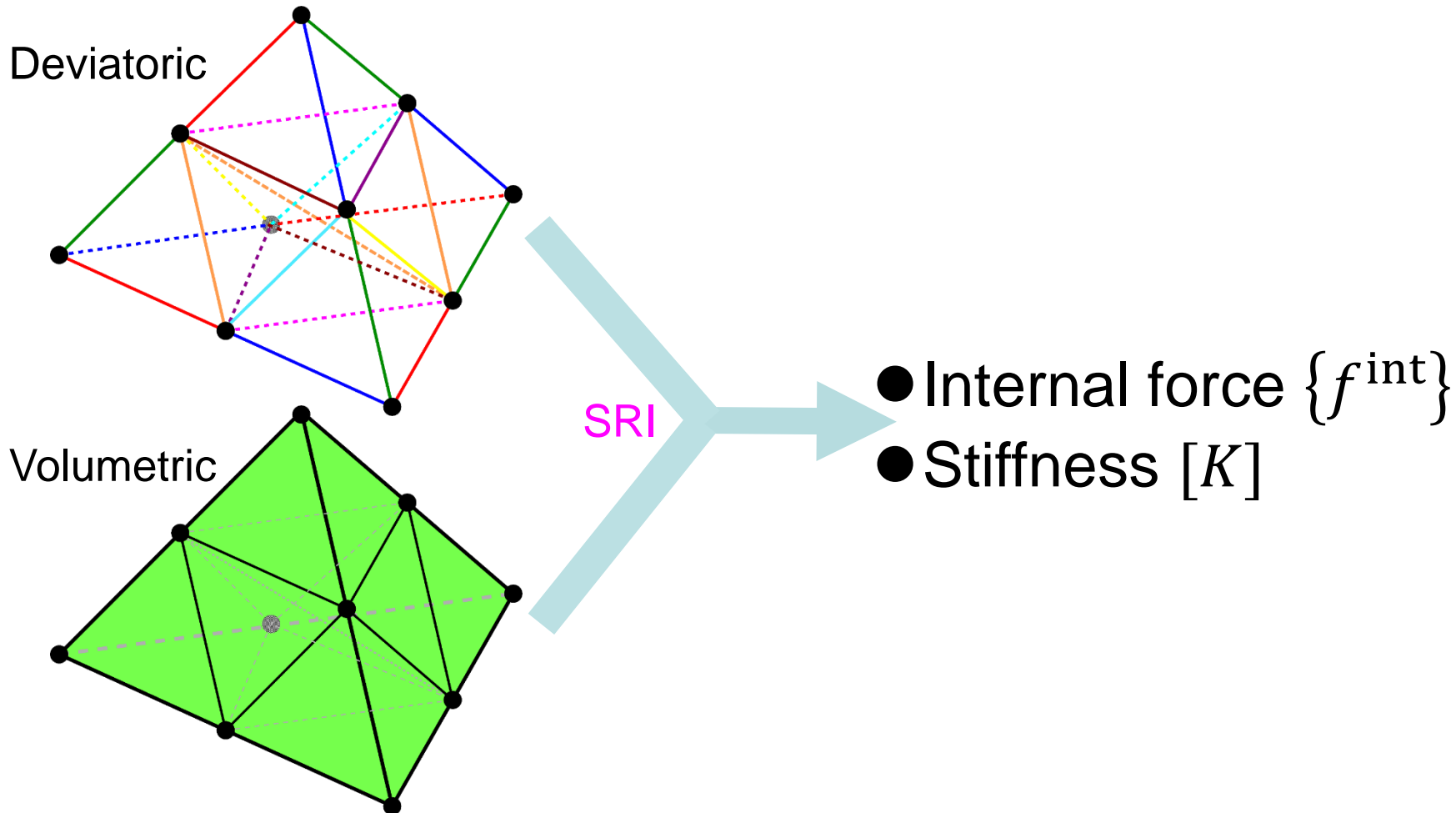
# (3) Volumetric Strain Smoothing

The spatial order of vol. strain should be lower than that of dev. strain to avoid volumetric locking.



- Treat the **overall mean** vol. strain of all sub-elements as the uniform element vol. strain (i.e., same approach as SRI elements).

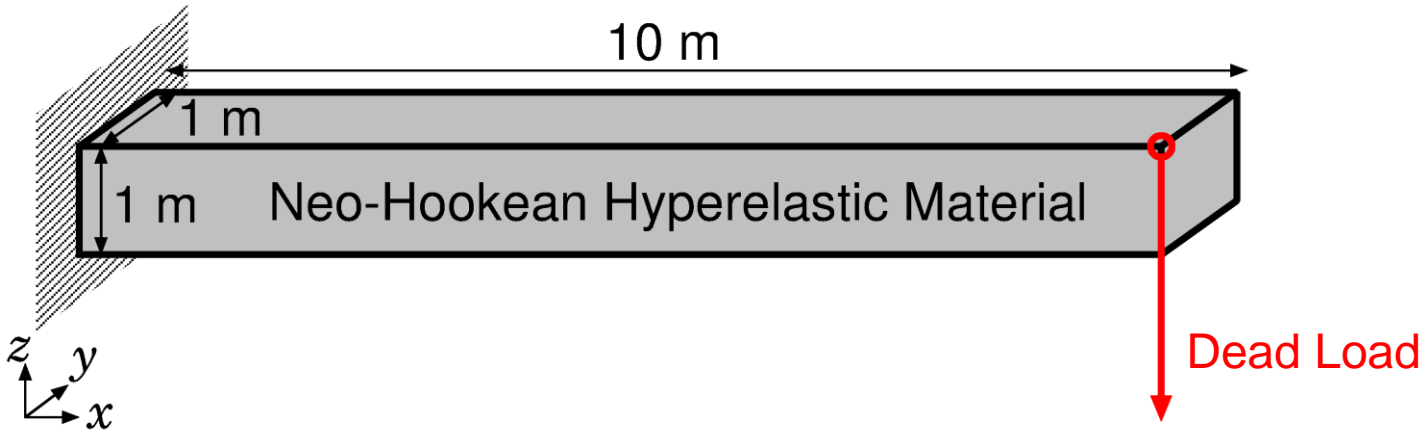
# (4) Combining with SRI Method



- Apply SRI method to combine the Dev. & Vol. parts and obtain  $\{f^{\text{int}}\}$  and  $[K]$ .

# Demonstration of SelectiveCS-FEM-T10

## Outline

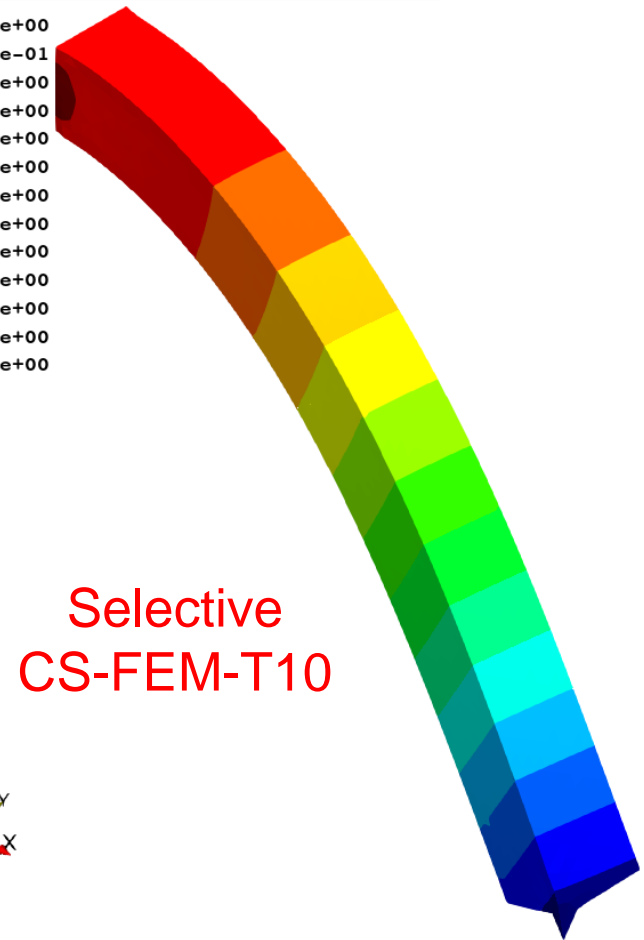
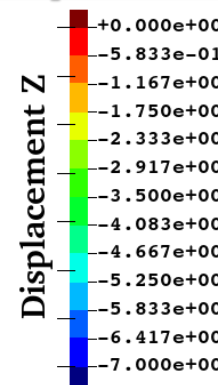
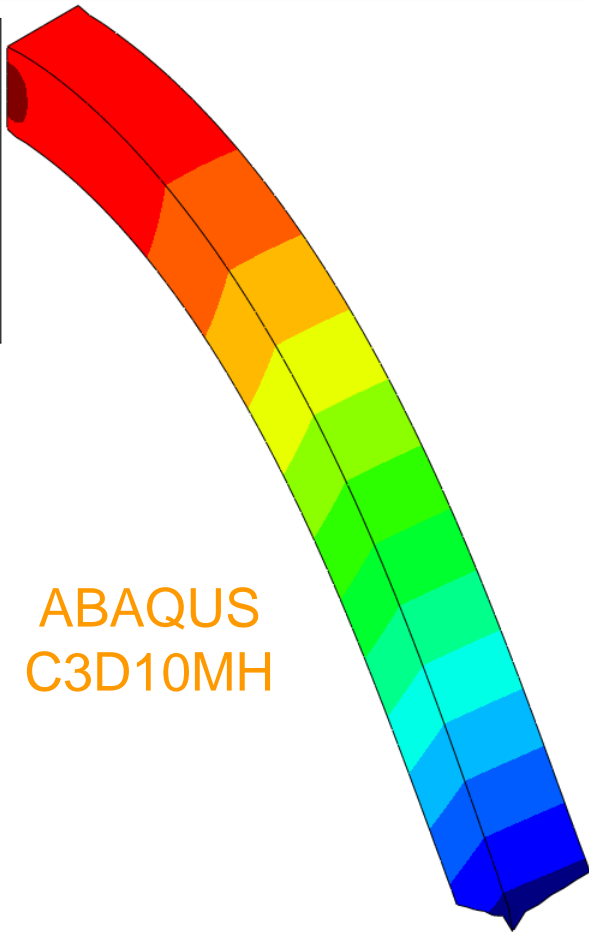
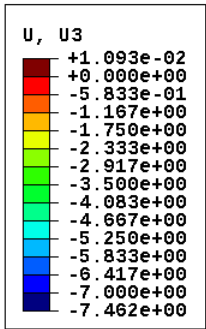


- Neo-Hookean hyperelastic material
- Initial Poisson's ratio:  $\nu_0 = 0.49$
- Compared to **ABAQUS C3D10MH** (modified hybrid T10 element) with the same mesh.



# Bending of Hyperelastic Cantilever

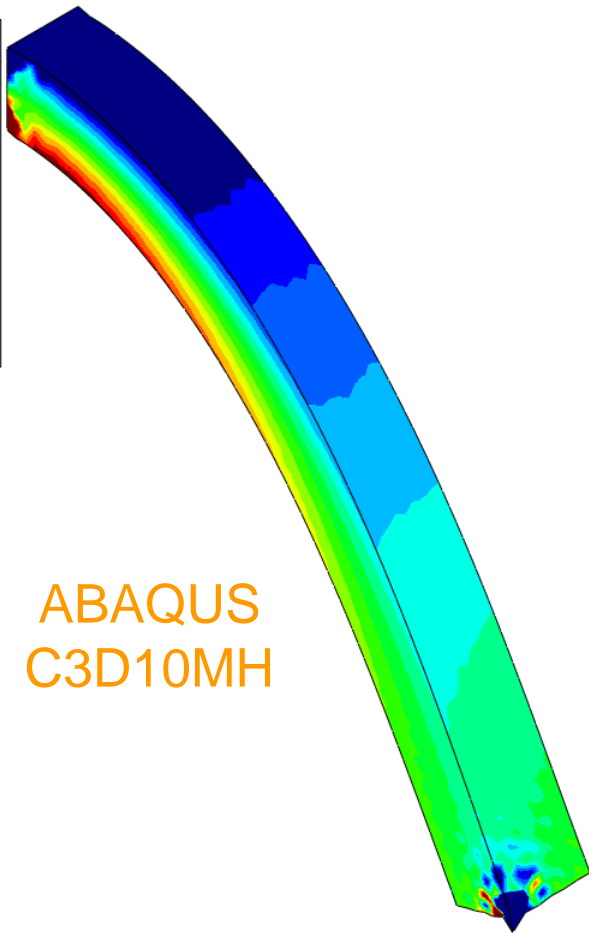
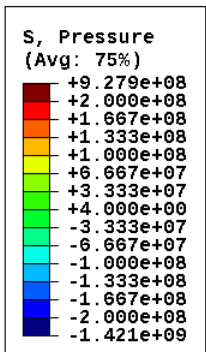
## Comparison of the deflection disp. at the final state



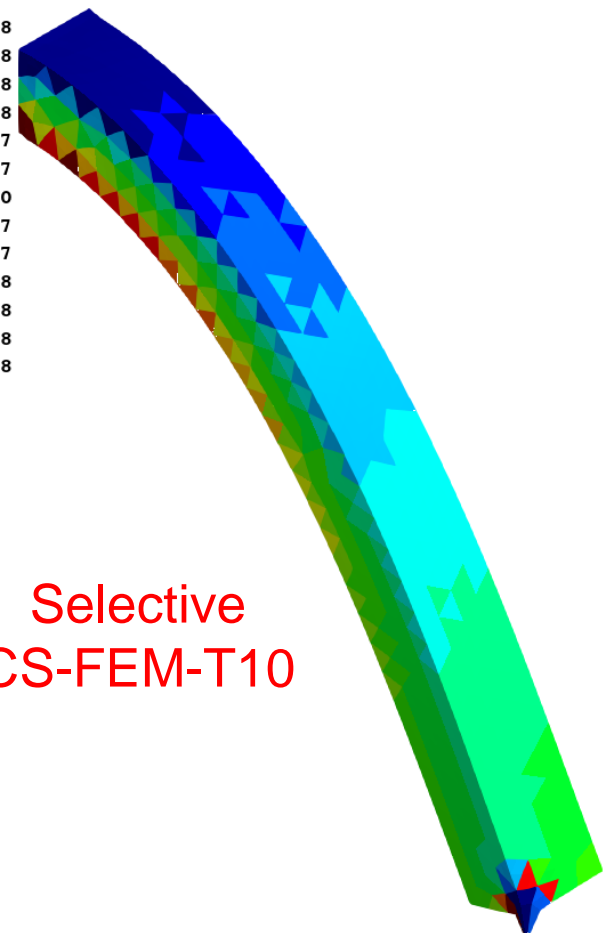
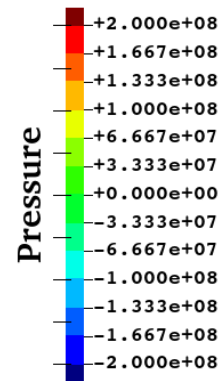
No volumetric locking is observed.

# Bending of Hyperelastic Cantilever

## Comparison of the pressure dist. at the final state



ABAQUS  
C3D10MH

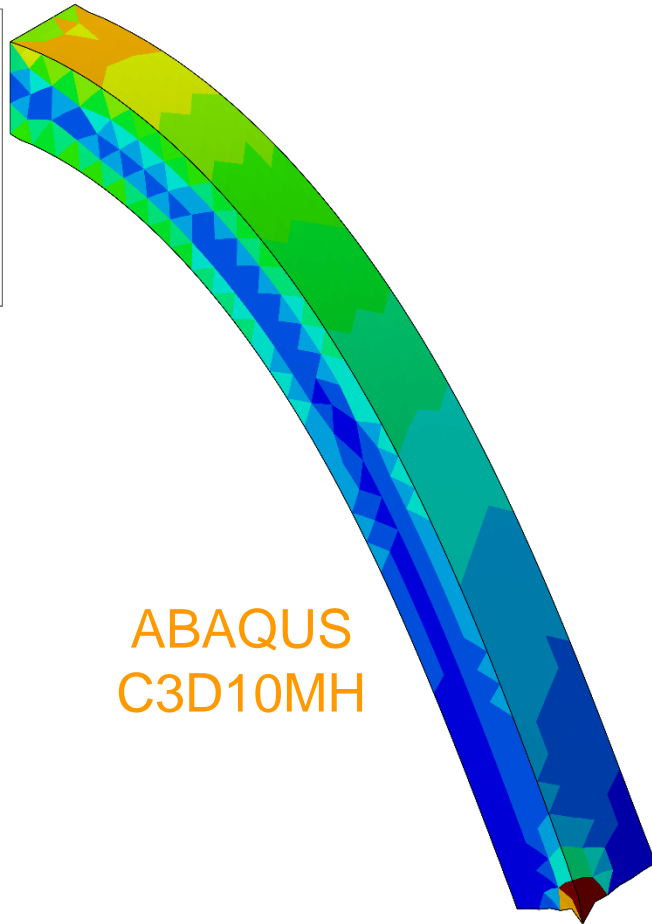
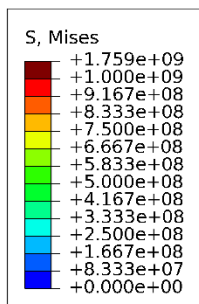


Selective  
CS-FEM-T10

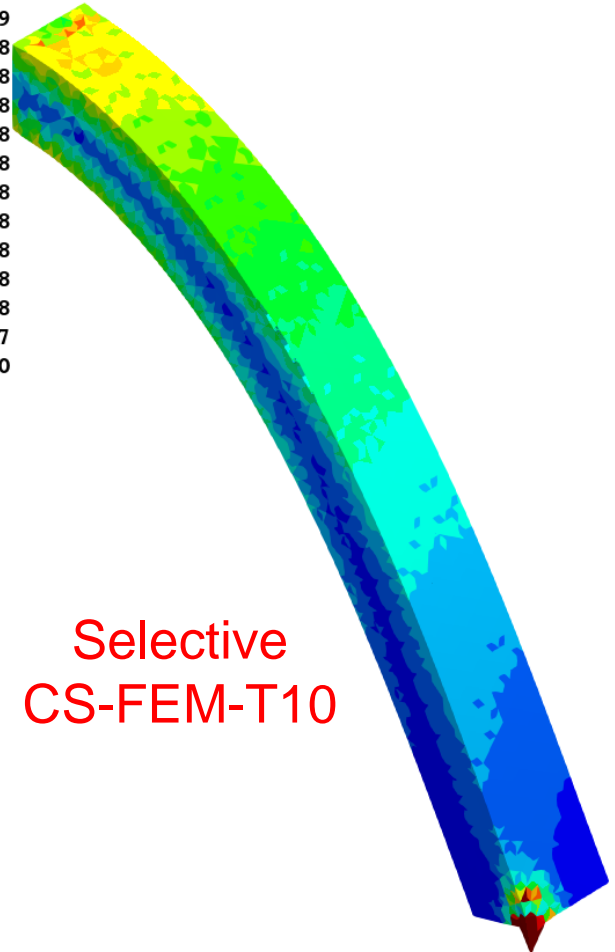
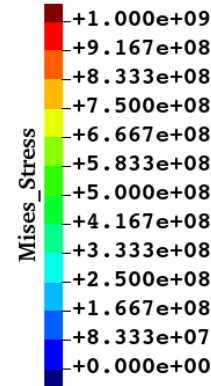
Almost the same pressure distributions with no checkerboarding.

# Bending of Hyperelastic Cantilever

## Comparison of the Mises stress dist. at the final state



ABAQUS  
C3D10MH

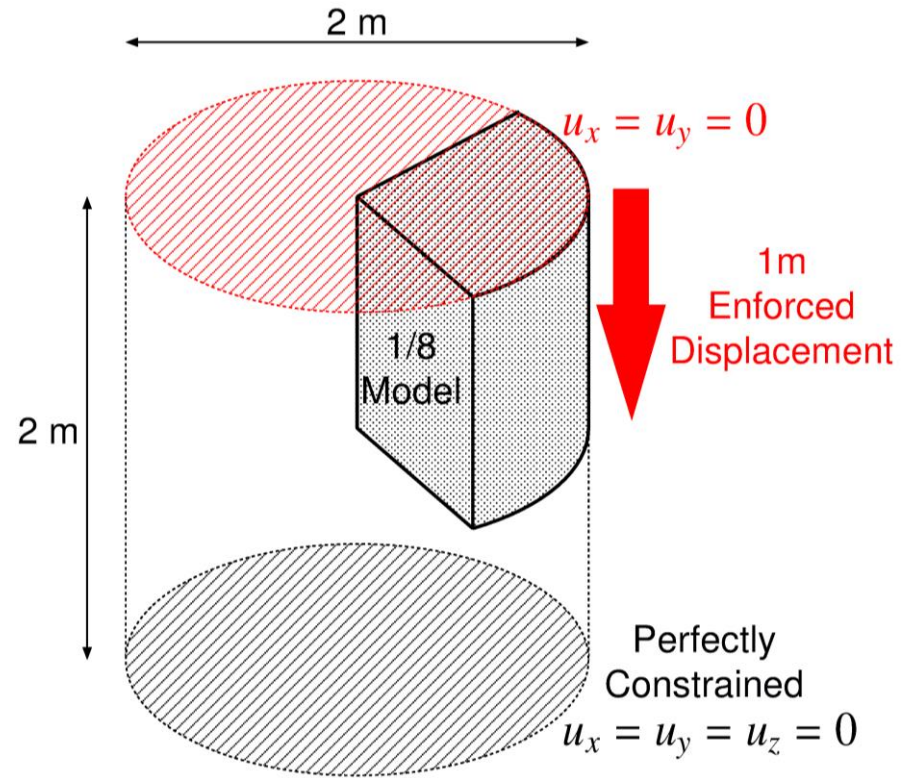


Selective  
CS-FEM-T10



Almost the same Mises stress distributions.

**Outline**



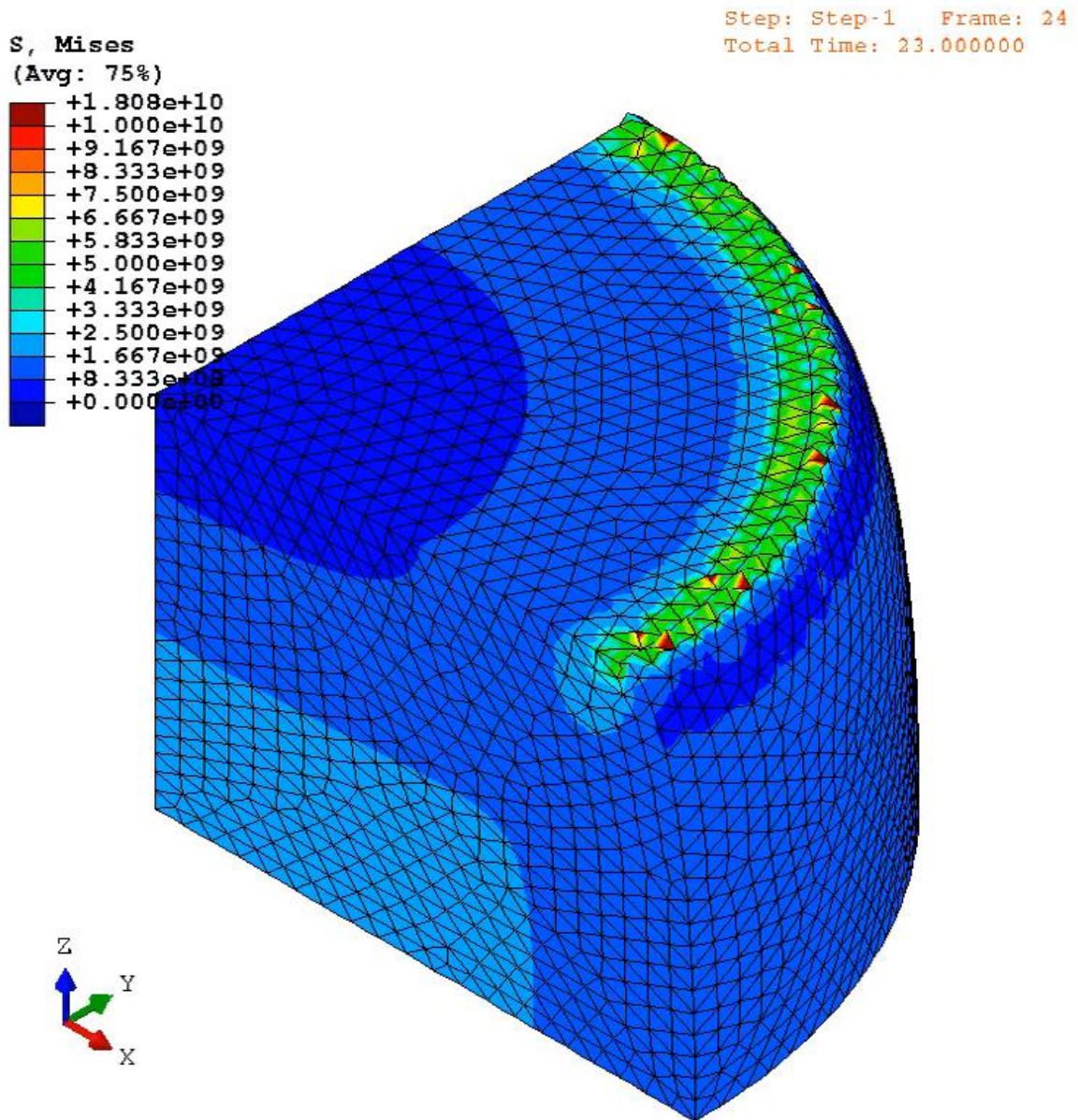
- Enforce **axial displacement** on the top face.
- Neo-Hookean body with  $\nu_{ini} = 0.49$ .
- Compare results with ABAQUS T10 hybrid elements (C3D10H, C3D10MH, C3D10HS) using the same mesh.

# Static Implicit Barreling of Hyperelastic Cylinder

## Animation of Mises stress (ABAQUS C3D10MH)

Convergence failure at **24%** compression

Unnaturally oscillating distributions are obtained around the rim.

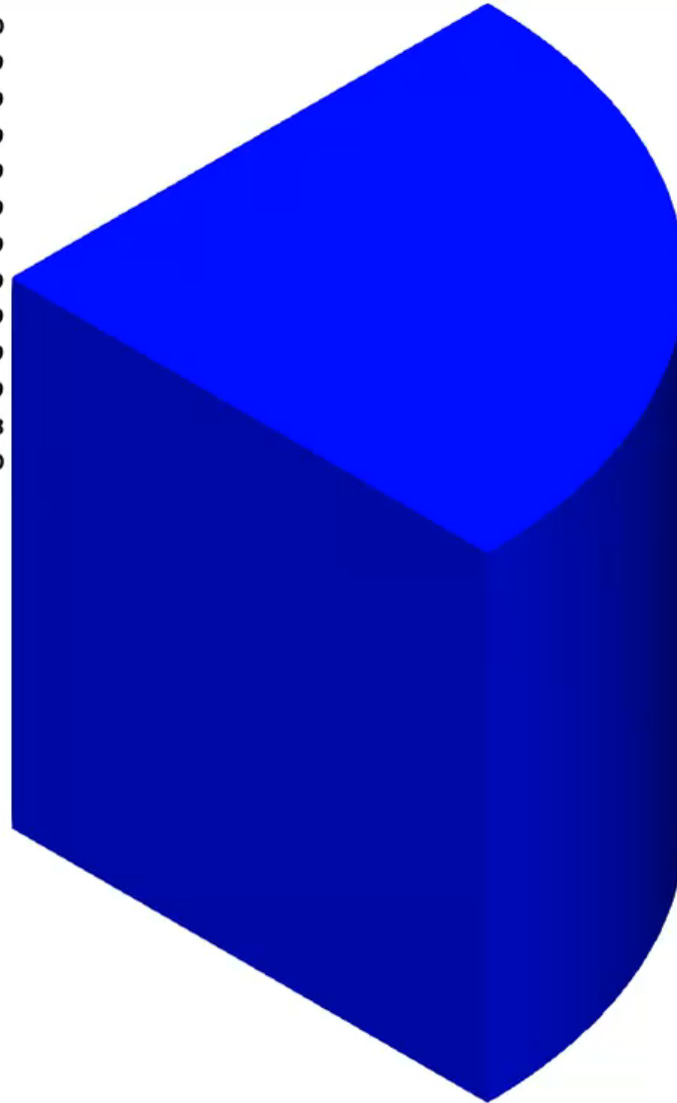
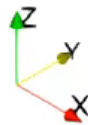
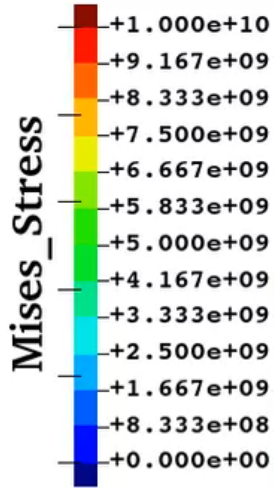


# Static Implicit **Barreling of Hyperelastic Cylinder**

## Animation of Mises stress (*Selective* *CS-FEM-T10*)

Convergence failure at **43%** compression

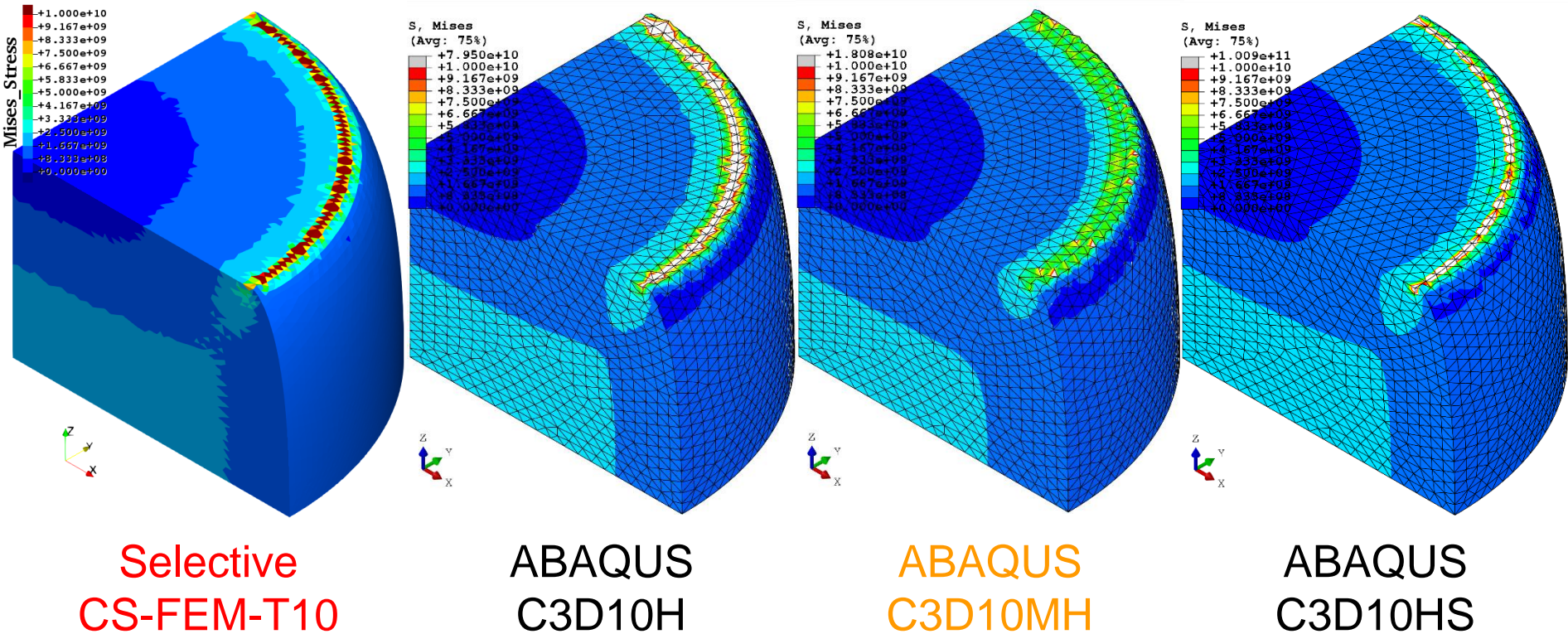
The present element is more **robust** than **ABAQUS C3D10MH**



Smooth distributions are obtained except around the rim.

# Static Implicit Barreling of Hyperelastic Cylinder

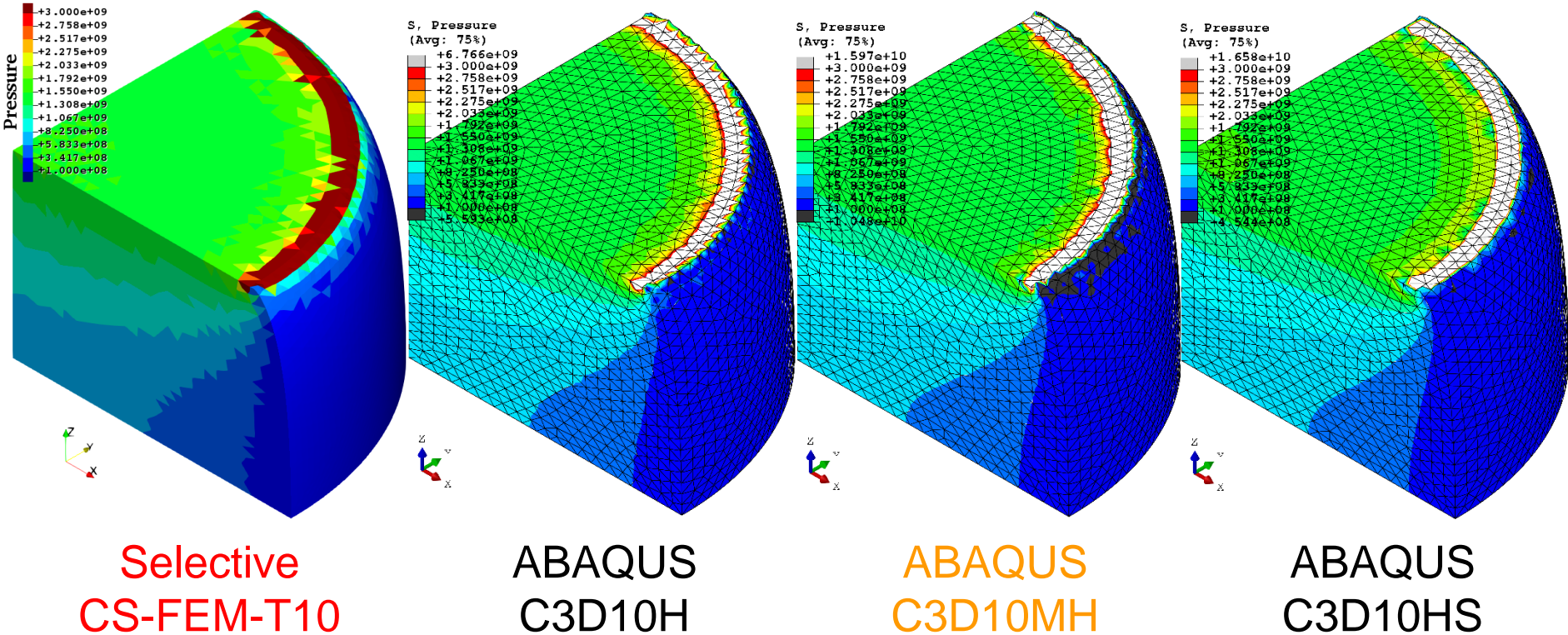
## Comparison of Mises stress at 24% comp.



All results are similar to each other except around the rim having stress singularity.

# Static Implicit Barreling of Hyperelastic Cylinder

## Comparison of pressure at 24% comp.

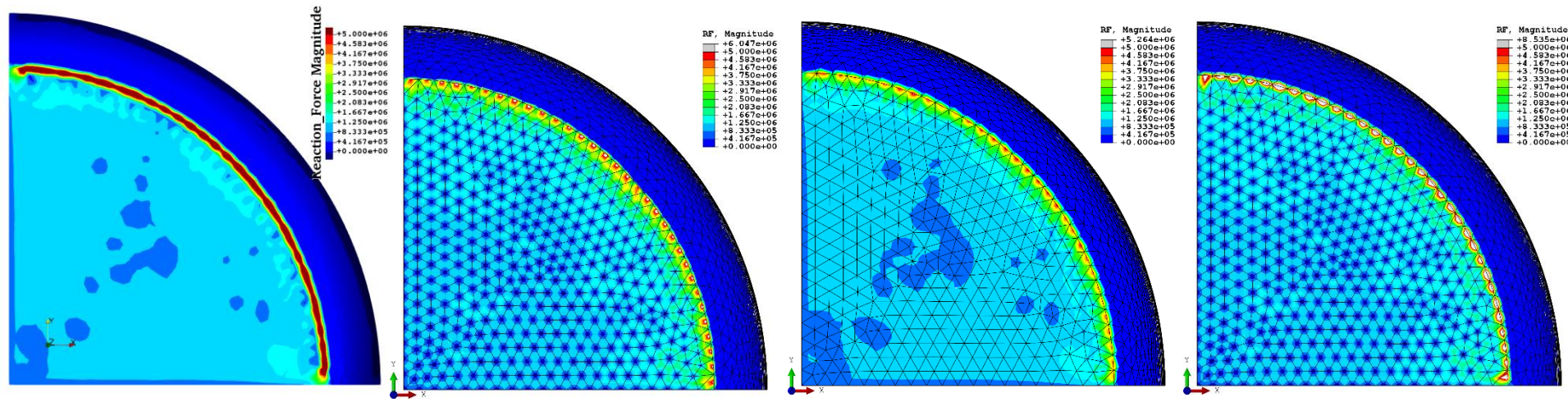


All results are similar to each other except around the rim having stress singularity.



# Static Implicit Barreling of Hyperelastic Cylinder

## Comparison of nodal reaction force at 24% comp.



Selective  
CS-FEM-T10

ABAQUS  
C3D10H

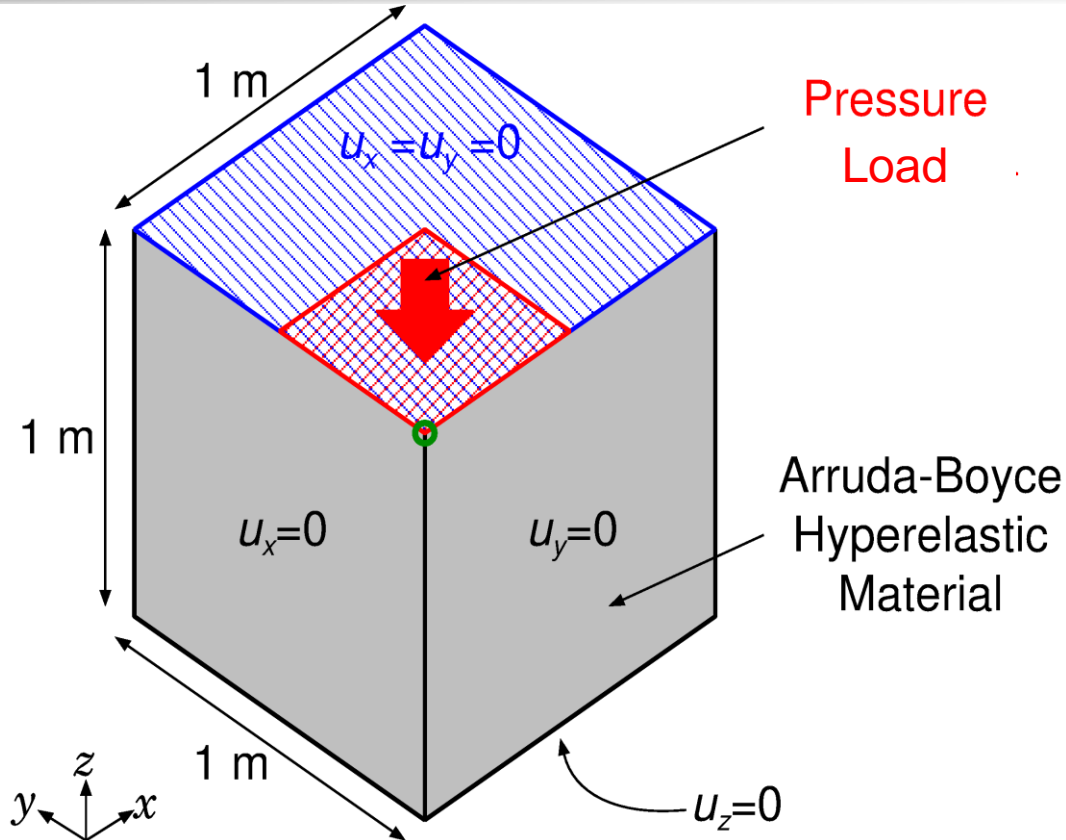
ABAQUS  
C3D10MH

ABAQUS  
C3D10HS

ABAQUS C3D10H and C3D10HS suffer from nodal force oscillation.

# Compression of Hyperelastic Block

## Outline

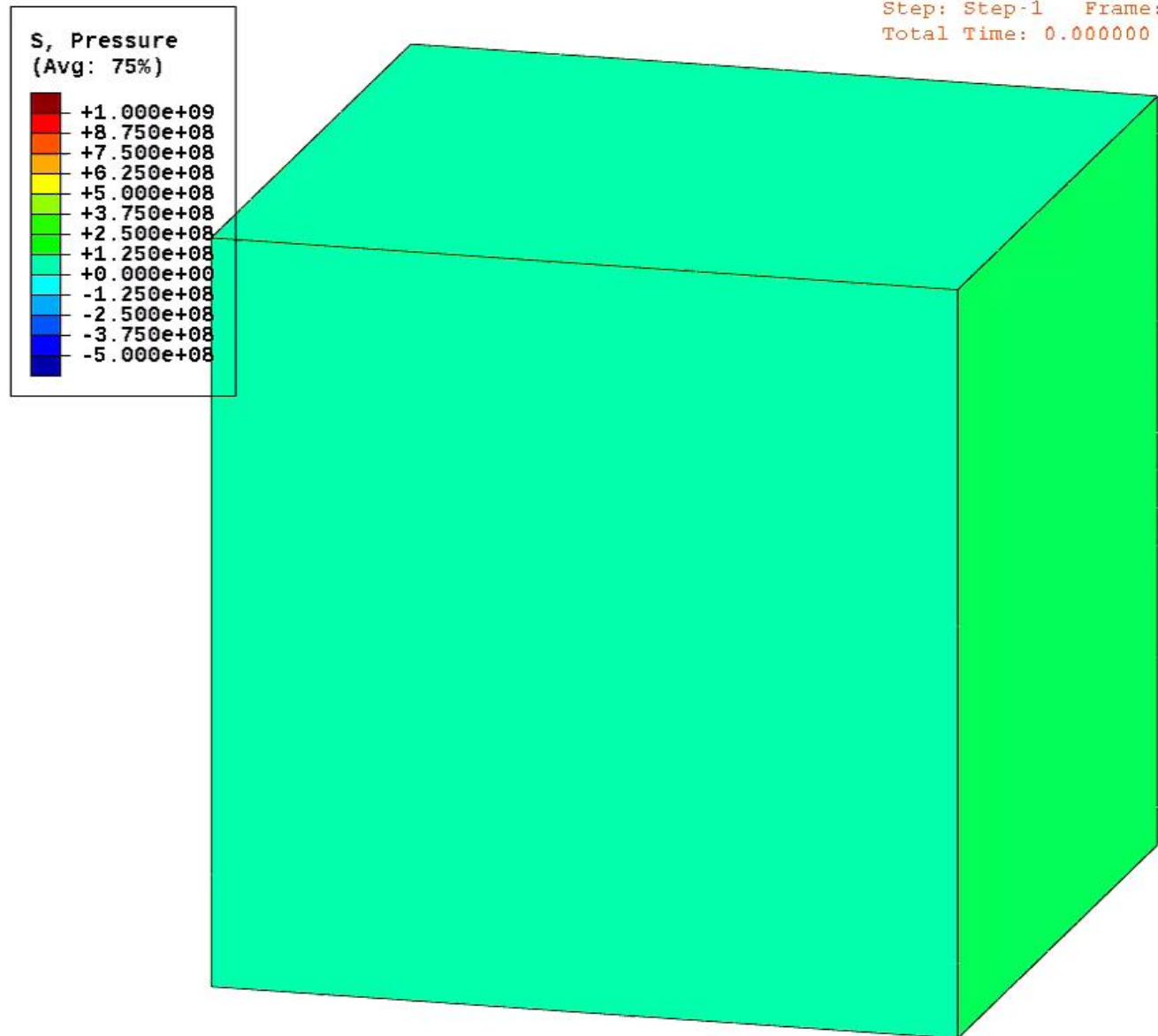


- Arruda-Boyce hyperelastic material ( $\nu_{ini} = 0.499$ ).
- Applying pressure on  $\frac{1}{4}$  of the top face.
- Compared to **ABAQUS C3D10MH** with the same unstructured T10 mesh.

# Static Implicit Compression of Hyperelastic Block

## Animation of pressure dist. (ABAQUS C3D10MH)

Step: Step-1 Frame: 0  
Total Time: 0.000000

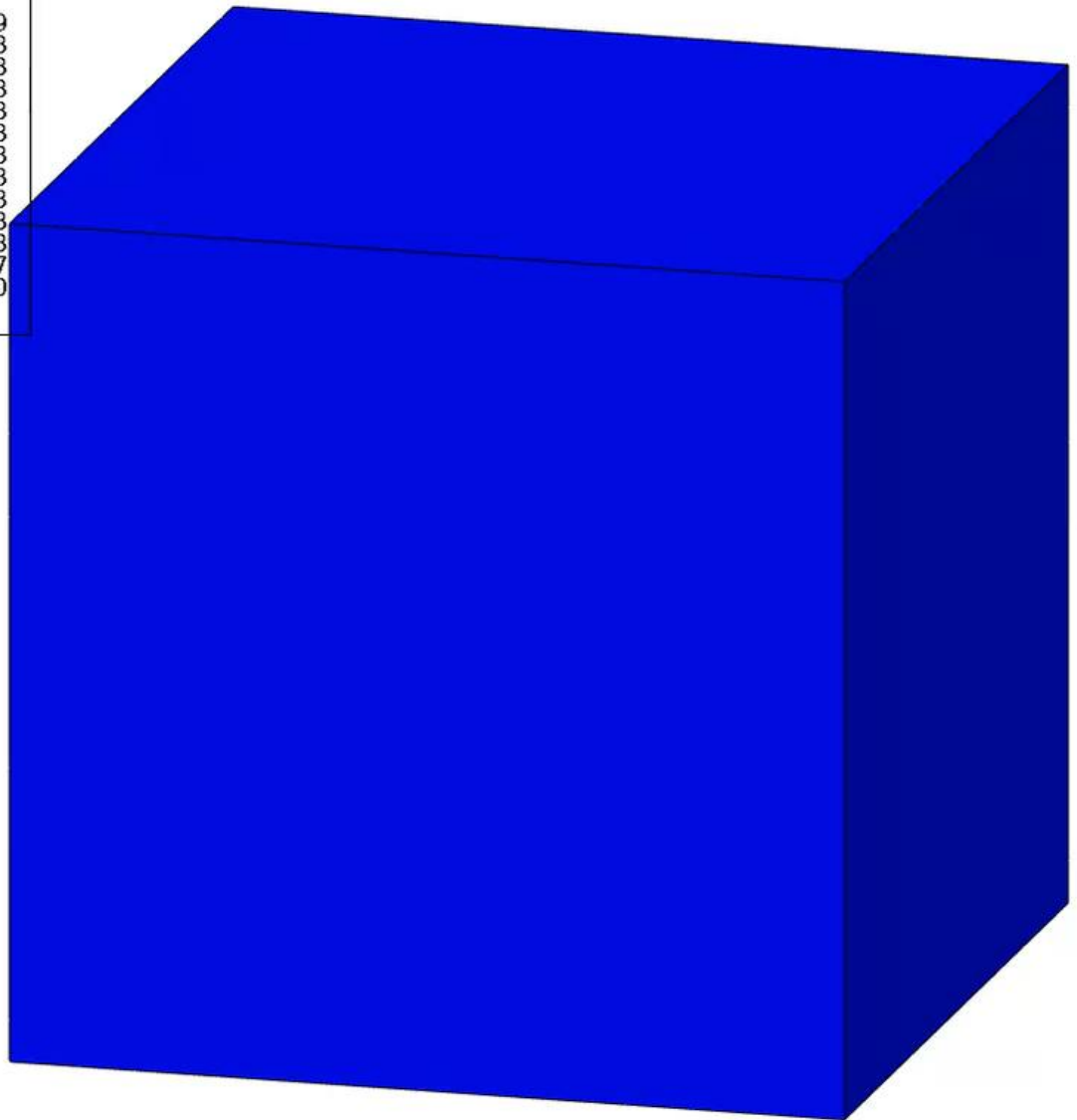
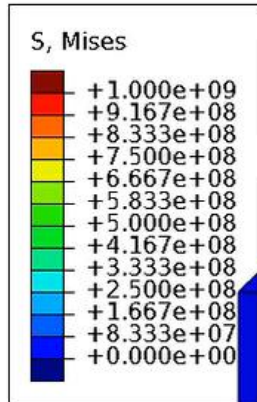


Convergence  
failure at  
**0.7 GPa**  
pressure



# Static Implicit Compression of Hyperelastic Block

**Animation**  
**of**  
**Mises stress**  
**dist.**  
**(ABAQUS**  
**C3D10MH)**



Convergence  
failure at  
**0.7 GPa**  
pressure

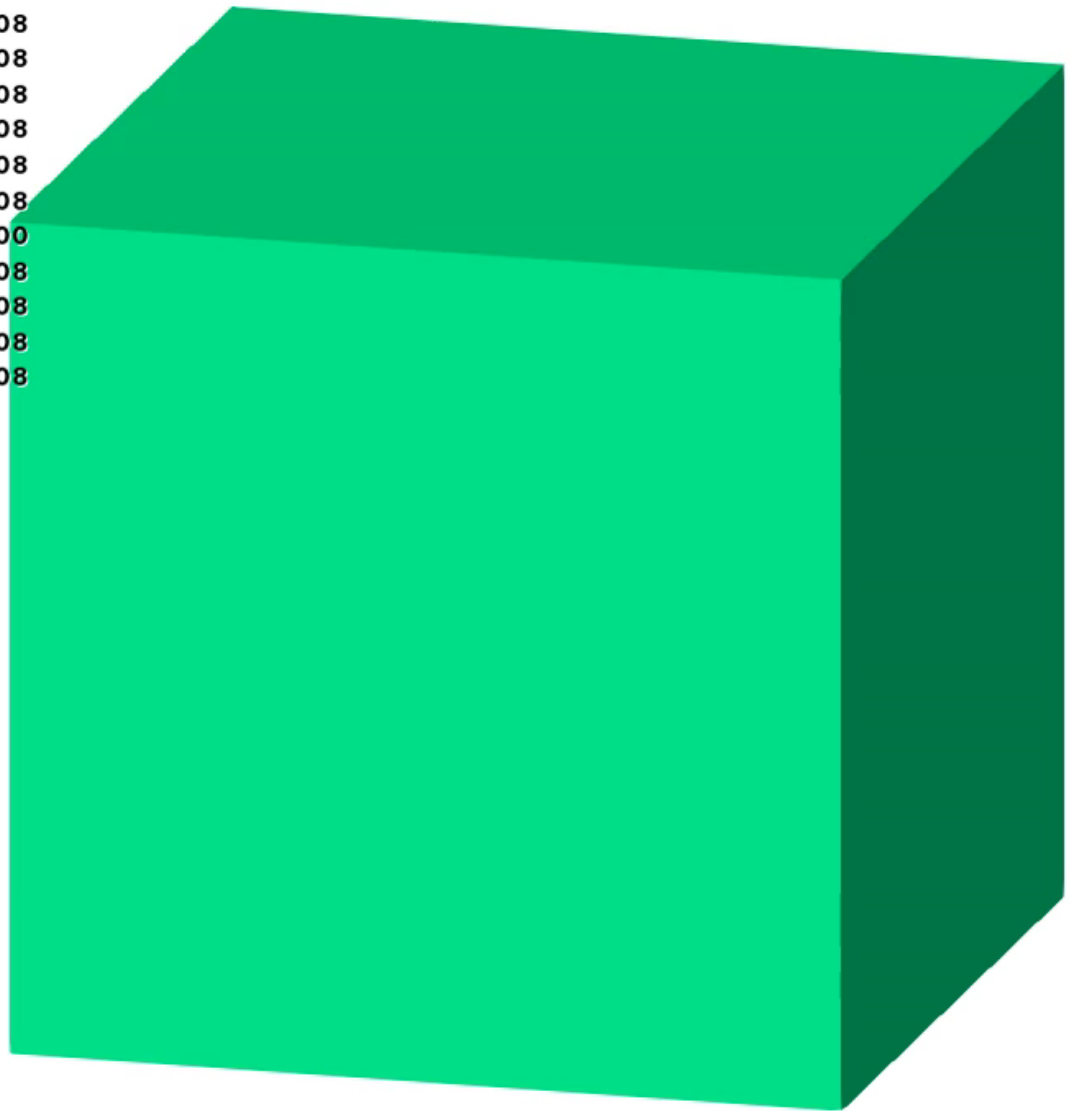
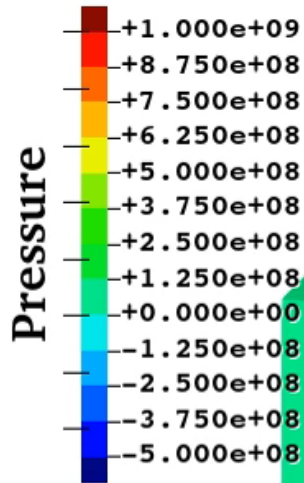


# Static Implicit Compression of Hyperelastic Block

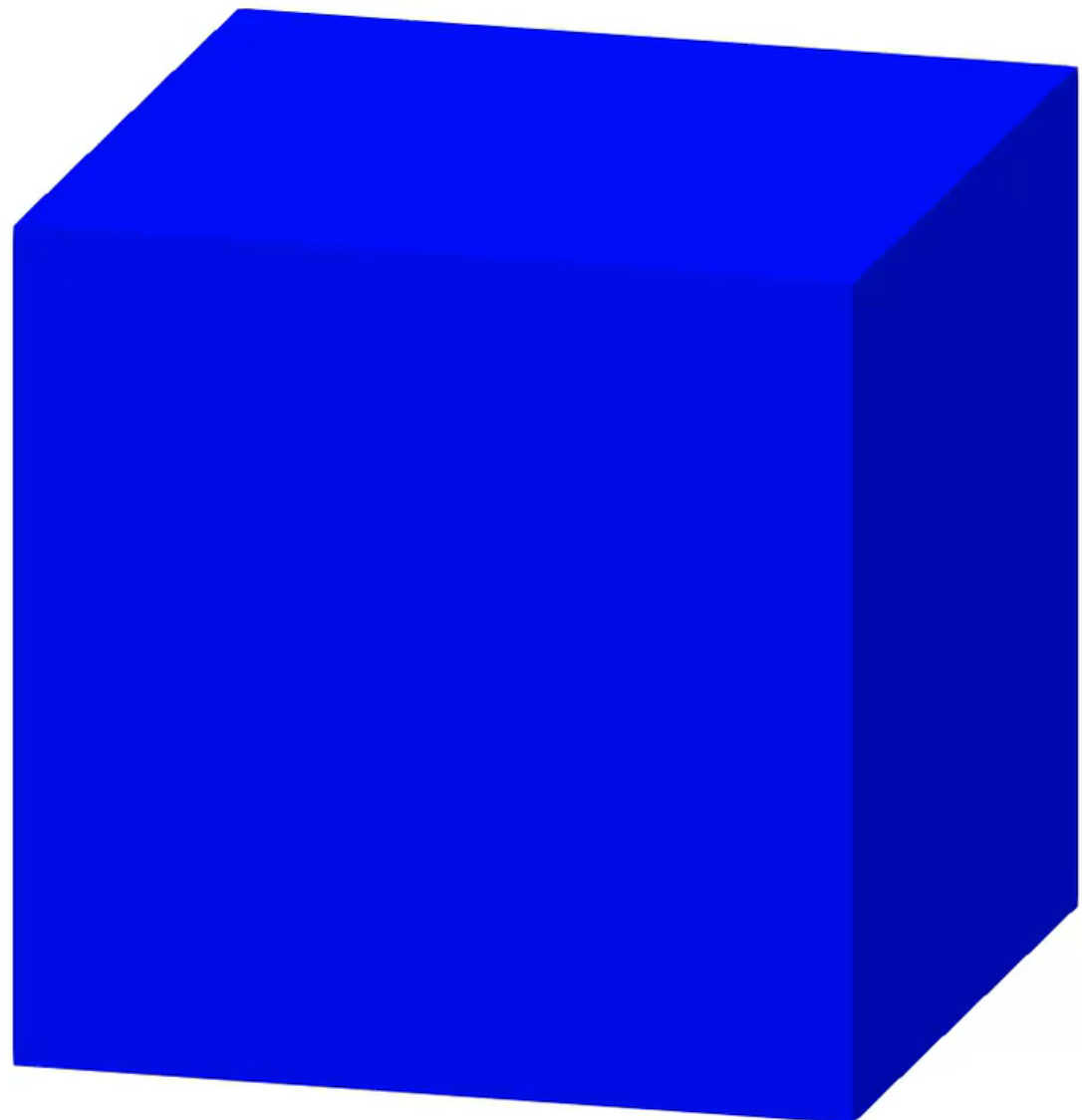
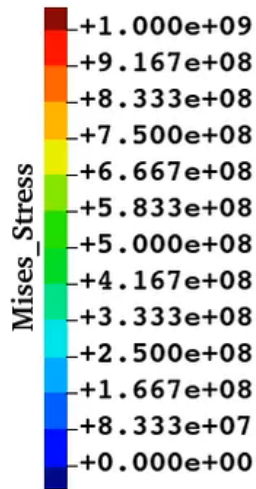
## Animation of pressure dist. (*Selective* *CS-FEM-T10*)

Convergence  
failure at  
1.3 GPa  
pressure

The present  
element  
is more  
**robust** than  
ABAQUS  
C3D10MH

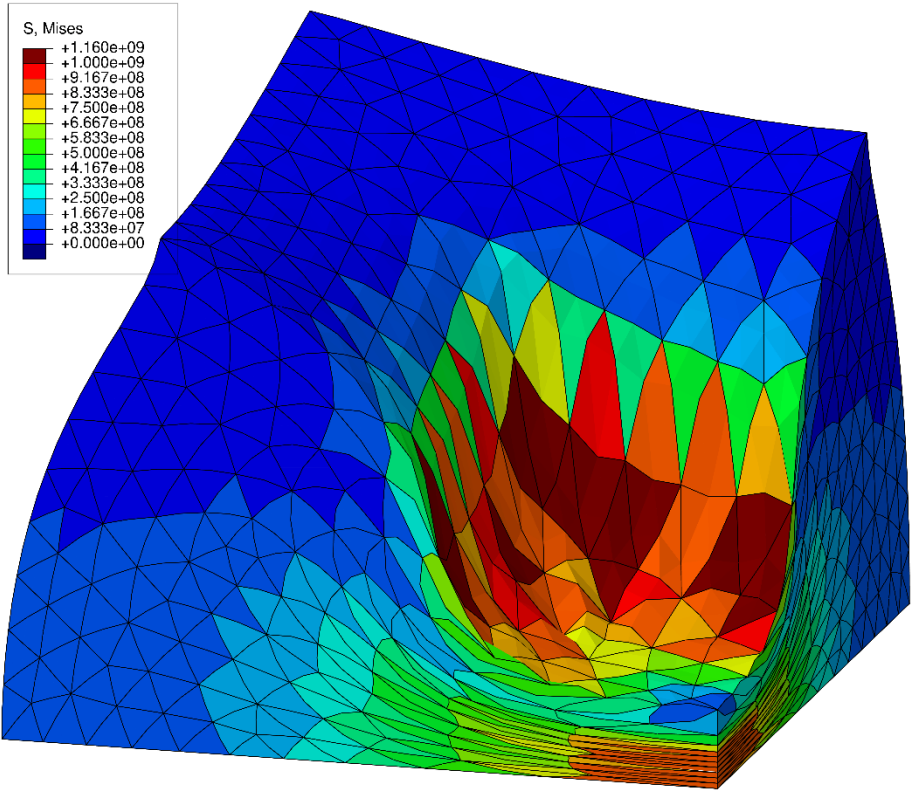


**Animation**  
**of**  
**Mises stress**  
**dist.**  
**(Selective**  
**CS-FEM-T10)**

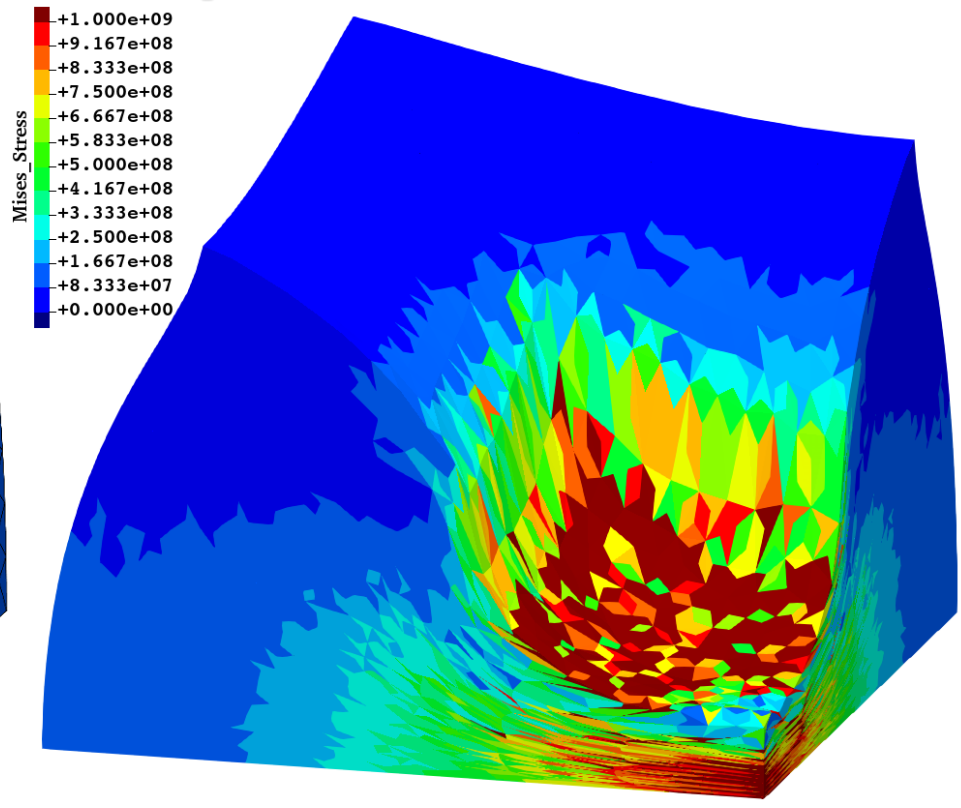


The present element presents **Mises stress oscillation.**

**Mises stress dist. at 0.7 GPa pressre**



ABAQUS C3D10MH



SelectiveCS-FEM-T10

Less smoothed Mises stress is observed in SelectiveCS-FEM-T10. Further improvement is still required.

# Characteristics of SelectiveCS-FEM-T10

## Benefits

- ✓ Accurate  
(no locking, no checkerboarding, no force oscillation).
- ✓ Robust (long-lasting in large deformation).
- ✓ No increase in DOF (No static condensation).
- ✓ Same memory & CPU costs as the other T10 elements.
- ✓ Implementable to commercial FE codes  
(e.g., ABAQUS UEL).

## Drawbacks

- ✗ Mises stress oscillation in some extreme analyses.
- ✗ No longer a T4 formulation.

SelectiveCS-FEM-T10 is competitive  
with the best ABAQUS T10 element, C3D10MH.



# Summary

# Summary

## One-sentence summary

SelectiveCS-FEM-T10 is already good enough for practical use as compared to ABAQUS Tet elements.

## Take-home message

**Please consider implementing  
SelectiveCS-FEM-T10 to your in-house code.  
It's supremely useful & easy to code!!**

Thank you for your kind attention!

# Appendix



# Differences between Old and New

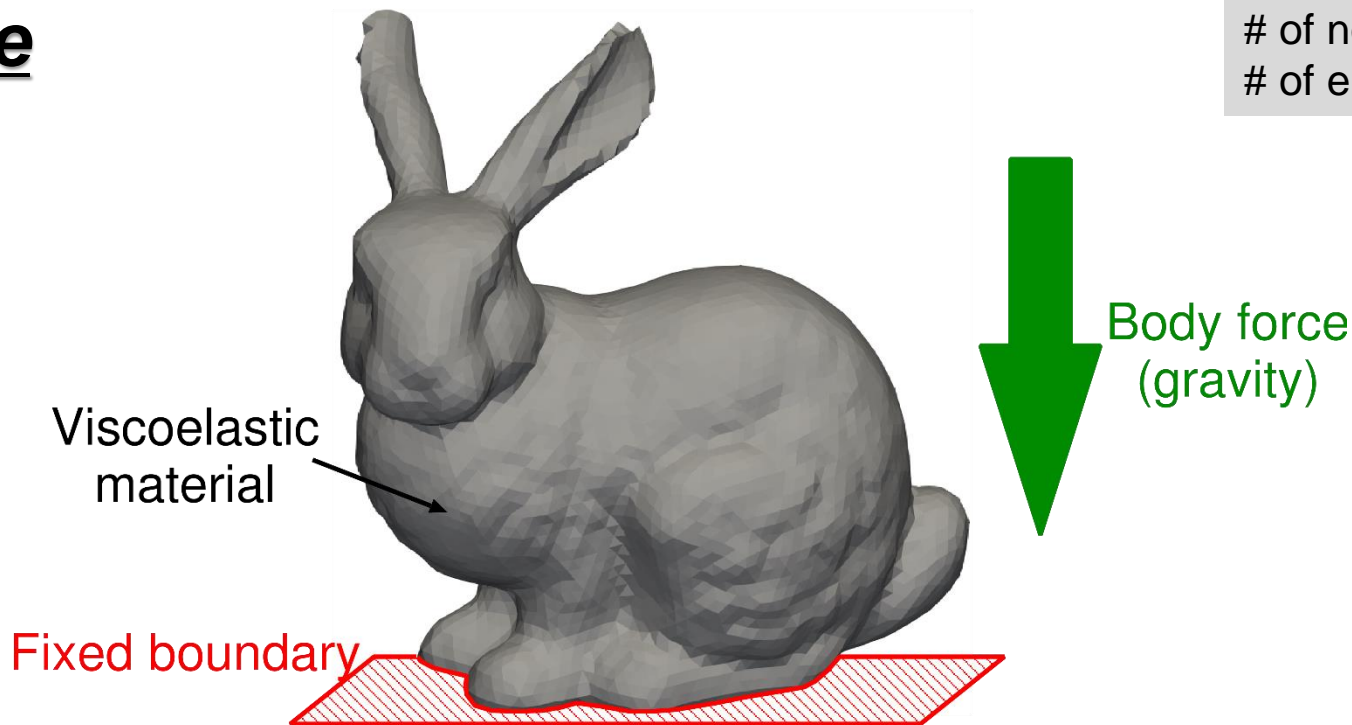
1. The new formulation has **NO dummy node** at the center of an element.
  - Fewer sub-elements and edges.
  - Asymmetric element.
2. The new formulation has **No ES-FEM<sup>-1</sup>** after ES-FEM.
  - Strain & stress evaluation at edges.
  - No strain smoothing at frame edges.

Intuitively, the lack of **element symmetry** and **frame edge smoothing** is not good for accuracy and stability; however, the new formulation is better in fact.

Its reason has not revealed yet.

## Outline

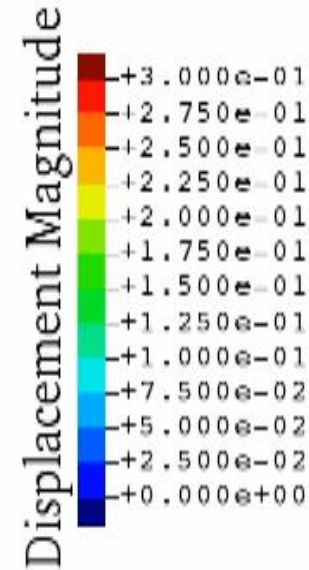
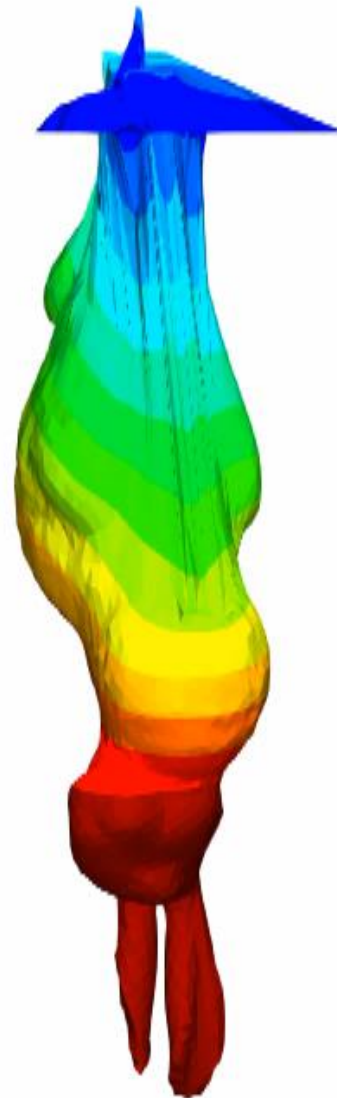
# of nodes: 24136  
# of elems: 126231



- Applying gravity to the Stanford Bunny and let it collapsed by its self-weight.
- Soft viscoelastic material ( $\nu_0 = 0.3$ ,  $\nu_\infty = 0.49$ ,  $\tau = 10$  s).
- Contact is NOT considered.
- Comparing F-barES-FEM-T4(2) and ABAQUS C3D4H.

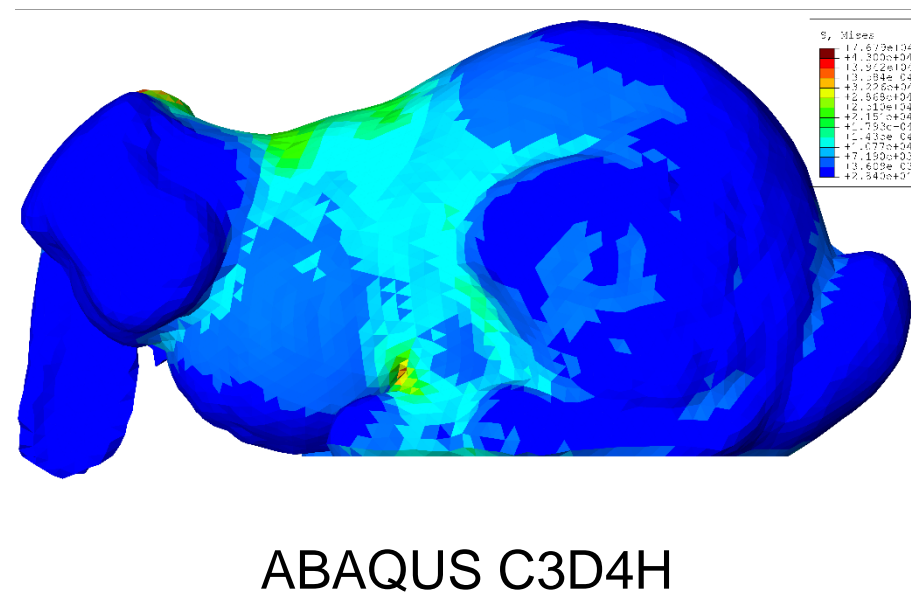
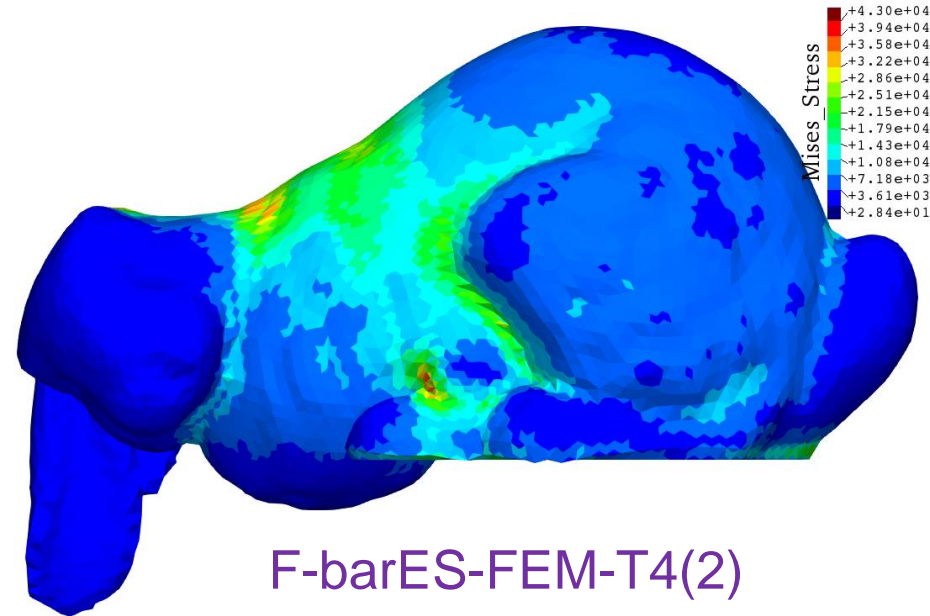
# Animation of Deformation

Because contact is not considered, the body penetrates the feet and finally becomes upside downside. The analysis lasts till the necking.



# Collapse Analysis of *Viscoelastic* Bunny

## Mises stress dist. when C3D4H get a convergence failure

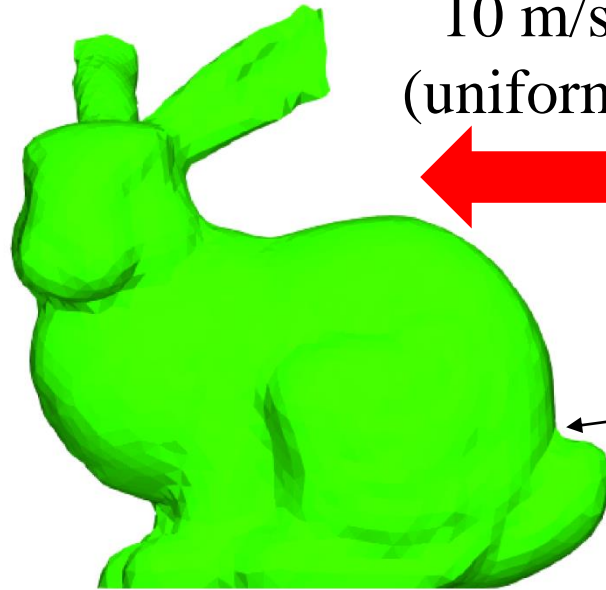


- ABAQUS C3D4H shows a stiffer result due to shear locking.
- The result of F-barES-FEM-T4 would be better.

# Impact of Rubber Bunny

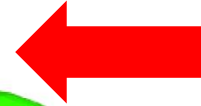
## Outline

Rigid Wall  
Contact condition  
free-slip, free-  
separation



Initial velocity

10 m/s  
(uniform)



Rubber body

$E = 6.0 \text{ MPa}$

$\nu = 0.49$

$\rho = 920 \text{ kg/m}^3$

- A bunny made of rubber (neo-Hookean) is crushed to a rigid wall.
- Compared with ABAQUS/Explicit C3D4 using a same T4 mesh.
- Note that neither Hex mesh nor hybrid elements is not available in this problem.

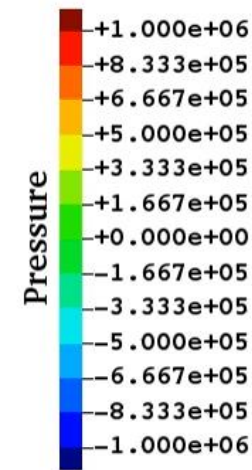
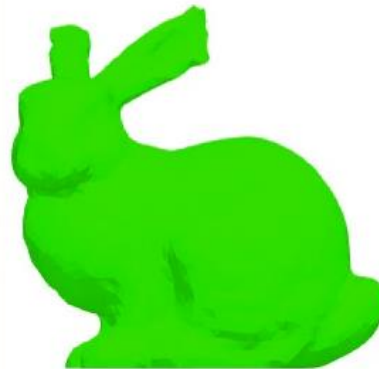


# Impact of Rubber Bunny

## Animation of Pressure Dist.

ABAQUS/Explicit  
C3D4

- ✗ Pressure Checkerboarding
- ✗ Shear Locking



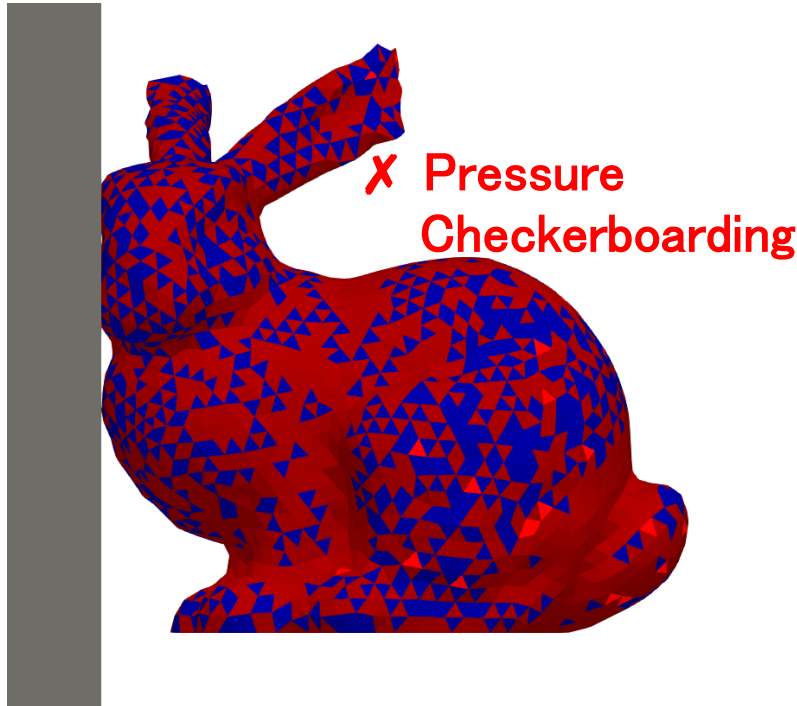
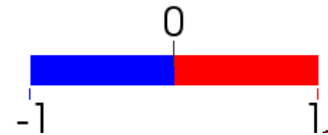
SymF-barES-  
FEM-T4(1)

- ✓ Smooth pressure
- ✓ No Locking

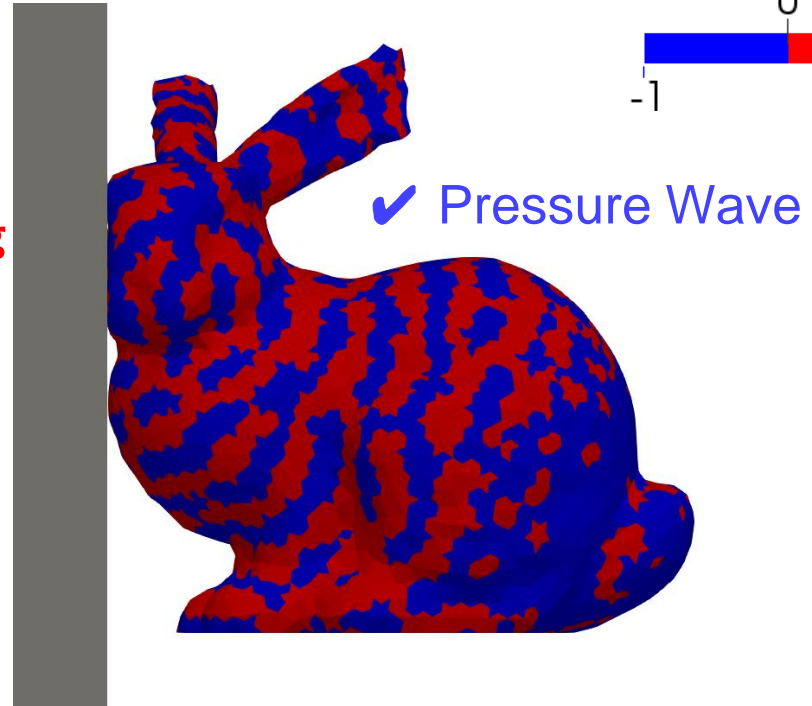
# Impact of Rubber Bunny

## Sign of Pressure at Initial Phase

Sign of Pressure



**X** Pressure  
Checkerboarding



**✓** Pressure Wave

ABAQUS/Explicit C3D4  
(Standard T4 element)

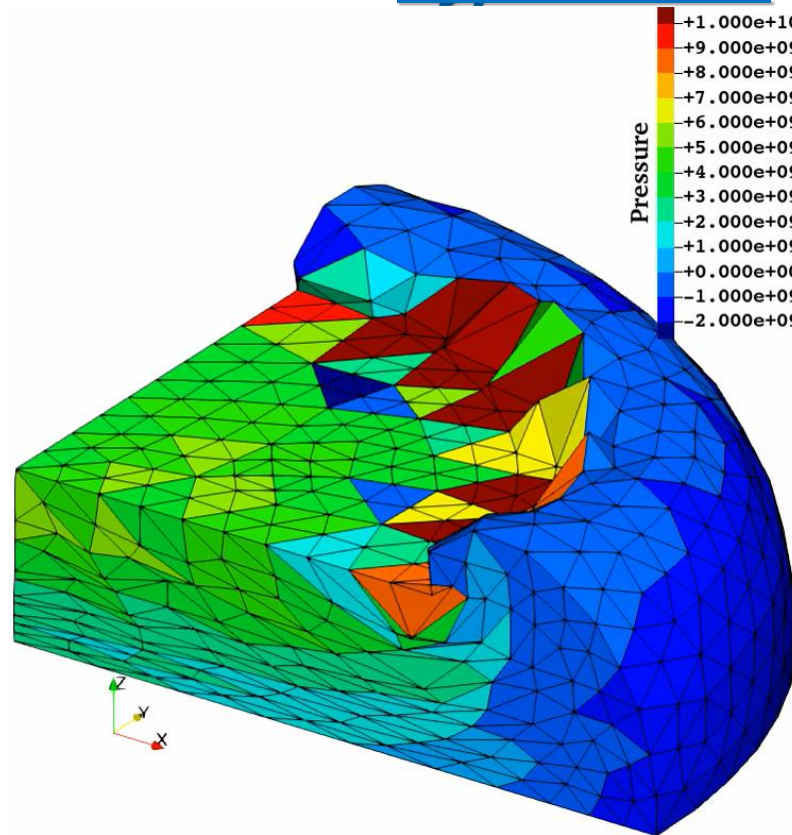
SymF-barES-FEM-T4(1)

The proposed S-FEM captures the pressure wave in a complex body successfully!!

# Issues (cont.)

E.g.) Compression of neo-Hookean hyperelastic body with  $v_{ini} = 0.49$

Same mesh  
as C3D10MH  
case.



As other S-FEMs,  
SelectiveCS-FEM-T10  
has many varieties  
in the formulation.

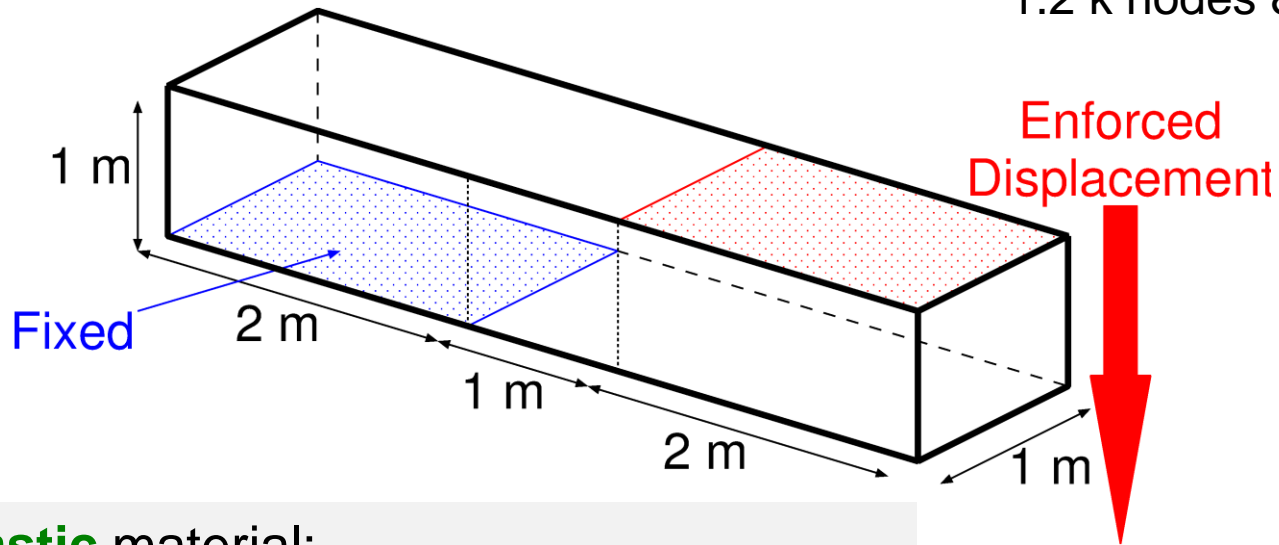
The proposed method  
last year was  
**not an optimal  
formulation yet.**

## SelectiveCS-FEM-T10 (Old Ver.)

- ✓ No shear/volumetric locking
- ✓ Little corner locking
- ✓ Little pressure checkerboarding
- ✓ Same cost & usability as T10 elements.

## Outline

1.2 k nodes & 4.8 k elems.



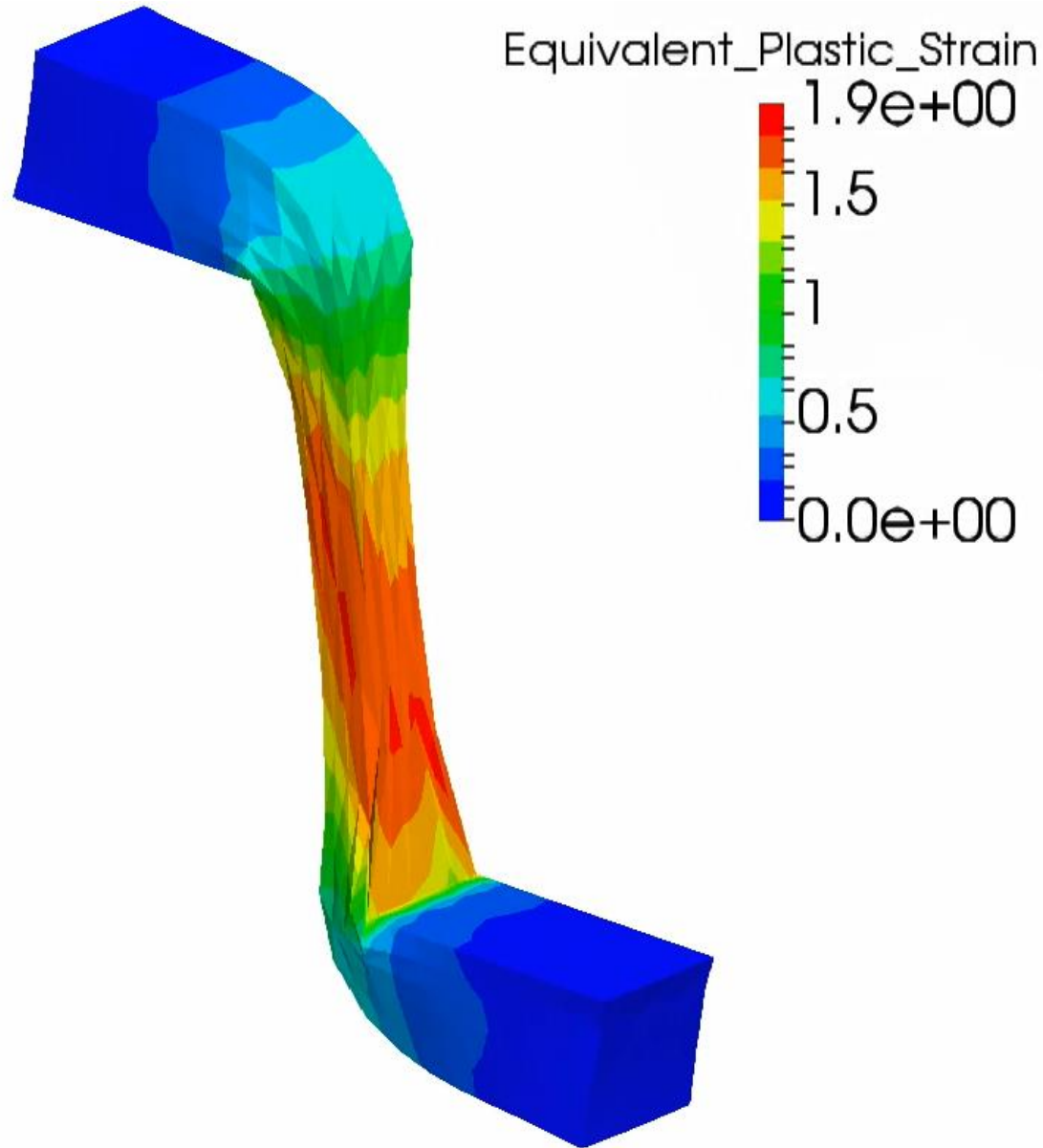
### **Elasto-plastic** material:

- Hencky elasticity with  $E = 1$  GPa and  $\nu = 0.3$ .
- Isotropic von Mises yield criterion with  $\sigma_Y = 1$  MPa and  $H = 0.1$  GPa (constant).

- Blue face is perfectly constrained.
- Red face is constrained in plane and pressed down.
- Compared to ABAQUS C3D4H with the same unstructured T4 mesh.

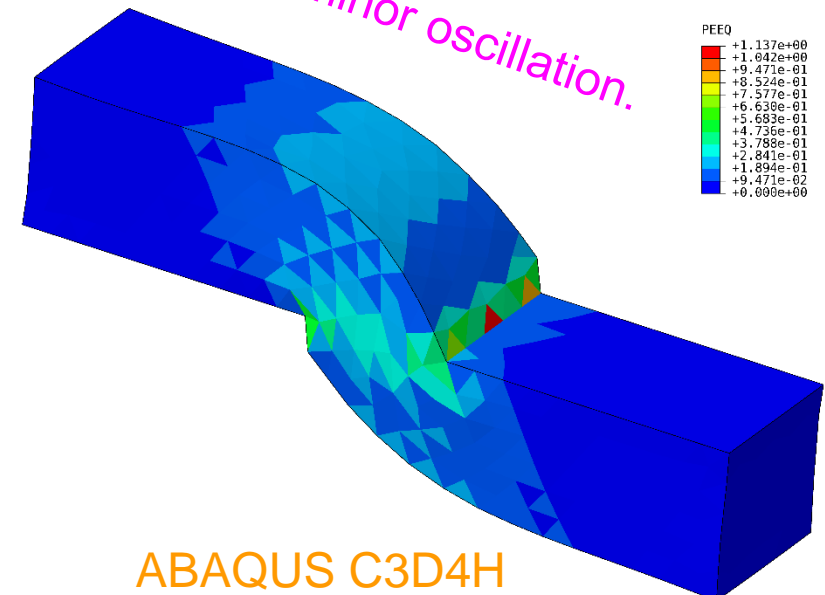
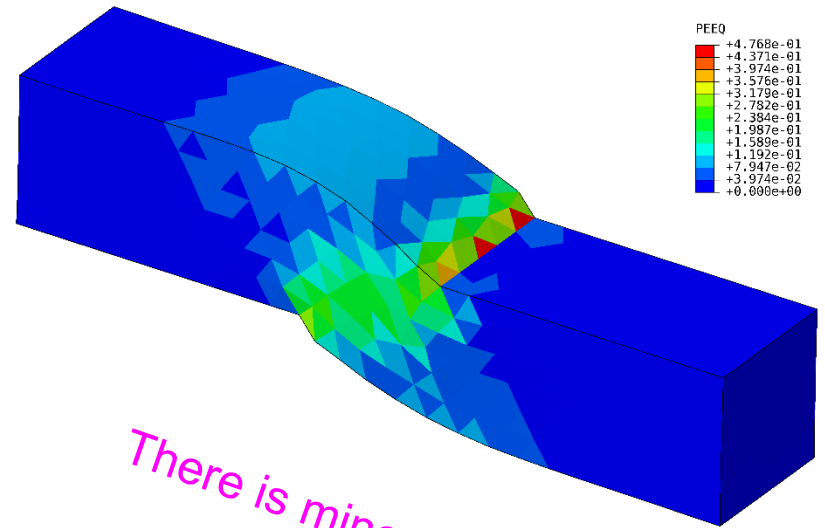
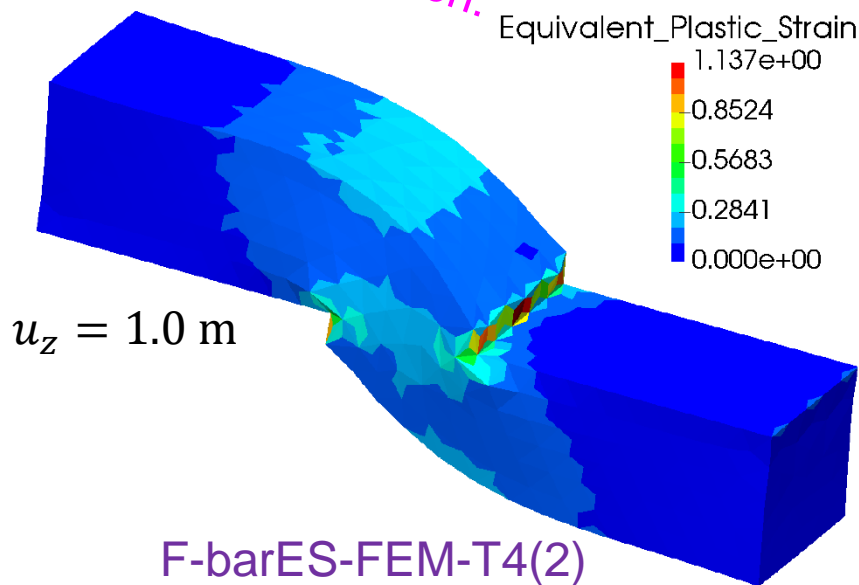
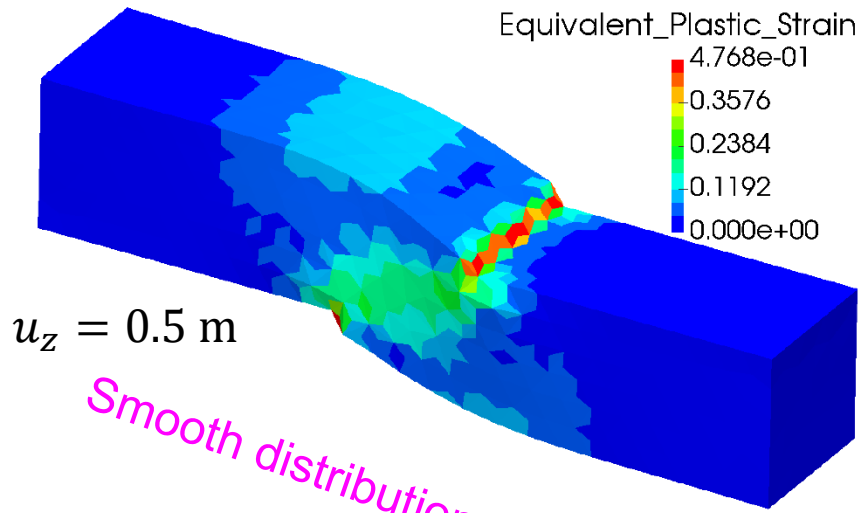
**Result of**  
**F-bar**  
**ES-FEM(2)**  
**(Equiv.**  
**plastic**  
**strain)**

Extreme large deformation with smooth strain dist. is successfully achieved.



# Shear-tensioning of *Elasto-plastic* Bar

## Equivalent plastic strain dist. in middle states



# Shear-tensioning of *Elasto-plastic* Bar

## Pressure dist. in middle states

